

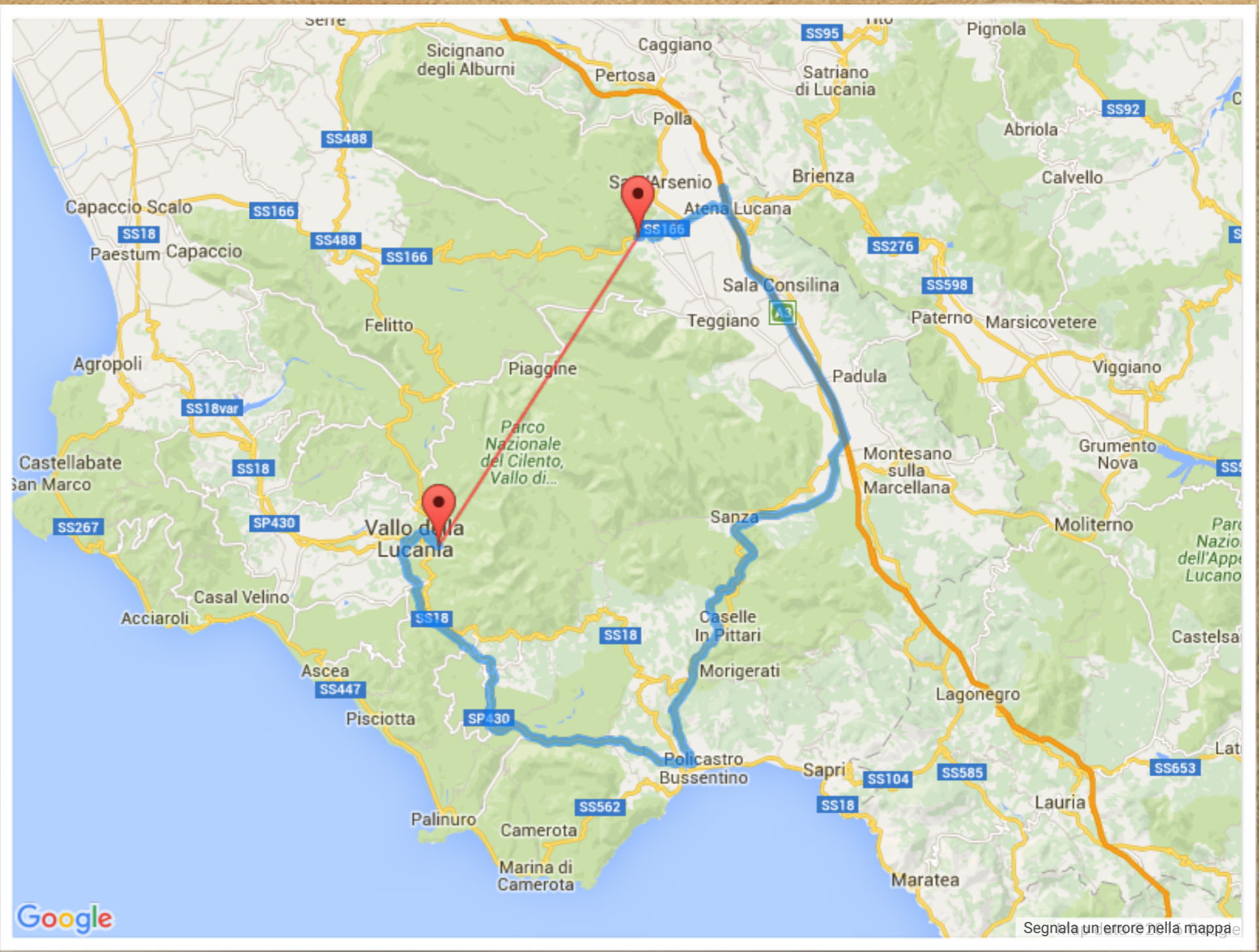
Zeno was born in Elea, 27 km from San Rufo

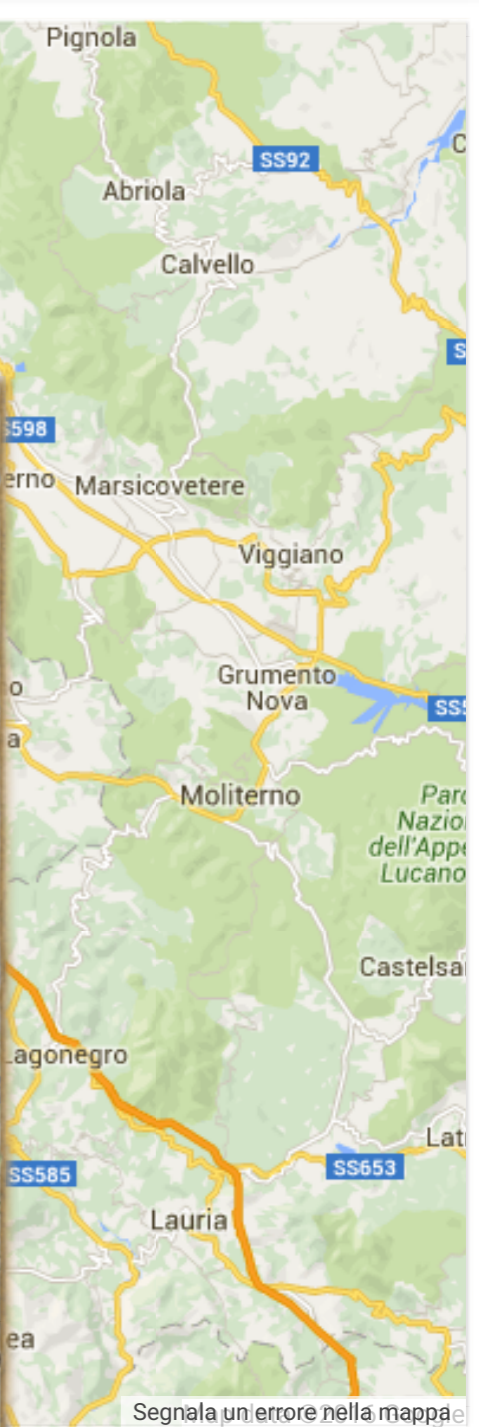
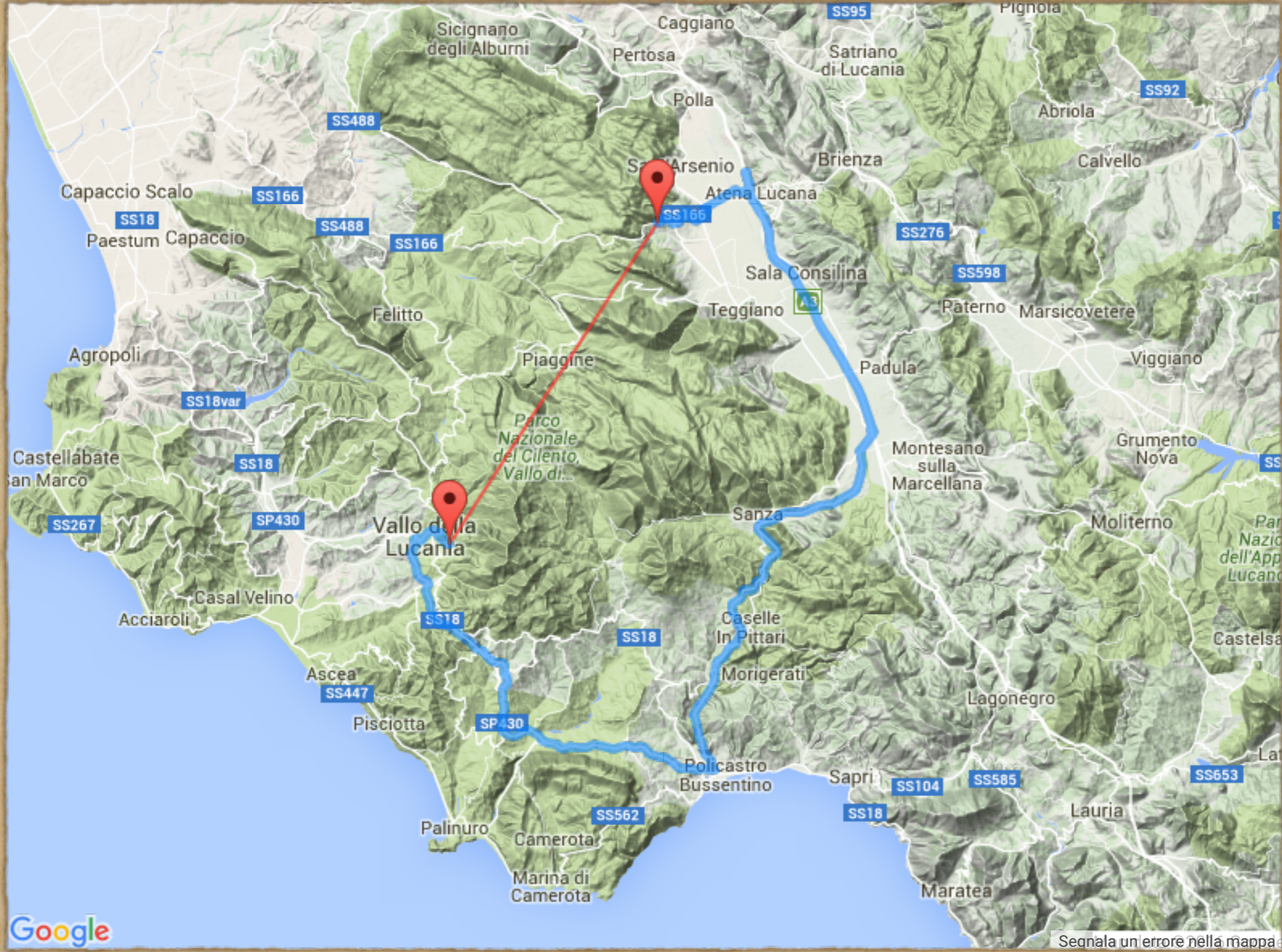
Saverio Pascazio

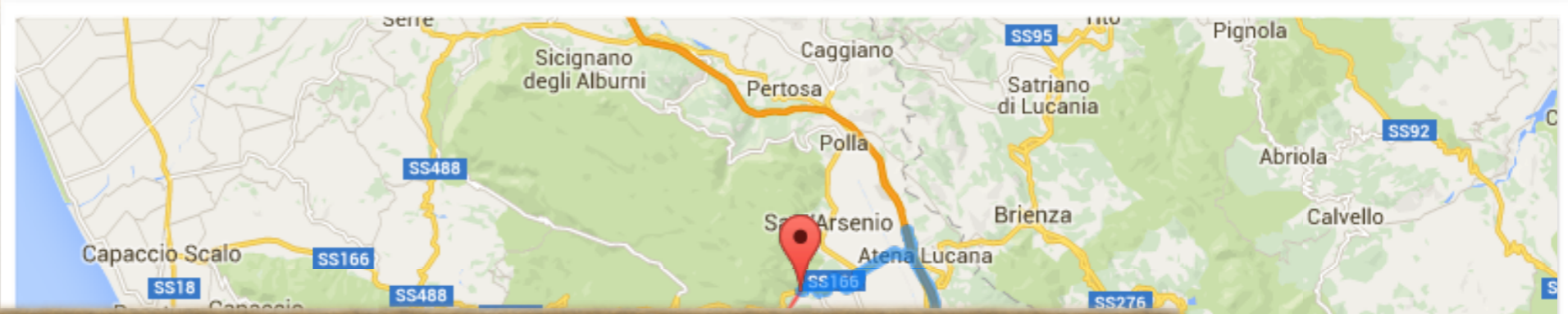
Dipartimento di Fisica and INFN

Bari, Italy

San Rufo, 11 July 2016







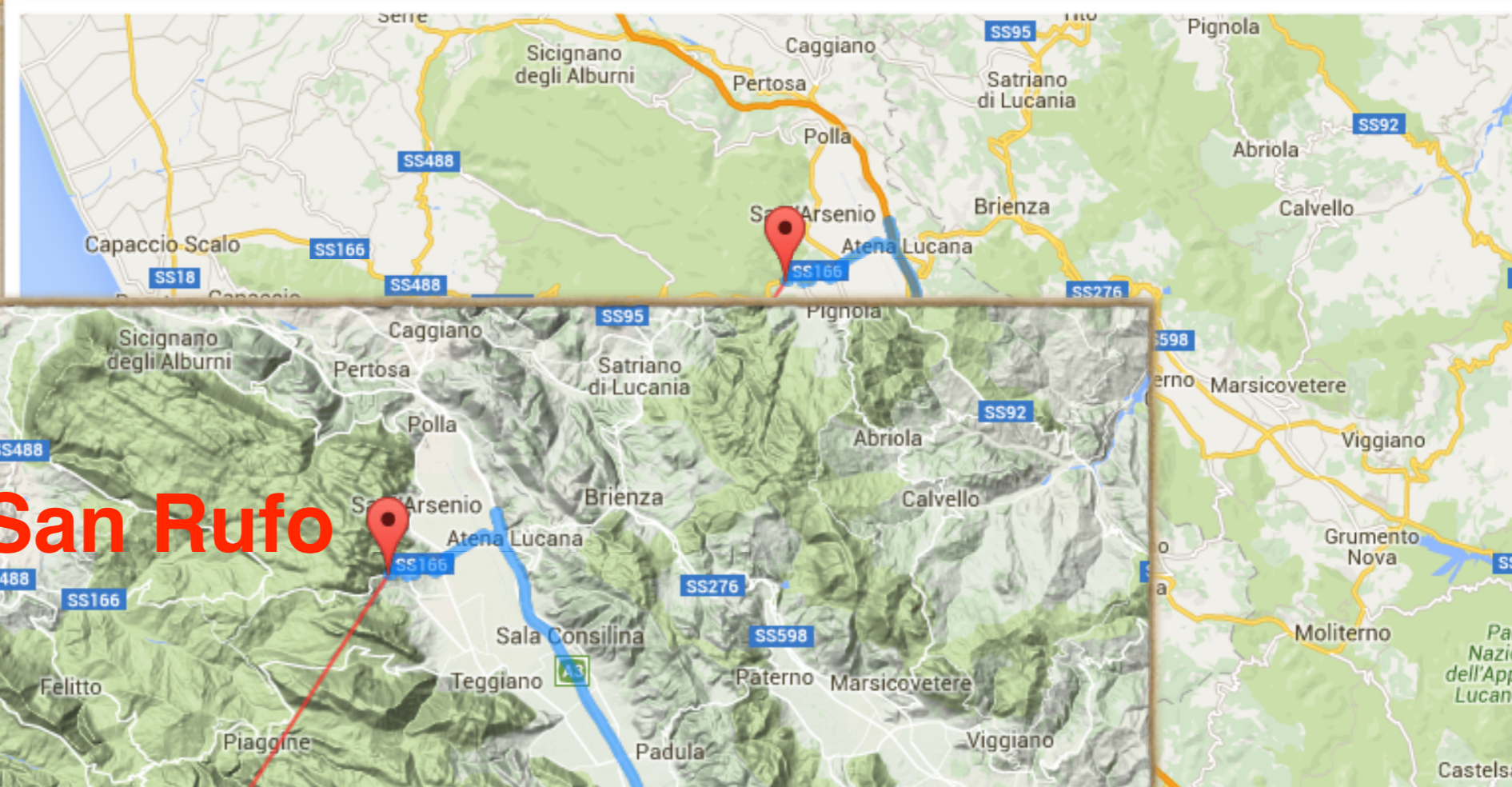
**San Rufo**

**Velia (Elea)**



**San Rufo**

**Velia (Elea)**



**Calcolo della distanza da Novi Velia a San Rufo**



La distanza in chilometri sulla strada = 108 km

Distanza in miglia sulla strada = 66.96 miglia

Tempo di percorrenza = 1 ore 32 minuti

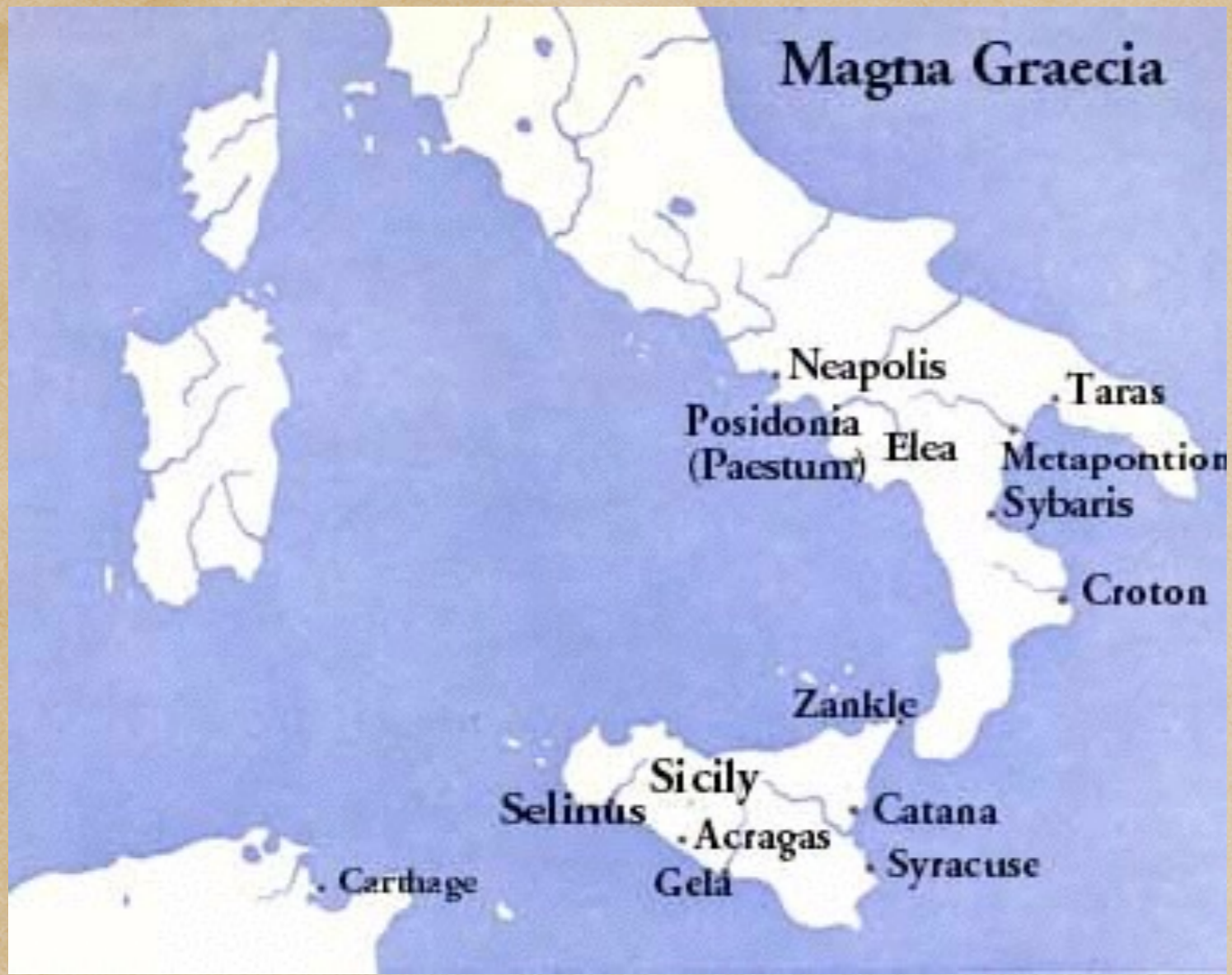
Consumo di carburante = 7.56 litri

Il prezzo del carburante = 12.1 euro



La distanza in linea retta in chilometri = 27.73 km

La distanza in linea d'aria in miglia = 17.2 miglia



Magna Graecia

Neapolis

Taras

Posidonia  
(Paestum)

Elea

Metapontion

Sybaris

Croton

Zankle

Sicily

Selinus

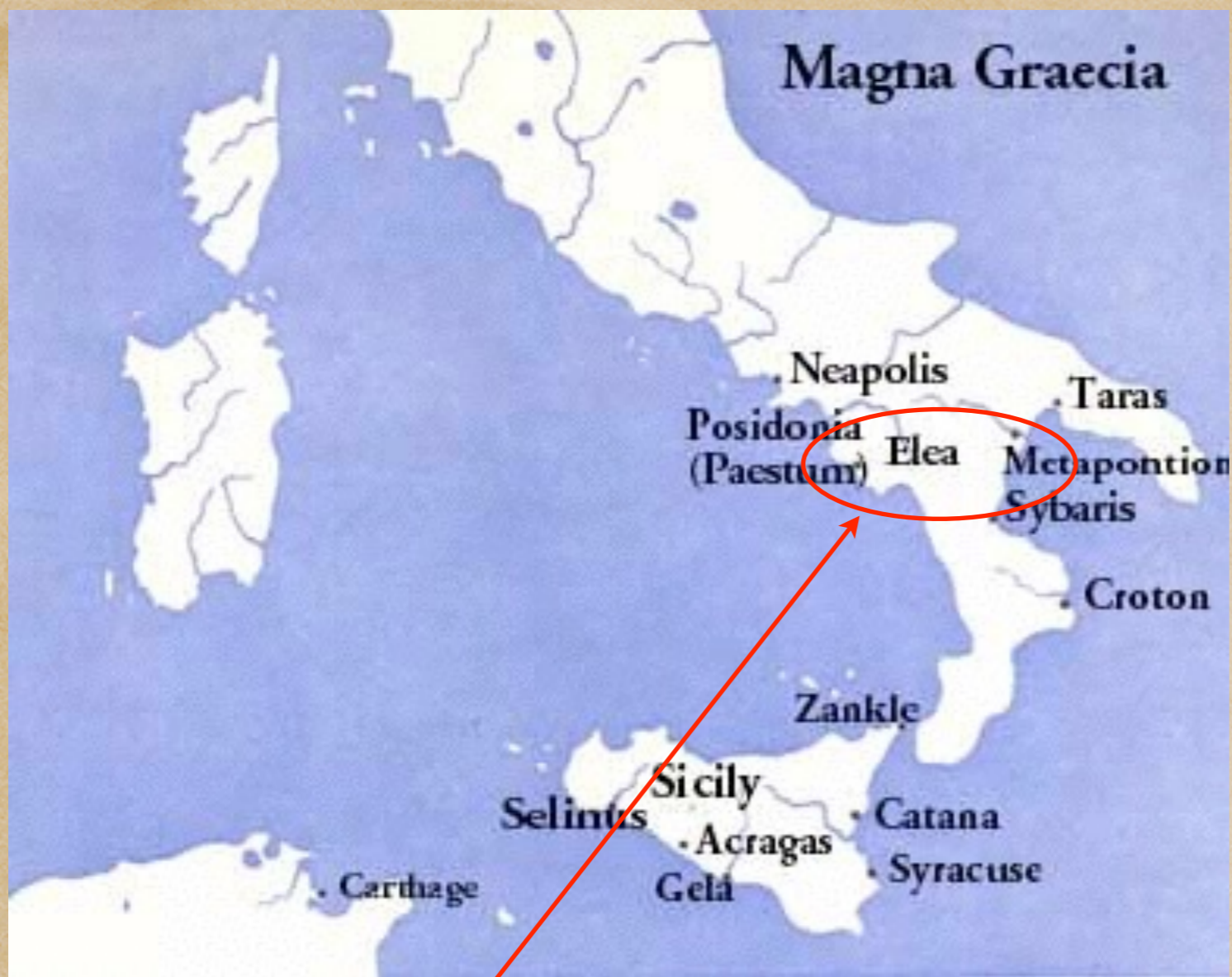
Catana

Acragas

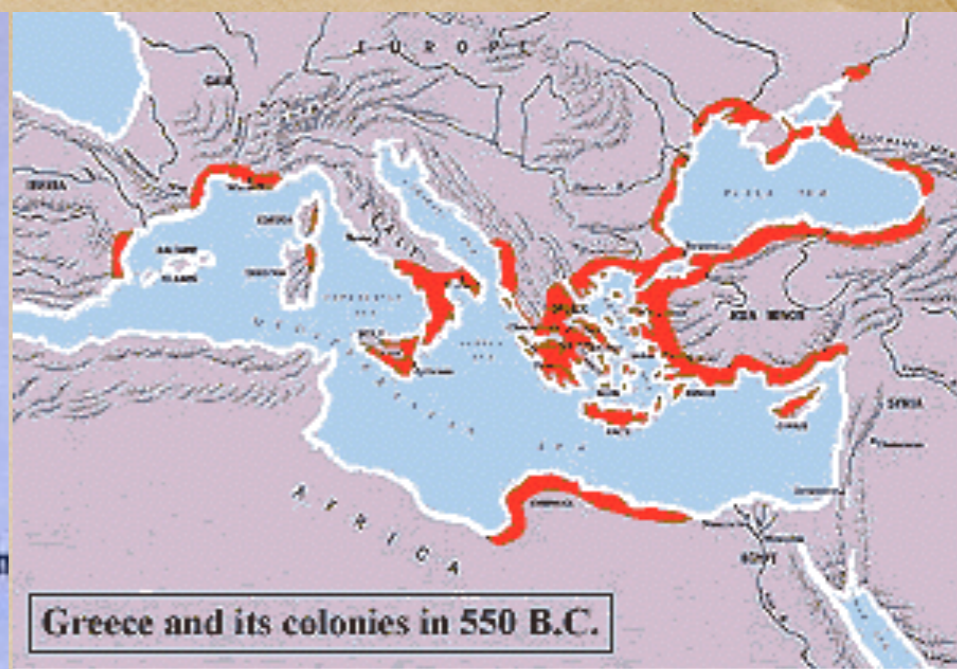
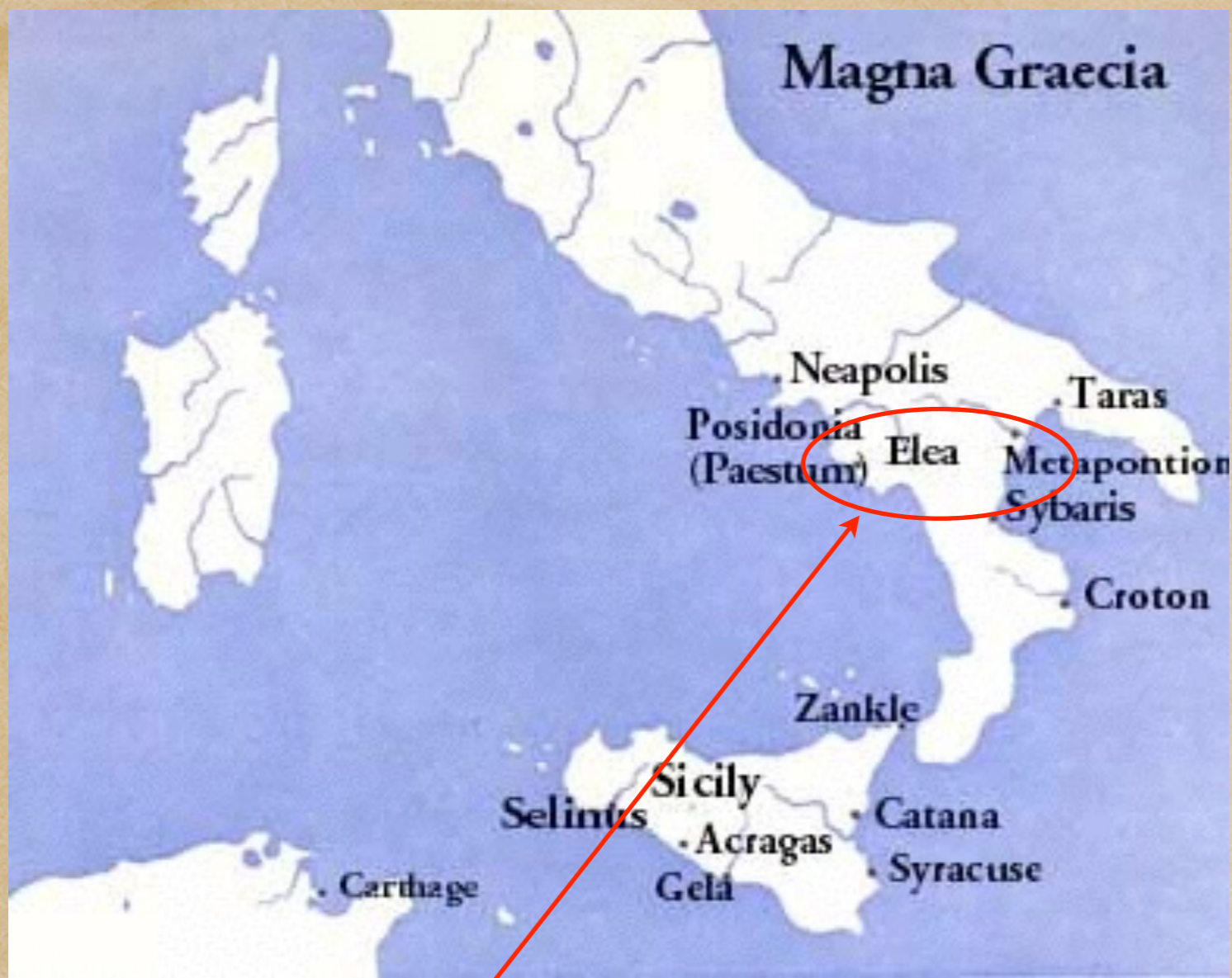
Syracuse

Gela

Carthage

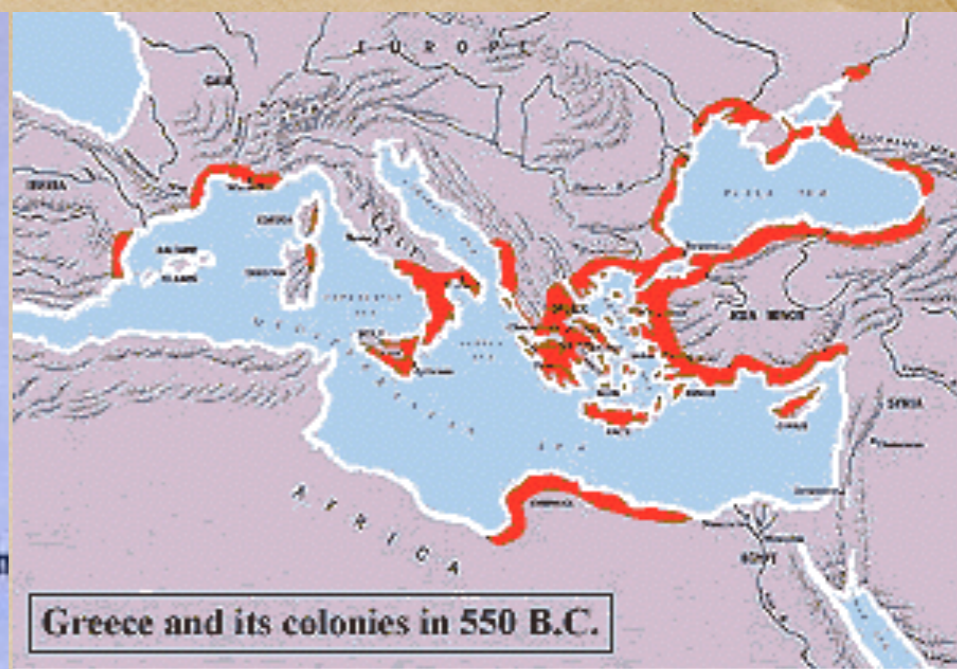
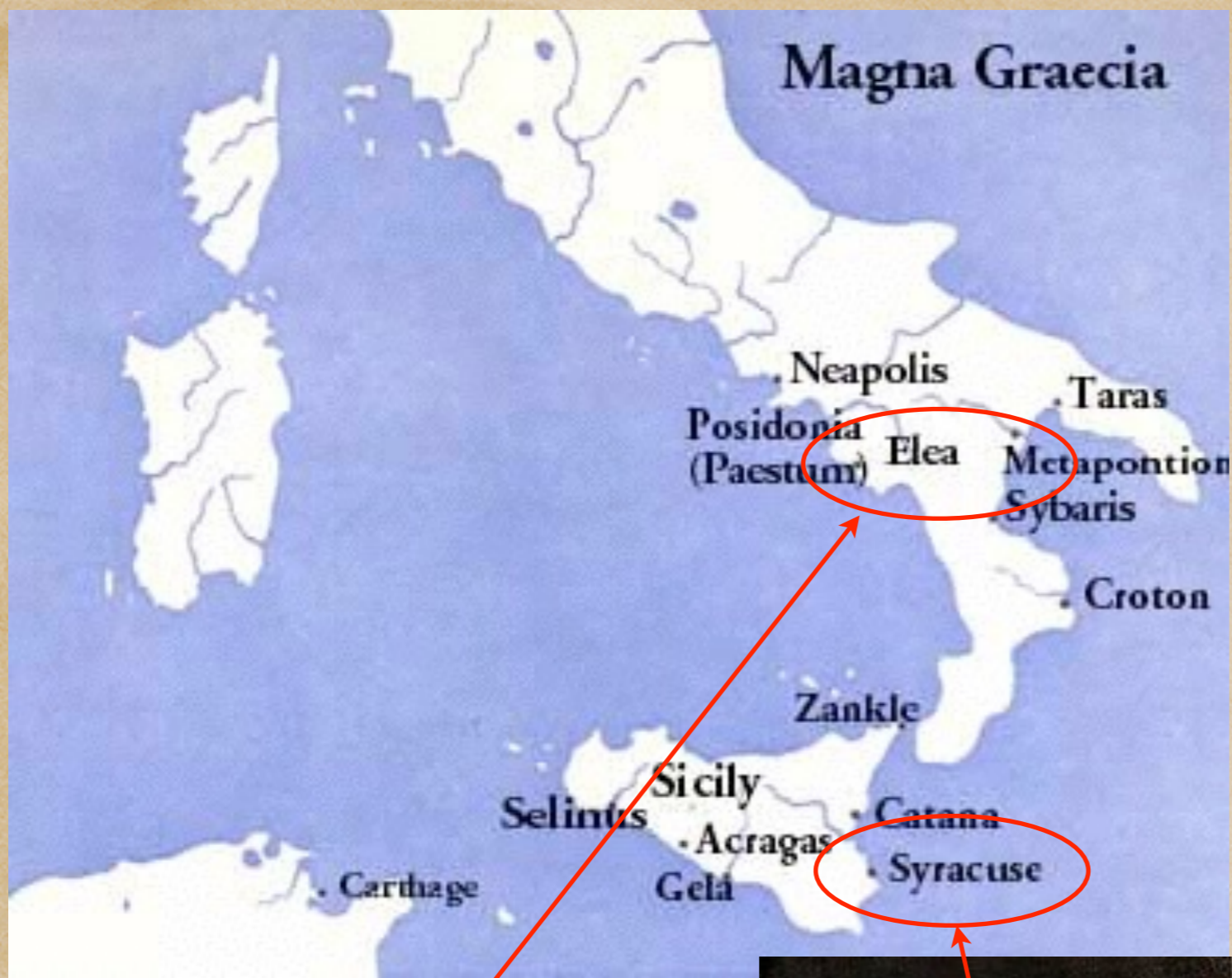


Zeno was  
born here



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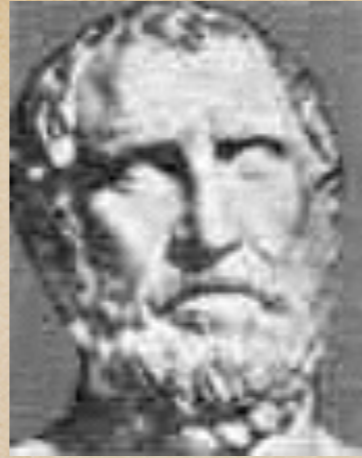


Zeno was born here



Archimedes

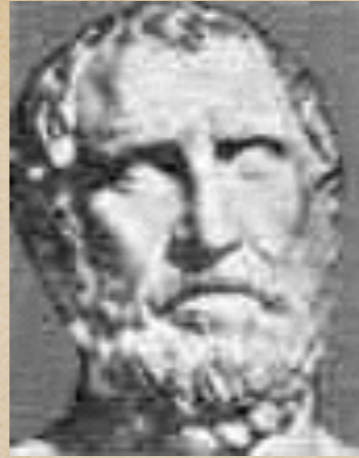
## Zeno of Elea



**Zeno** was an Eleatic philosopher, a native of Elea in Italy, son of Teleutagoras, and the favorite disciple of **Parmenides**. He was born about 488 BC, and at the age of forty accompanied Parmenides to Athens.

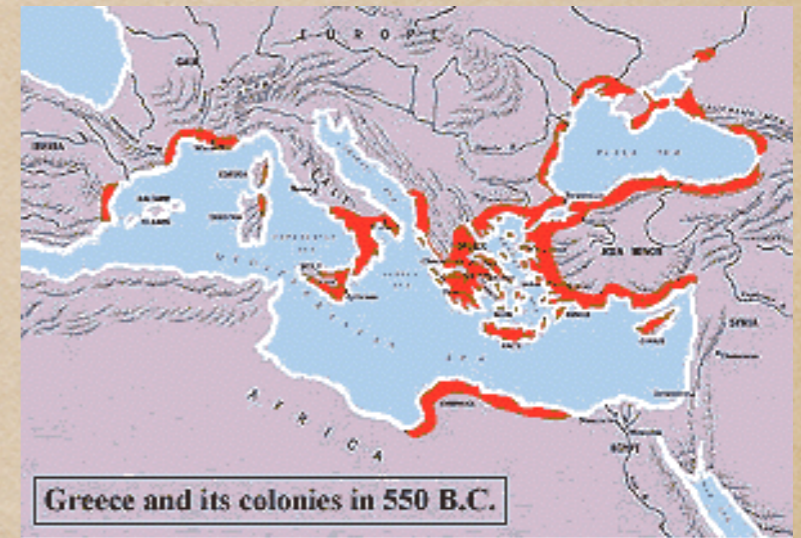
They were supposed to discuss politics but they spent most of the time discussing philosophy. They came back defeated.

# Zeno of Elea



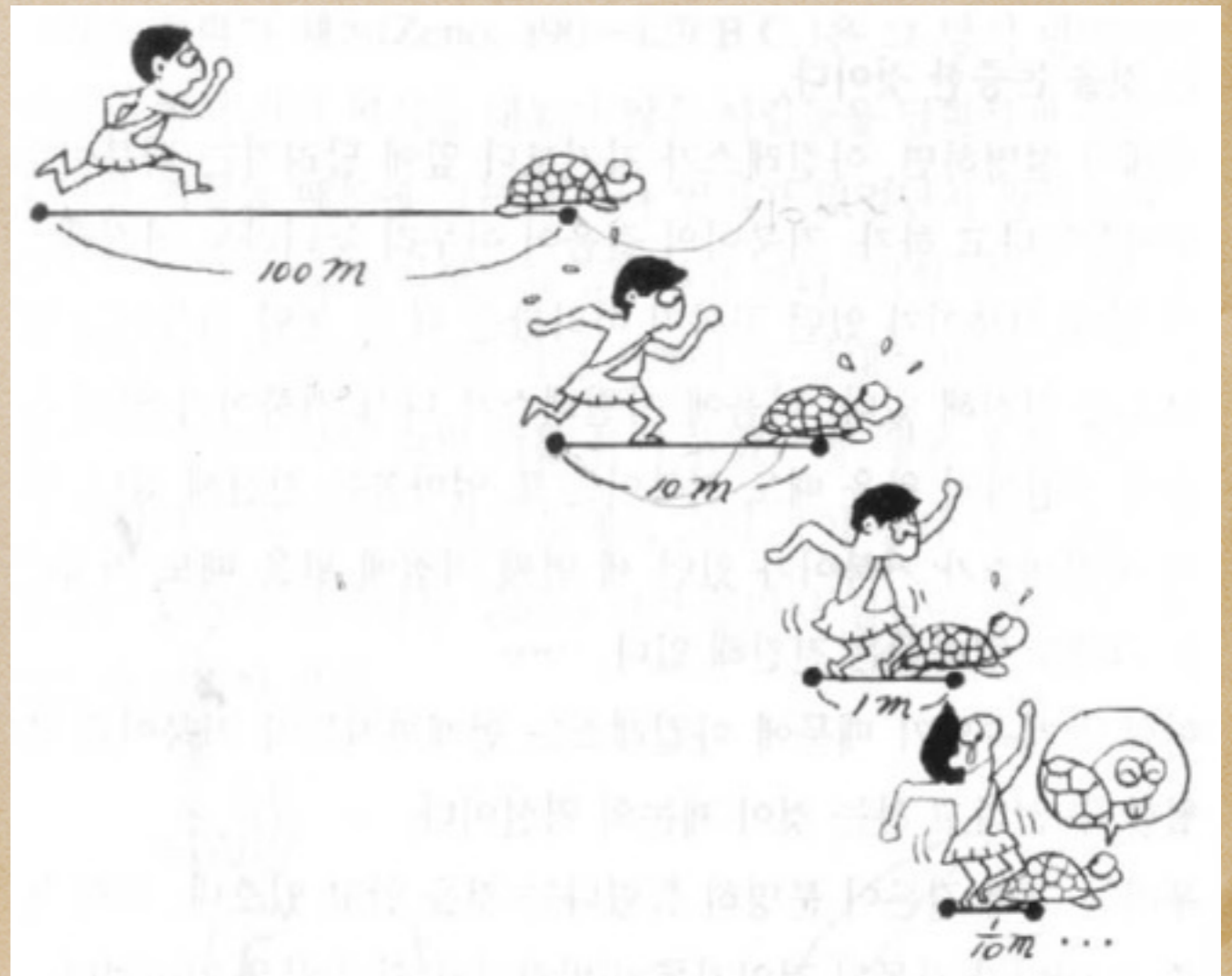
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# Zeno and Parmenides

- ◆ the paradoxes:
- ◆ the most famous one: the tortoise



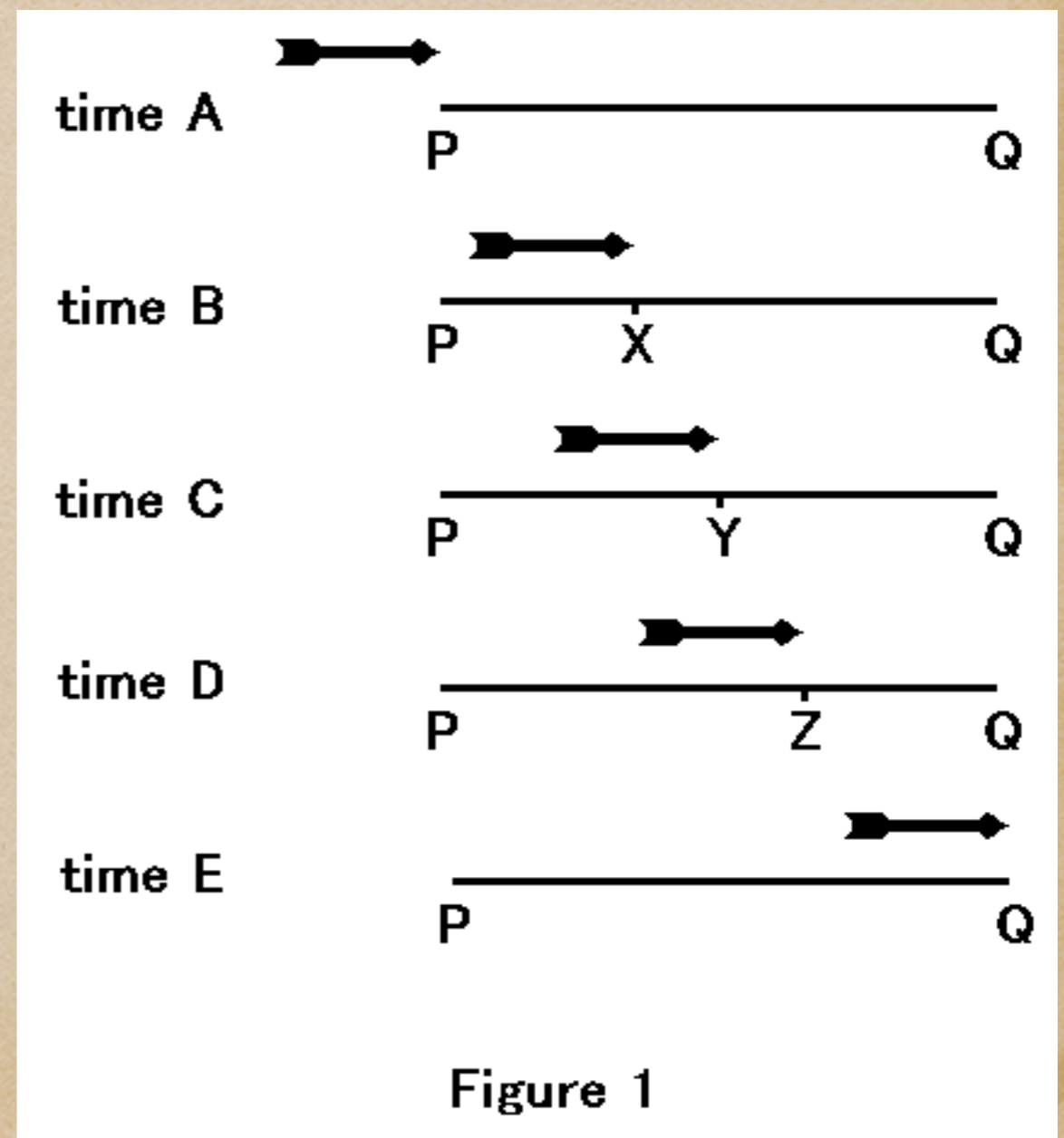
# Zeno and Parmenides

- ◆ the paradoxes: the sped arrow

# Zeno and Parmenides

## ◆ the paradoxes: the sped arrow

At any given moment the sped arrow is in a space equal to its own length, and therefore is at rest at that moment. So, it is at rest at all moments. The sum of an infinite number of these positions of rest is not a motion.



# Zeno and Parmenides

## ◆ the paradoxes: the sped arrow

notice: act of observation  
not (explicitly) mentioned

At any given moment the sped arrow is in a space equal to its own length, and therefore is at rest at that moment. So, it is at rest at all moments. The sum of an infinite number of these positions of rest is not a motion.

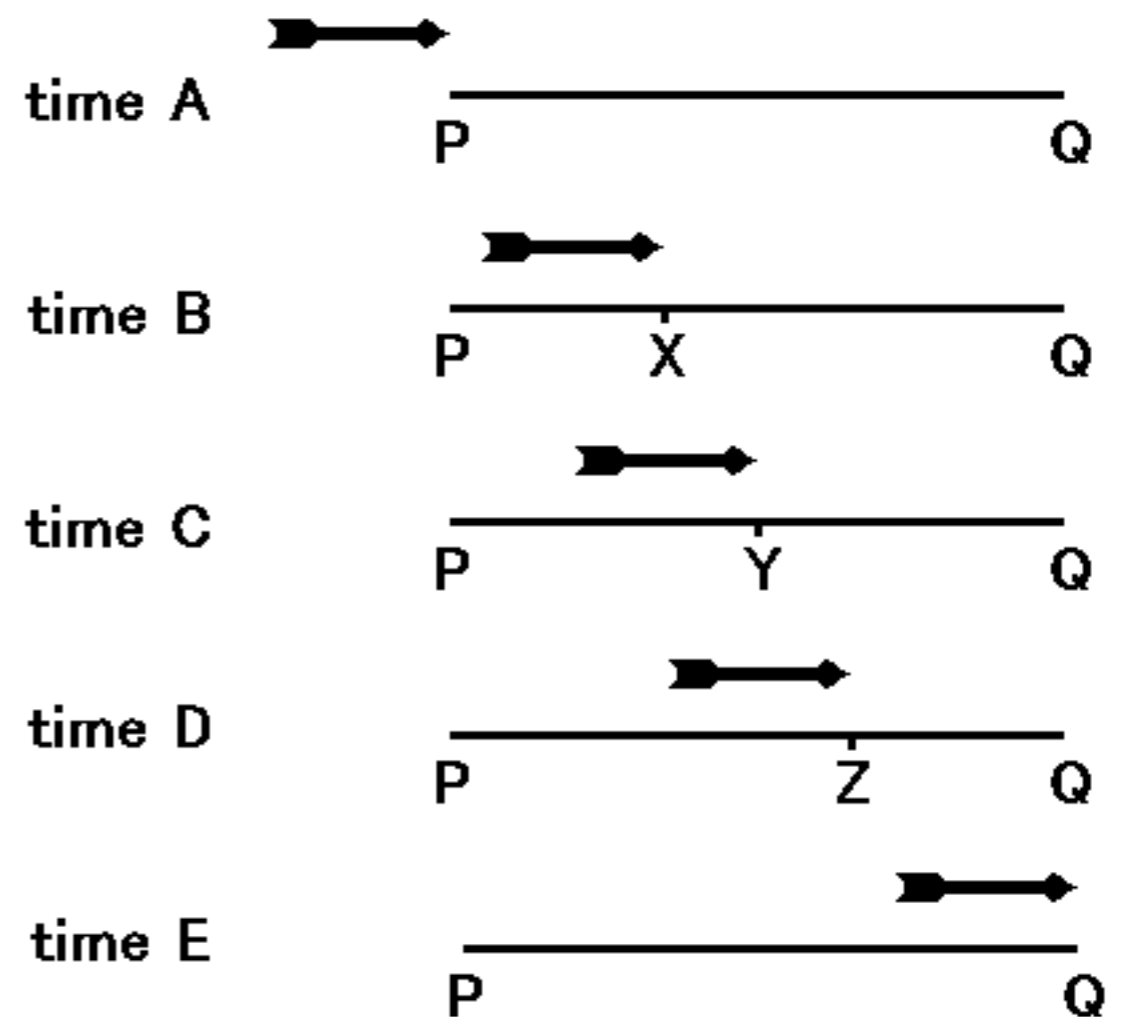


Figure 1

School of Athens  
(Raphael's Room of the Signature, Vatican Museums)





# School of Athens (Raphael's Room of the Signature, Vatican Museums)



*Plato &  
Aristotle*

*Parmenides*

*Pythagoras*

*Heraclitus  
(Michelangelo)*

*Raphael*

# School of Athens (Raphael's Room of the Signature, Vatican Museums)



*Zeno*

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# Quantum Zeno effect

quantum system

$\psi$

Hamiltonian

$H$

Schrodinger equation

$$\psi_t = e^{-iHt} \psi_0$$

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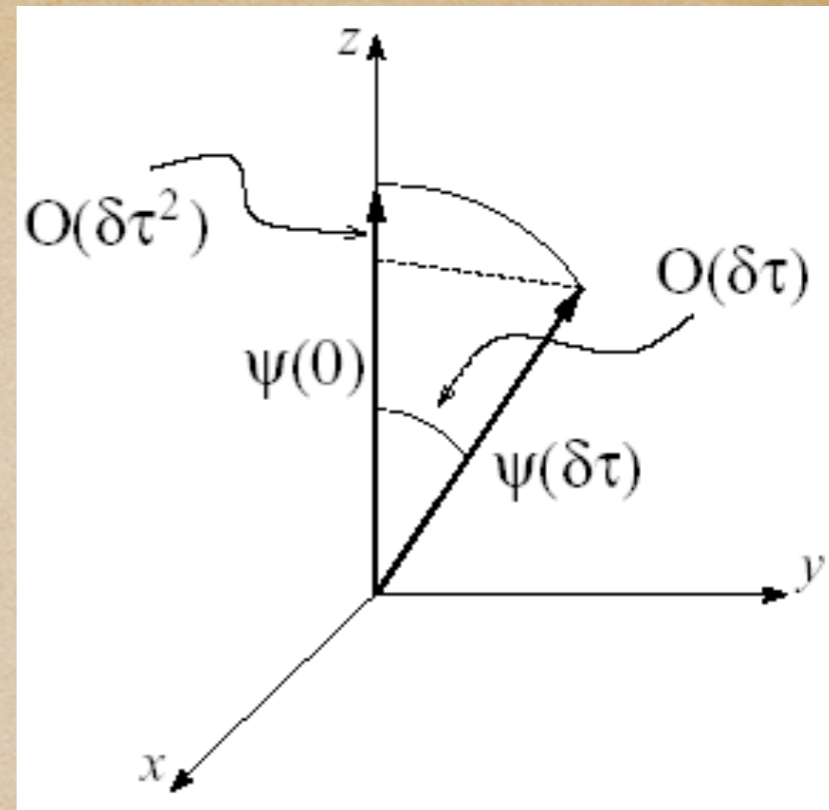
survival probability

$$p(t) = |\langle \psi_t | \psi_0 \rangle|^2 = 1 - t^2 / \tau_Z^2$$

$$\tau_Z^{-2} \equiv \langle \psi_0 | H^2 | \psi_0 \rangle - \langle \psi_0 | H | \psi_0 \rangle^2$$

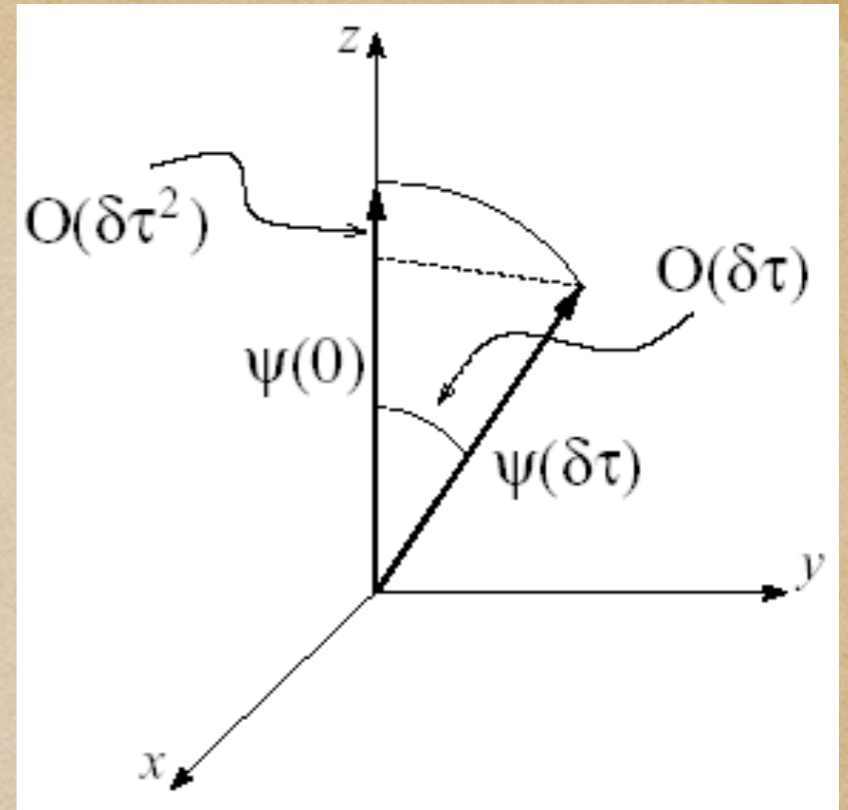
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$$[p(t/N)]^N \simeq \left( 1 - \frac{t^2}{\tau_Z^2 N^2} \right)^N \xrightarrow{N \rightarrow \infty} 1$$

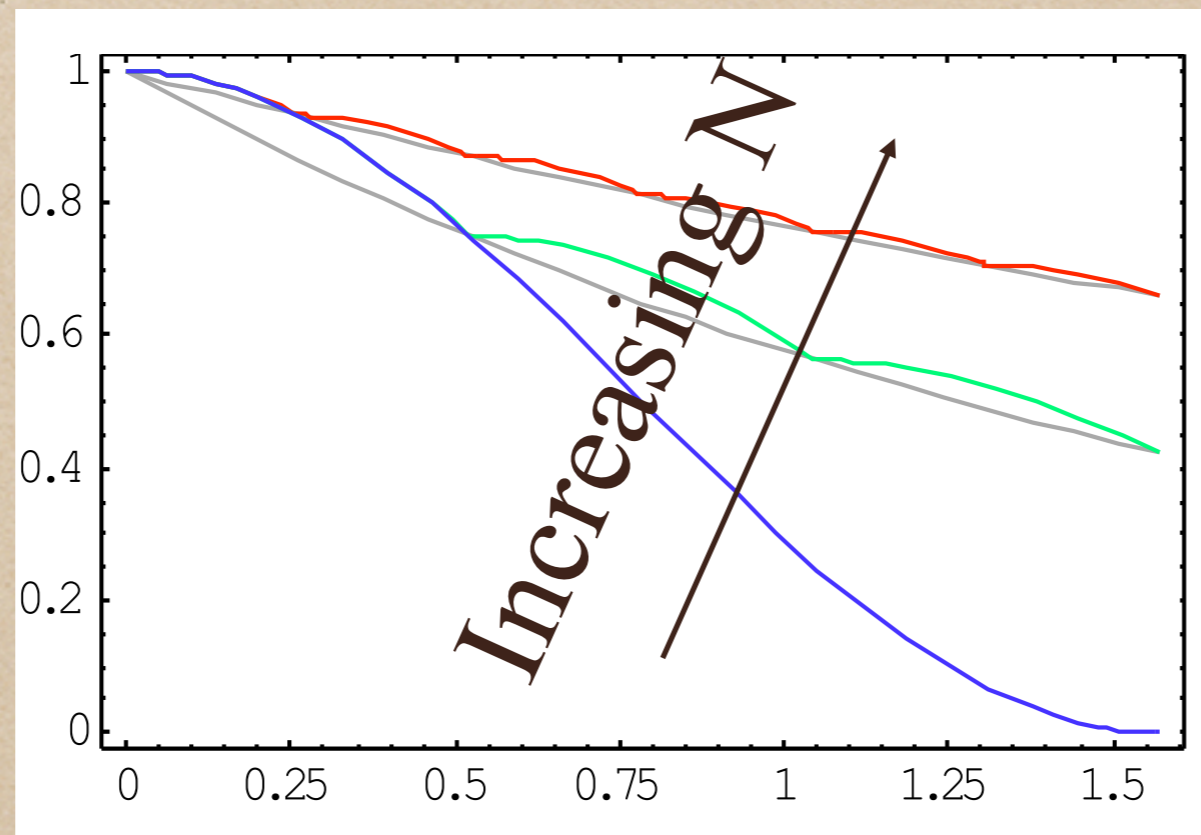
Frequent observations hinder dynamics

Quantum Zeno effect

$$[p(t/N)]^N \approx \left(1 - \frac{t^2}{\tau_Z^2 N^2}\right)^N \xrightarrow{N \rightarrow \infty} 1$$

MANY experiments on MANY physical systems

$$[p(t/N)]^N \simeq \left(1 - \frac{t^2}{\tau_Z^2 N^2}\right)^N \xrightarrow{N \rightarrow \infty} 1$$



$$[p(t/6)]^6$$

$$[p(t/3)]^3$$

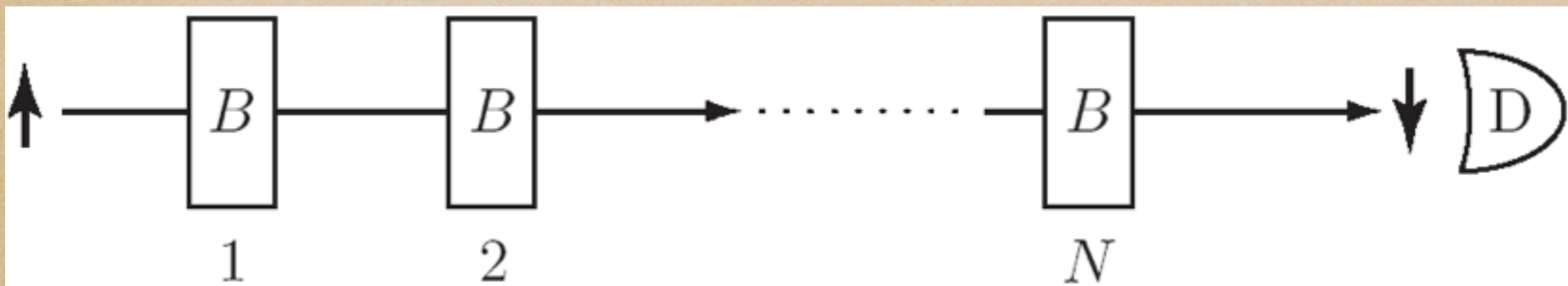
$$[p(t/1)]^1$$

**MANY** experiments on **MANY** physical systems

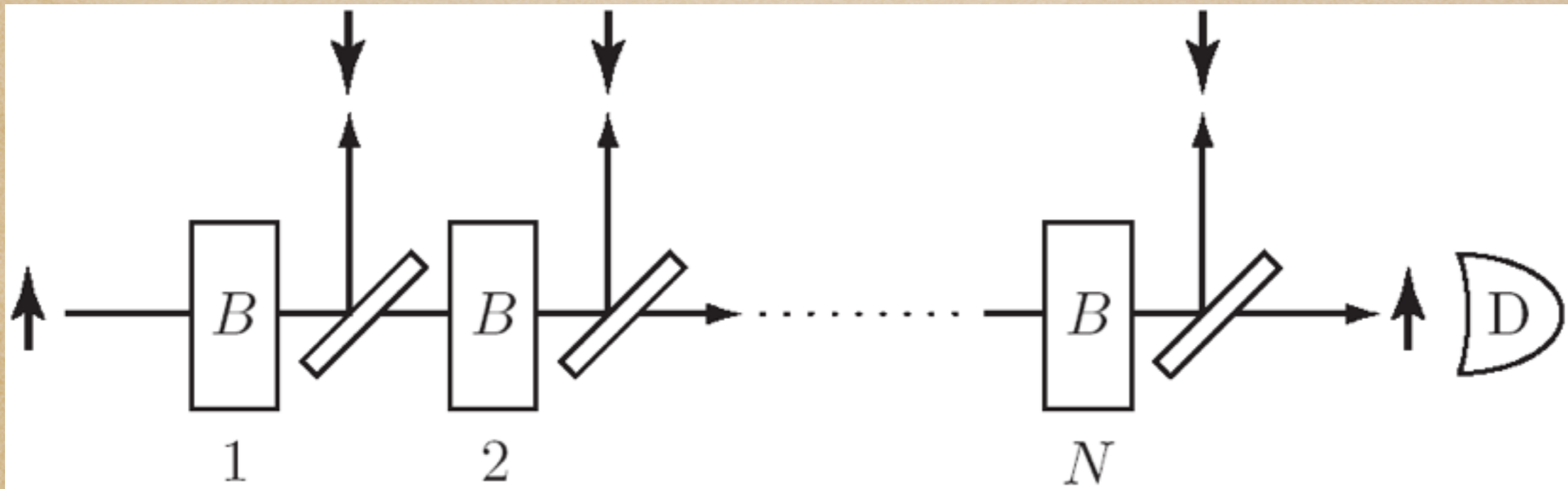


one expt: neutron spin

one expt: neutron spin

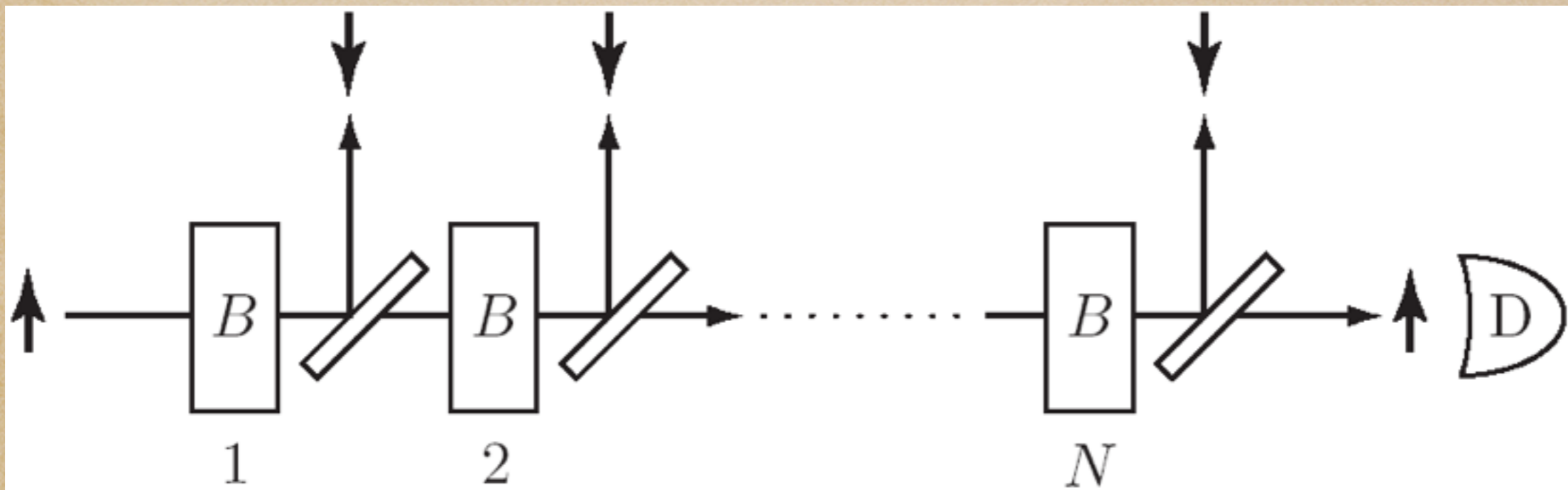


# one expt: neutron spin



Pascasio, Namiki, Badurek, Rauch, Phys. Lett. A **169**, 155 (1993)

# one expt: neutron spin



$$p(t) = \left| \langle \Psi(0) | \Psi(t) \rangle \right|^2 = \cos^2 \left( \frac{t}{\tau_Z} \right)$$

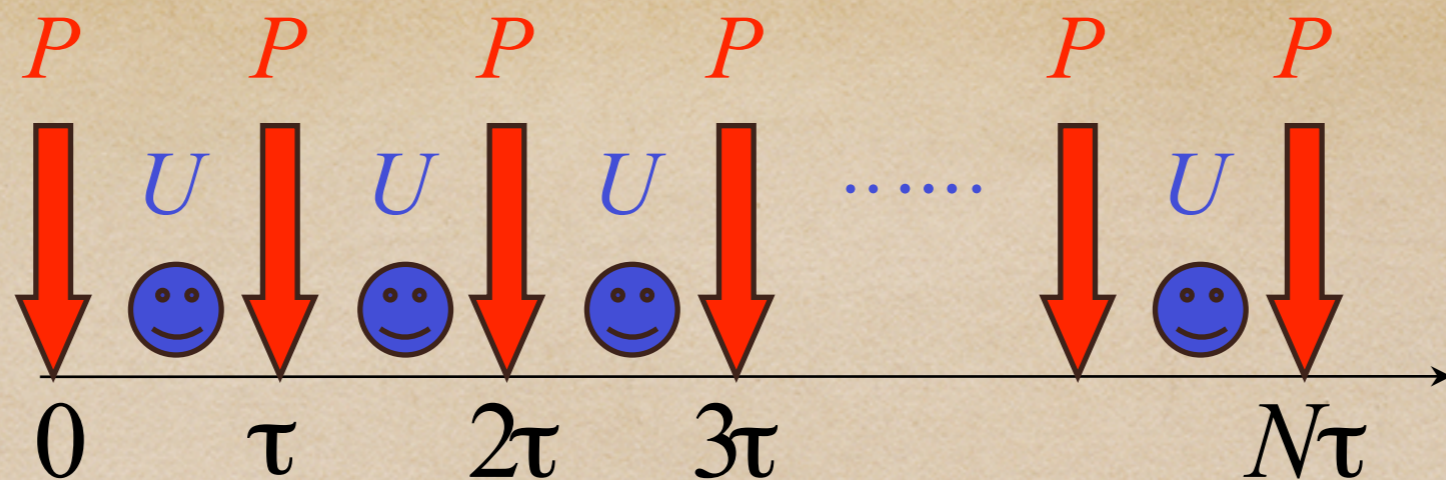
$$p^{(N)}(t) = p \left( \frac{t}{N} \right)^N = \cos^{2N} \left( \frac{t}{N\tau_Z} \right)$$

$$p^{(N)}(t) \xrightarrow{N \rightarrow \infty} 1$$

Pascazio, Namiki, Badurek, Rauch, Phys. Lett. A **169**, 155 (1993)

Repeated observation freeze system in its initial state

Formulation due to Misra and Sudarshan 1977



$$\rho^{(N)}(t) = V_N(t) \rho_0 V_N(t)^\dagger, \quad V_N(t) = [P U(t/N) P]^N$$

The probability to find the system in  $\mathcal{H}_P$  reads

$$p^{(N)}(t) = \text{Tr}[V_N(t) \rho_0 V_N(t)^\dagger] \xrightarrow{N \rightarrow \infty} \text{Tr}[P \rho_0] = 1$$

Repeated observation freeze system in its initial state

Formulation due to **Misra and Sudarshan 1977**

# examples and theorems

- ◆ the value of proof
- ◆ Franco (+ myself)
- ◆ Beppe: time consuming

# examples and theorems

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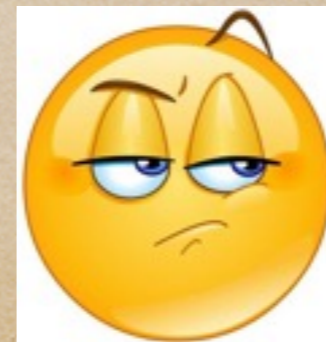


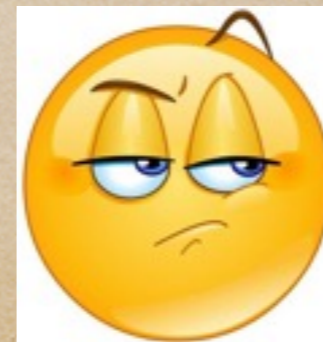
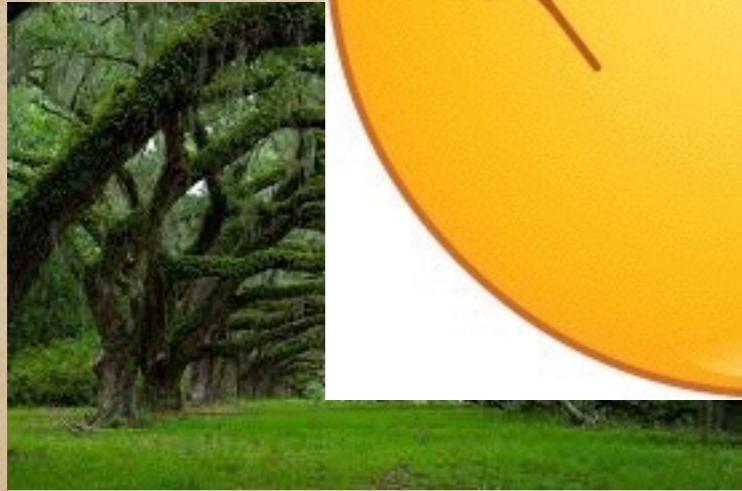
# examples and theorems

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Very  
Good

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## THE GEOMETRY OF THE QUANTUM ZENO EFFECT

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### 3. Geometry of Quantum Mechanics

States are not vectors  $|\psi\rangle \in \mathcal{H}$  but rather rays, elements of the Hilbert manifold  $\mathbb{P}\mathcal{H}$ , which can be conveniently parametrized as rank-one projection operators. This projection map enables one to identify on  $\mathbb{P}\mathcal{H}$  a metric tensor, usually called the Fubini–Study metric, and a symplectic structure [9, 10]. Both of them define on  $\mathbb{P}\mathcal{H}$  that is called a Kählerian structure. To work with this tensor on  $\mathcal{H}$  instead of  $\mathbb{P}\mathcal{H}$  is quite convenient for computational purposes.

We shall consider finite-dimensional systems. Let  $\mathcal{H} \simeq \mathbb{C}^n$  and introduce the orthonormal basis  $\{|e_1\rangle, \dots, |e_n\rangle\}$  and coordinates  $z_k = (q_k + ip_k)$ . This entails

$$\mathcal{H} \rightarrow \mathbb{C}^n \rightarrow \mathbb{R}^{2n}, \quad (3.1)$$

with

$$|\psi\rangle \mapsto \begin{pmatrix} \langle e_1|\psi\rangle \\ \langle e_2|\psi\rangle \\ \vdots \\ \langle e_n|\psi\rangle \end{pmatrix} =: \begin{pmatrix} z_1 \\ z_2 \\ \vdots \\ z_n \end{pmatrix} =: \begin{pmatrix} q_1 + ip_1 \\ q_2 + ip_2 \\ \vdots \\ q_n + ip_n \end{pmatrix} \mapsto \begin{pmatrix} q_1 \\ \vdots \\ q_n \\ p_1 \\ \vdots \\ p_n \end{pmatrix}. \quad (3.2)$$

The complex inner product of  $\mathcal{H}$  induces the Hermitian structure

$$\mathfrak{h} = \sum_k d\bar{z}_k \otimes dz_k = \mathfrak{g} + \frac{i}{2}\omega, \quad (3.3)$$

where

$$\mathfrak{g} = \frac{1}{2} \sum_k (d\bar{z}_k \otimes dz_k + dz_k \otimes d\bar{z}_k) = \sum_k d\bar{z}_k \otimes_s dz_k, \quad (3.4)$$

$$\omega = -i \sum_k (d\bar{z}_k \otimes dz_k - dz_k \otimes d\bar{z}_k) = -i \sum_k d\bar{z}_k \wedge dz_k \quad (3.5)$$

are a Riemannian metric and a symplectic form, respectively. In terms of the real coordinates, they read

$$\mathfrak{g} = \sum_k (dq_k \otimes dq_k + dp_k \otimes dp_k), \quad \omega = 2 \sum_k dq_k \wedge dp_k, \quad (3.6)$$

respectively. Let us introduce the dual coordinate vector fields

$$\frac{\partial}{\partial z_k} = \frac{1}{2} \left( \frac{\partial}{\partial q_k} - i \frac{\partial}{\partial p_k} \right), \quad dz_j \left( \frac{\partial}{\partial z_k} \right) = \frac{\partial}{\partial z_k} z_j = \delta_j^k, \quad d\bar{z}_j \left( \frac{\partial}{\partial z_k} \right) = 0 \quad (3.7)$$

and analogously for  $\frac{\partial}{\partial \bar{z}_k}$ . In terms of them we can write the contravariant form of the Hermitian structure

$$K = \sum_k \frac{\partial}{\partial \bar{z}_k} \otimes \frac{\partial}{\partial z_k} = G + \frac{i}{2}\Omega, \quad (3.8)$$

where

$$G = \sum_k \frac{\partial}{\partial \bar{z}_k} \otimes_s \frac{\partial}{\partial z_k} = \frac{1}{4} \sum_k \left( \frac{\partial}{\partial q_k} \otimes \frac{\partial}{\partial q_k} + \frac{\partial}{\partial p_k} \otimes \frac{\partial}{\partial p_k} \right), \quad (3.9)$$

$$\Omega = -i \sum_k \frac{\partial}{\partial \bar{z}_k} \wedge \frac{\partial}{\partial z_k} = -\frac{1}{2} \sum_k \frac{\partial}{\partial q_k} \wedge \frac{\partial}{\partial p_k}. \quad (3.10)$$

By using  $\Omega$  we can construct the Hamiltonian vector field  $X_f$  generated by any (smooth) Hamiltonian function  $f$ , in the standard way, i.e.

$$X_f = \Omega(df, \cdot) = -i \sum_k \left( \frac{\partial f}{\partial \bar{z}_k} \frac{\partial}{\partial z_k} - \frac{\partial f}{\partial z_k} \frac{\partial}{\partial \bar{z}_k} \right) = \frac{1}{2} \sum_k \left( \frac{\partial f}{\partial p_k} \frac{\partial}{\partial q_k} - \frac{\partial f}{\partial q_k} \frac{\partial}{\partial p_k} \right). \quad (3.11)$$

It is easy to verify that it satisfies the equation  $\omega(X_f, \cdot) = df$ . The tensor  $\Omega$  defines also a Lie-algebra structure on functions, with the Poisson brackets

$$\begin{aligned} \{f, g\} &= \Omega(df, dg) \\ &= -i \sum_k \left( \frac{\partial f}{\partial \bar{z}_k} \frac{\partial g}{\partial z_k} - \frac{\partial f}{\partial z_k} \frac{\partial g}{\partial \bar{z}_k} \right) = \frac{1}{2} \sum_k \left( \frac{\partial f}{\partial p_k} \frac{\partial g}{\partial q_k} - \frac{\partial f}{\partial q_k} \frac{\partial g}{\partial p_k} \right). \end{aligned} \quad (3.12)$$

On the other hand,  $G$  defines a Jordan algebra on all quadratic functions, with the Jordan brackets

$$\begin{aligned} \{f, g\}_+ &= G(df, dg) \\ &= \frac{1}{2} \sum_k \left( \frac{\partial f}{\partial \bar{z}_k} \frac{\partial g}{\partial z_k} + \frac{\partial f}{\partial z_k} \frac{\partial g}{\partial \bar{z}_k} \right) = \frac{1}{4} \sum_k \left( \frac{\partial f}{\partial q_k} \frac{\partial g}{\partial q_k} + \frac{\partial f}{\partial p_k} \frac{\partial g}{\partial p_k} \right). \end{aligned} \quad (3.13)$$

The real quadratic functions are the expectation values of observables

$$f_A(\psi) = \langle \psi | A | \psi \rangle = \sum_{k,l} \bar{z}_k A_{kl} z_l. \quad (3.14)$$

$(\Omega, G)$  defines a Lie–Jordan algebra on these expectation values,

$$\{f_A, f_B\} = f_{i(AB-BA)}, \quad \{f_A, f_B\}_+ = f_{\frac{1}{2}(AB+BA)}, \quad (3.15)$$

isomorphic to the Lie–Jordan algebra of the observables.

The Hamilton equations, whose Hamiltonian vector fields (3.11) are generated by quadratic functions  $f_H = \langle \psi | H | \psi \rangle$ ,

$$\dot{z}_k = X_{f_H}(z_k) = -i \frac{\partial f}{\partial \bar{z}_k} = -i \sum H_{kl} z_l, \quad (3.16)$$

are nothing but the Schrödinger equation with Hamiltonian operator  $H$ ,  $\dot{\psi} = H\psi$ . The evolution of any expectation value (3.14) is given in terms of the Poisson brackets

$$\dot{f}_A = \{f_H, f_A\} = f_{i(HA-AH)}, \quad (3.17)$$

which is the Heisenberg equation for the operator  $A$ ,  $\langle \psi | \dot{A} | \psi \rangle = \langle \psi | i(HA - AH) | \psi \rangle$ .

Projectability onto  $\mathbb{P}\mathcal{H}$  requires a conformal factor

$$\tilde{G}(\psi) = \langle \psi | \psi \rangle G(\psi), \quad \tilde{\Omega}(\psi) = \langle \psi | \psi \rangle \Omega(\psi). \quad (3.18)$$

Observe that  $\tilde{\Omega}$  does not satisfy the Jacobi identity anymore. However, it does on expectation values. Thus,  $\tilde{\Omega}$  projects onto  $\mathbb{P}\mathcal{H}$ , a Poisson space. Moreover, one should consider homogeneous expectation values

$$\tilde{f}_A = \frac{\langle \psi | A | \psi \rangle}{\langle \psi | \psi \rangle}. \quad (3.19)$$

We are now ready to make the first key observation: the Zeno time (2.4) is the inverse length of the Hamiltonian vector field on the complex projective space, i.e.

$$\tau_Z^{-2} = \tilde{G}(d\tilde{f}_H, d\tilde{f}_H). \quad (3.20)$$

Indeed, we have

$$d\tilde{f}_H = \frac{1}{\|\psi\|^2} (df_H - \tilde{f}_H d\|\psi\|^2), \quad (3.21)$$

and from (3.15) we get

$$G(df_H, df_H) = \{f_H, f_H\}_+ = f_{H^2} = \langle \psi | H^2 | \psi \rangle. \quad (3.22)$$

Therefore,

$$\begin{aligned} \tilde{G}(d\tilde{f}_H, d\tilde{f}_H) &= \frac{1}{\|\psi\|^2} G(df_H - e_H d\|\psi\|^2, df_H - e_H d\|\psi\|^2) \\ &= \tilde{f}_{H^2} - (\tilde{f}_H)^2 = (\Delta H)^2. \end{aligned} \quad (3.23)$$

#### 4. An Example: The Qubit

Let  $\mathcal{H} \simeq \mathbb{C}^2 \simeq \mathbb{R}^4$  with Hamiltonian

$$H = h_0 \mathbb{I} + \vec{h} \cdot \vec{\sigma}, \quad (4.1)$$

where  $\vec{\sigma} = (\sigma_x, \sigma_y, \sigma_z)$  is the vector of Pauli matrices,  $h_0 \in \mathbb{R}$ , and  $\vec{h} = (h_x, h_y, h_z) \in \mathbb{R}^3$ . We introduce coordinates  $z_1, z_2$  in the eigenbasis of  $\sigma_z$ , i.e.  $\sigma_z |e_j\rangle = (-1)^j |e_j\rangle$ ,  $j = 1, 2$ . The expectation value (3.14) of the Hamiltonian  $H$  reads

$$f_H = \langle \psi | H | \psi \rangle = h_0 u + h_x x + h_y y + h_z z = h_0 u + \vec{h} \cdot \vec{x}, \quad (4.2)$$

where the quadratic functions  $u, x, y, z$  are the expectation values of the Pauli matrices

$$\begin{aligned} u &= f_{\mathbb{I}} = |z_1|^2 + |z_2|^2 = q_1^2 + p_1^2 + q_2^2 + p_2^2, \\ x &= f_{\sigma_x} = \bar{z}_1 z_2 + \bar{z}_2 z_1 = 2(q_1 q_2 + p_1 p_2), \\ y &= f_{\sigma_y} = -i(\bar{z}_1 z_2 - \bar{z}_2 z_1) = 2(q_1 p_2 - p_1 q_2), \\ z &= f_{\sigma_z} = |z_1|^2 - |z_2|^2 = q_1^2 + p_1^2 - q_2^2 - p_2^2. \end{aligned} \quad (4.3)$$

Notice that  $u$  and  $\vec{x}$  are not independent, since

$$u^2 = (|z_1|^2 + |z_2|^2)^2 = x^2 + y^2 + z^2 = \vec{x}^2. \quad (4.4)$$

By making use of (4.4) we easily get that the Zeno time (2.4) is

$$\tau_Z^{-2} = \tilde{G}(d\tilde{f}_H, d\tilde{f}_H) = \tilde{f}_{H^2} - (\tilde{f}_H)^2 = \vec{h}^2 - \frac{(\vec{h} \cdot \vec{x})^2}{u^2} = \frac{(\vec{h} \wedge \vec{x})^2}{\vec{x}^2}, \quad (4.5)$$

where  $\wedge$  is the vector product in  $\mathbb{R}^3$ .

Let us now consider the Zeno effect with projection

$$P = |e_1\rangle\langle e_1| = \frac{1}{2}(\mathbb{I} + \sigma_3). \quad (4.6)$$

The Zeno dynamics (2.6) becomes

$$U_Z(t) = e^{-iH_Z t} P, \quad H_Z = PHP = \frac{h_0 + h_z}{2}(\mathbb{I} + \sigma_3). \quad (4.7)$$

The Zeno Hamiltonian function reads

$$f_{H_Z} = \frac{h_0 + h_z}{2}(u + z) = (h_0 + h_z)|z_1|^2 = (h_0 + h_z)(q_1^2 + p_1^2), \quad (4.8)$$

which should be compared to the “free” Hamiltonian function (4.2) and (4.3). The infinitesimal generator of the Zeno dynamics is

$$X_Z = -i(h_0 + h_z) \left( z_1 \frac{\partial}{\partial z_1} - \bar{z}_1 \frac{\partial}{\partial \bar{z}_1} \right) = 2(h_0 + h_z) \left( p_1 \frac{\partial}{\partial q_1} - q_1 \frac{\partial}{\partial p_1} \right) \quad (4.9)$$

and the dynamics reads

$$\dot{u} = 0, \quad \dot{x} = -2(h_0 + h_z)y, \quad \dot{y} = 2(h_0 + h_z)x, \quad \dot{z} = 0. \quad (4.10)$$

Observe that, due to (4.4), the first equation,  $\dot{u} = 0$ , entails that the flow is on the sphere  $|\vec{x}| = \text{constant}$ . This flow is depicted in Fig. 1.

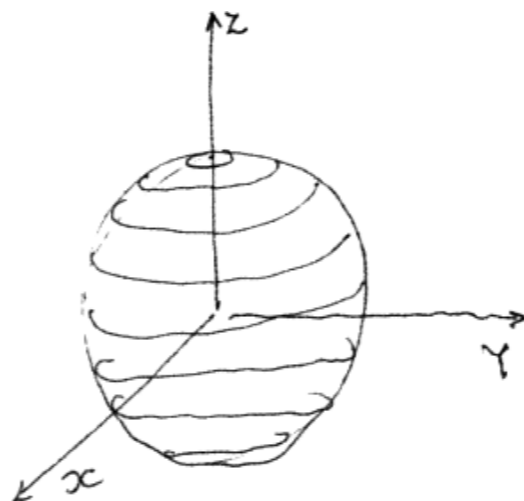
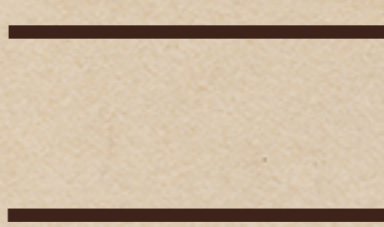


Fig. 1. Zeno flow of a qubit subject to measurement  $P = \frac{1}{2}(\mathbb{I} + \sigma_3)$ , according to Beppe Marmo, author of the drawing.

IN QZE, *system* need not be 1D...

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example:

measure  $\longrightarrow$    $|1\rangle$   
 $|0\rangle = |\text{in}\rangle$

system remains in initial state

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more interesting

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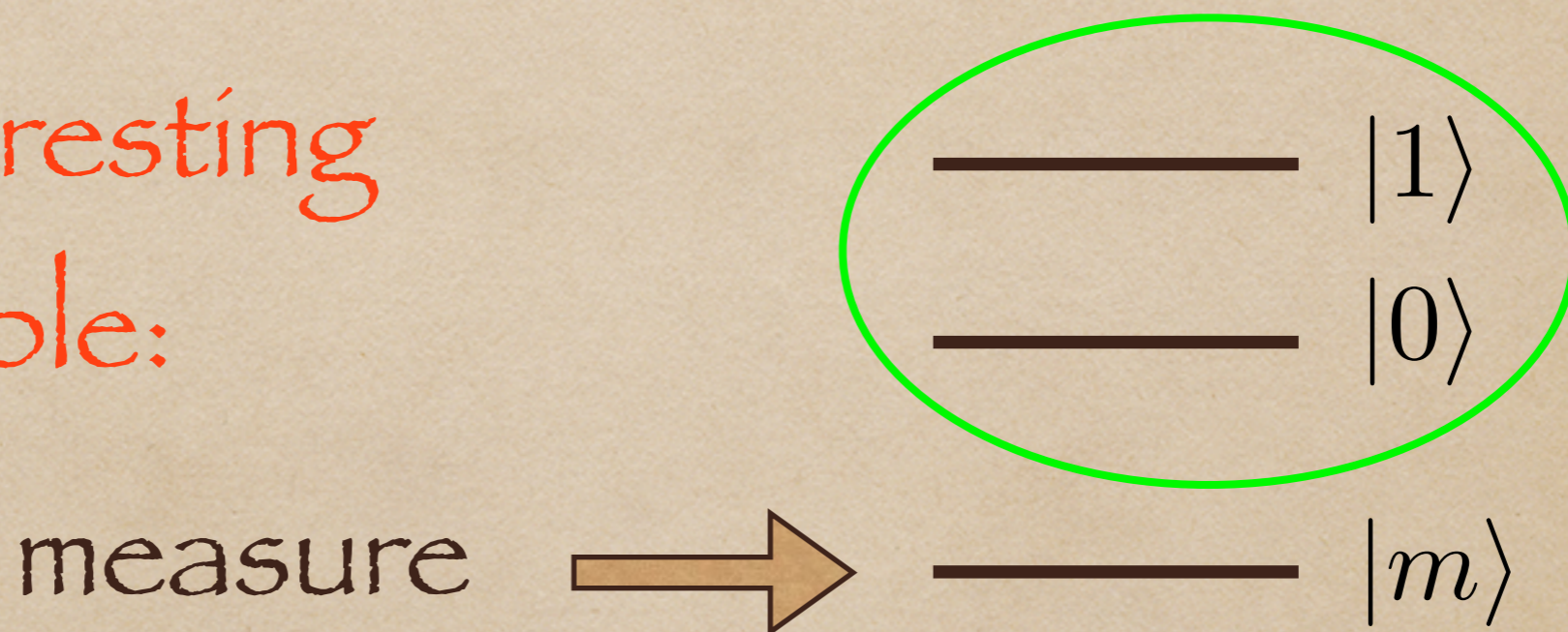
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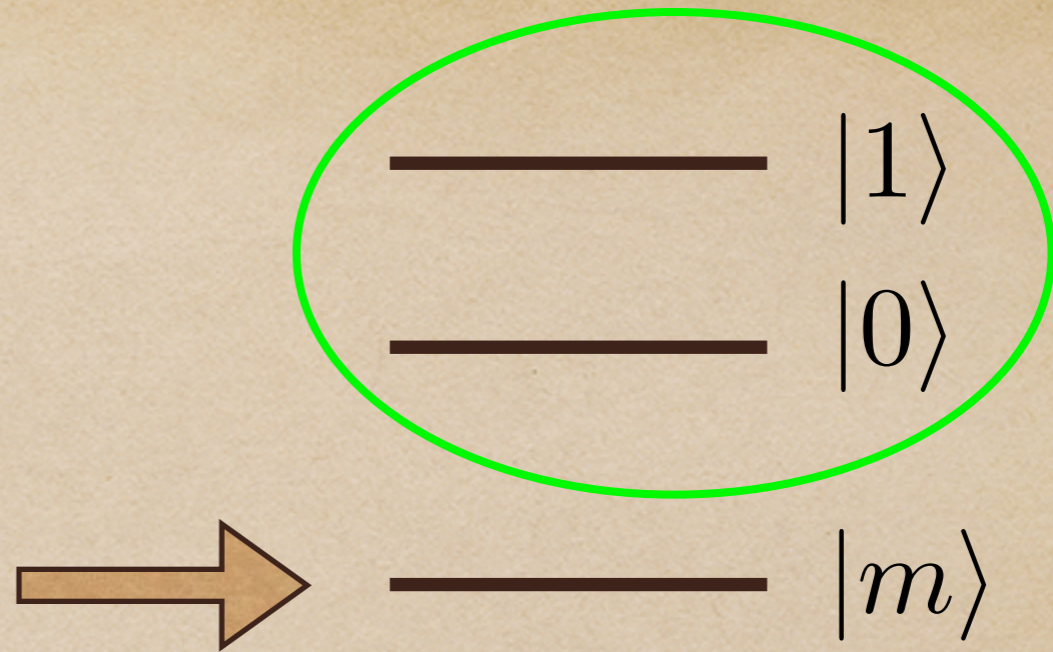
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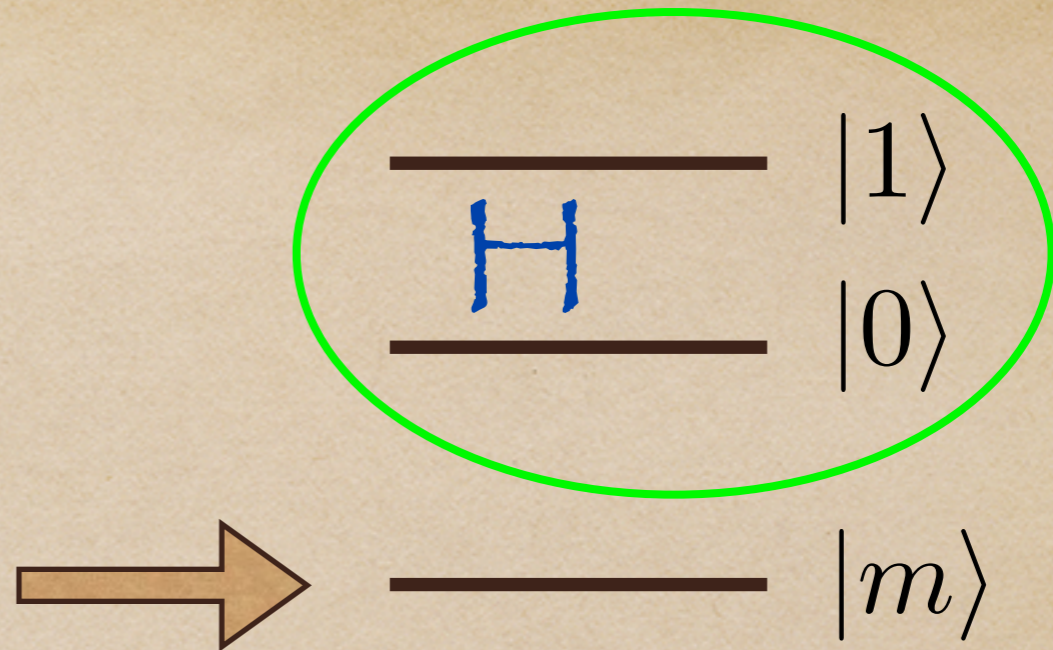


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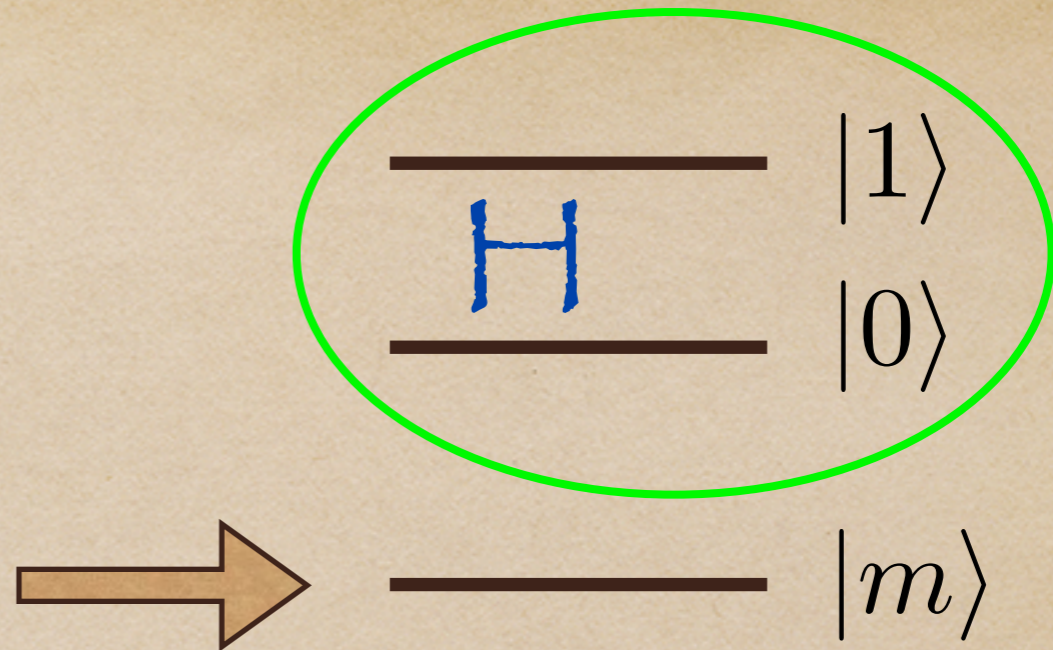


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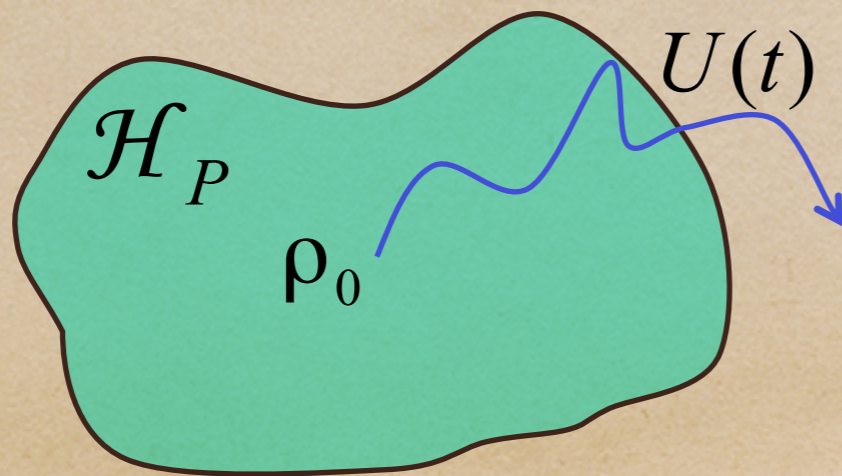
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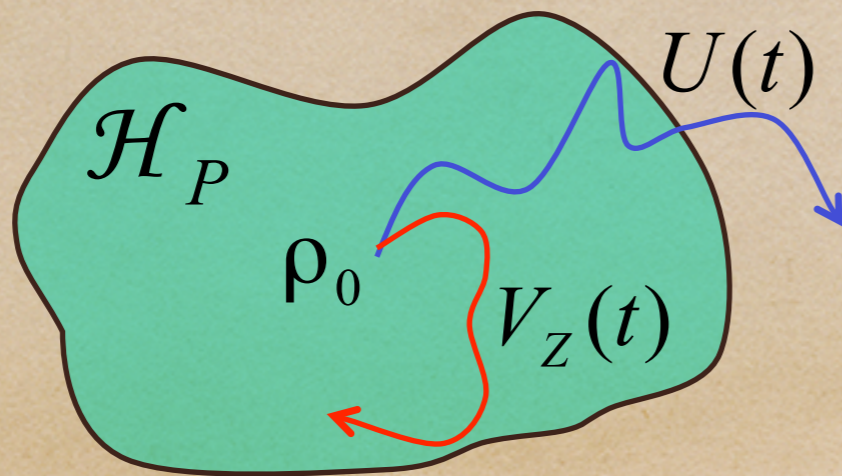
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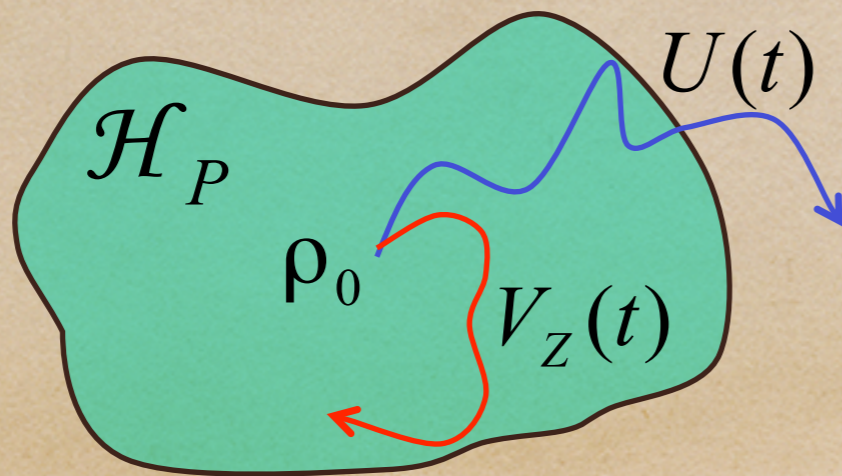
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Friedman 1972

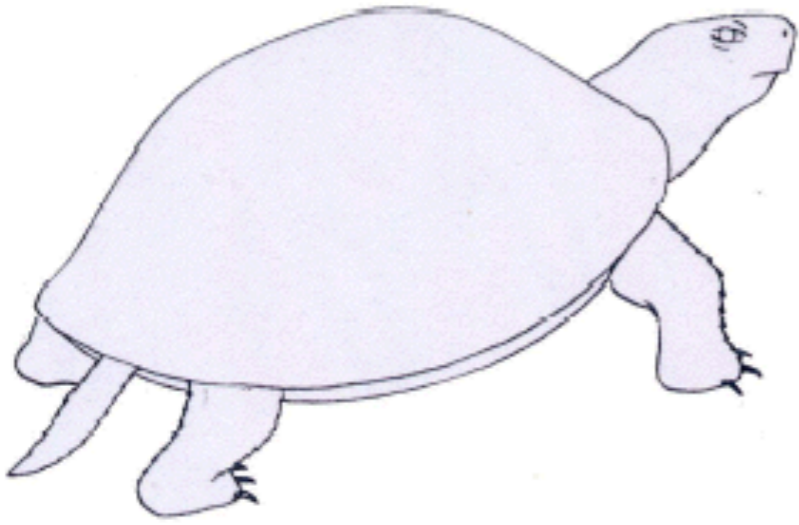
Facchi, Gorini, Marmo, Pascazio, Sudarshan 2000

Exner, Ichinose 2005

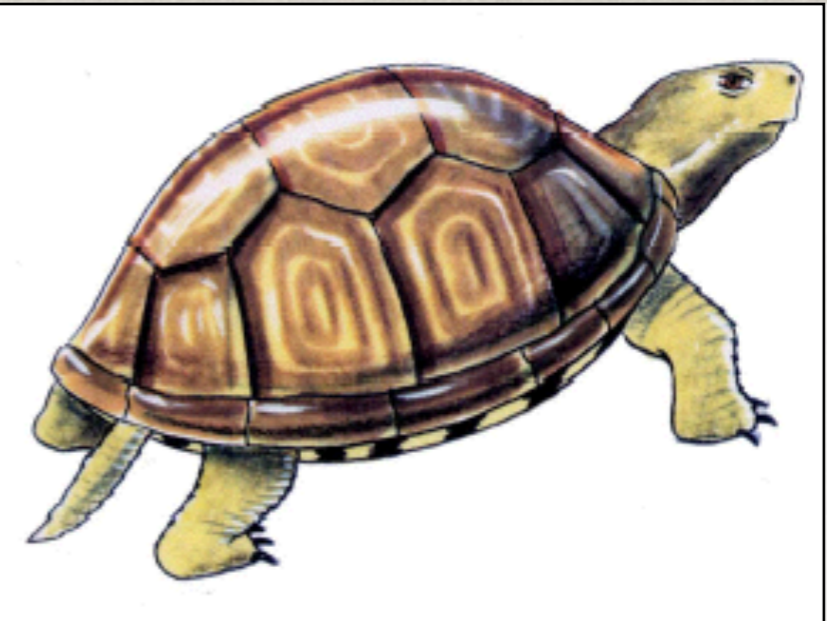
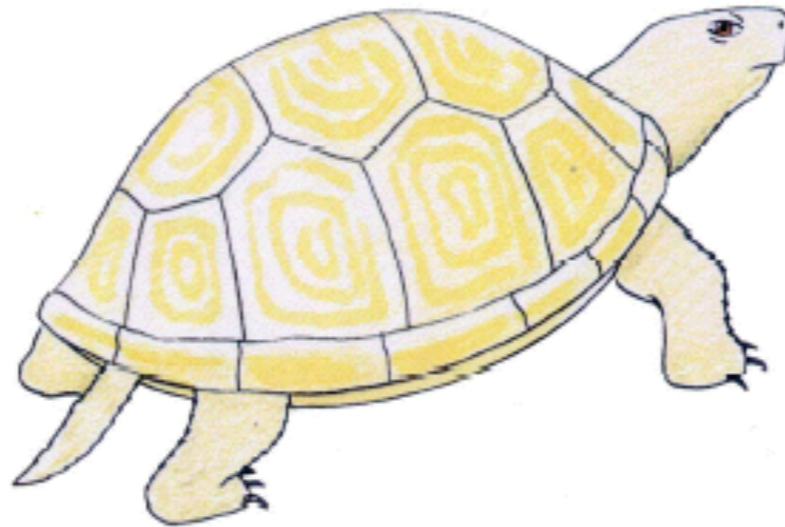
Facchi et al >2008



# Quantum Zeno subspaces

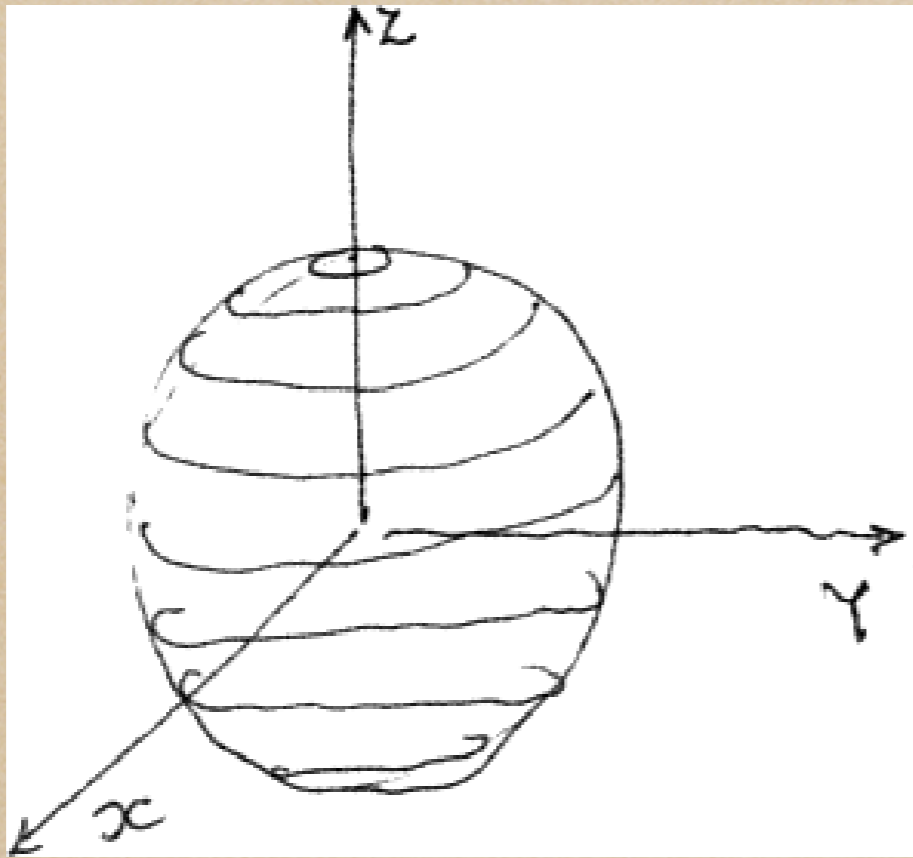


**DYNAMICAL  
SUPERSELECTION  
SECTORS**



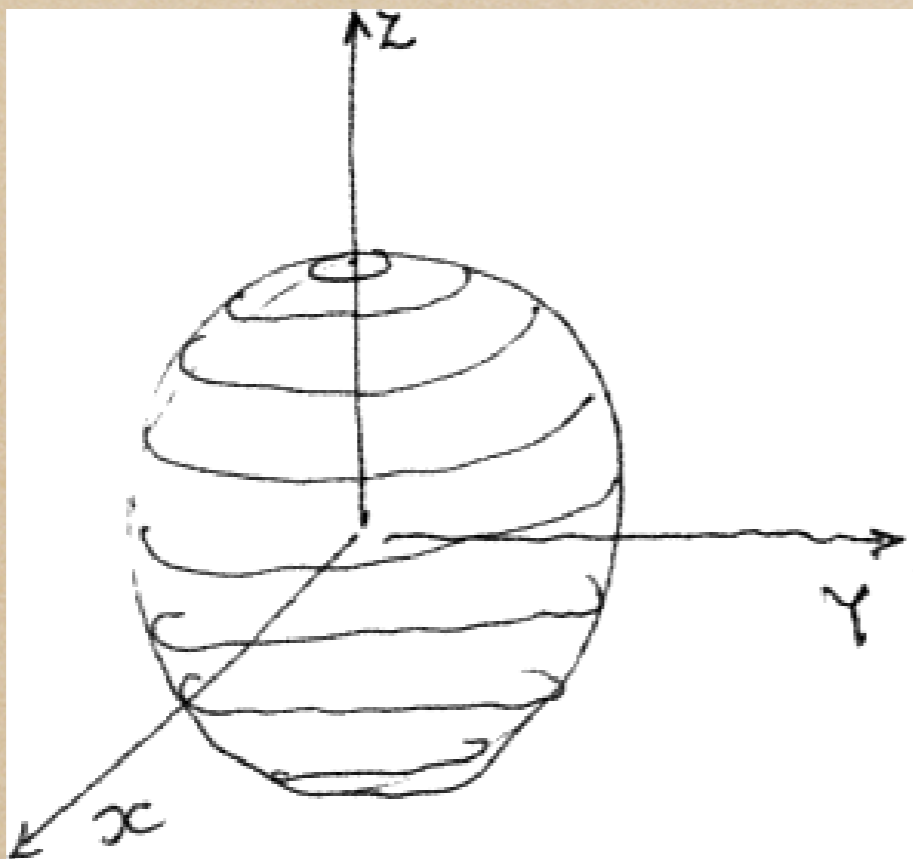
**Coupling  
or  $N$**

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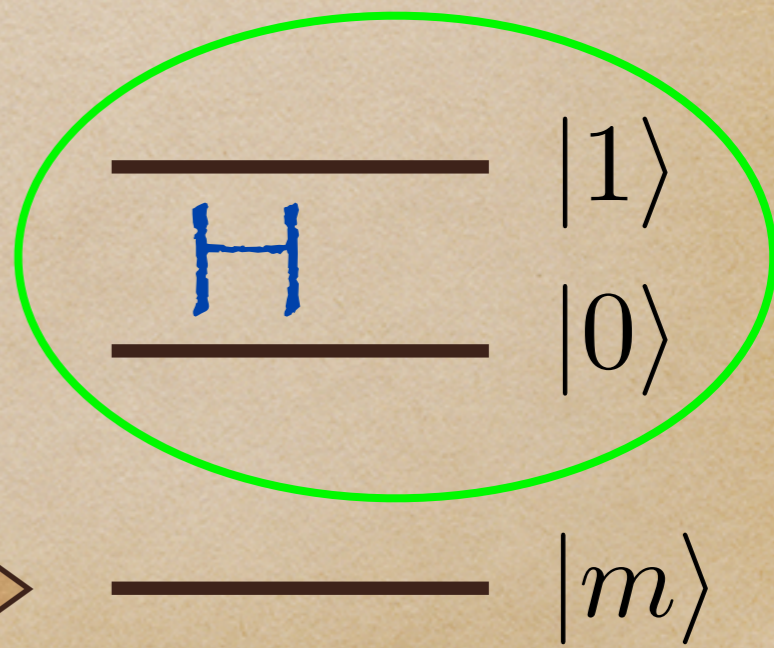
← Beppe's

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challenge (for the youngest in the audience): extend to qutrit



# Folding and unfolding



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Carinena, Ibort, Marmo, Morandi, Geometry from dynamics, classical and quantum  
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The unmanifest world is simple and linear,  
it is the manifest world which is 'folded' and nonlinear.

G. Marmo



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- ◆ definitions are better than proofs
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