

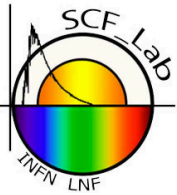
EXPERIMENTAL GRAVITY TESTS IN THE SOLAR SYSTEM

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Laboratori Nazionali di Frascati (LNF) dell'INFN, Frascati (Rome), Italy

VULCANO WORKSHOP 2016

Outline



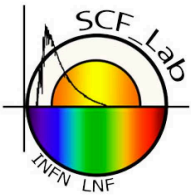
Introduction:

- Science with Satellite/Lunar Laser Ranging
- Tests of General Relativity

Data analysis:

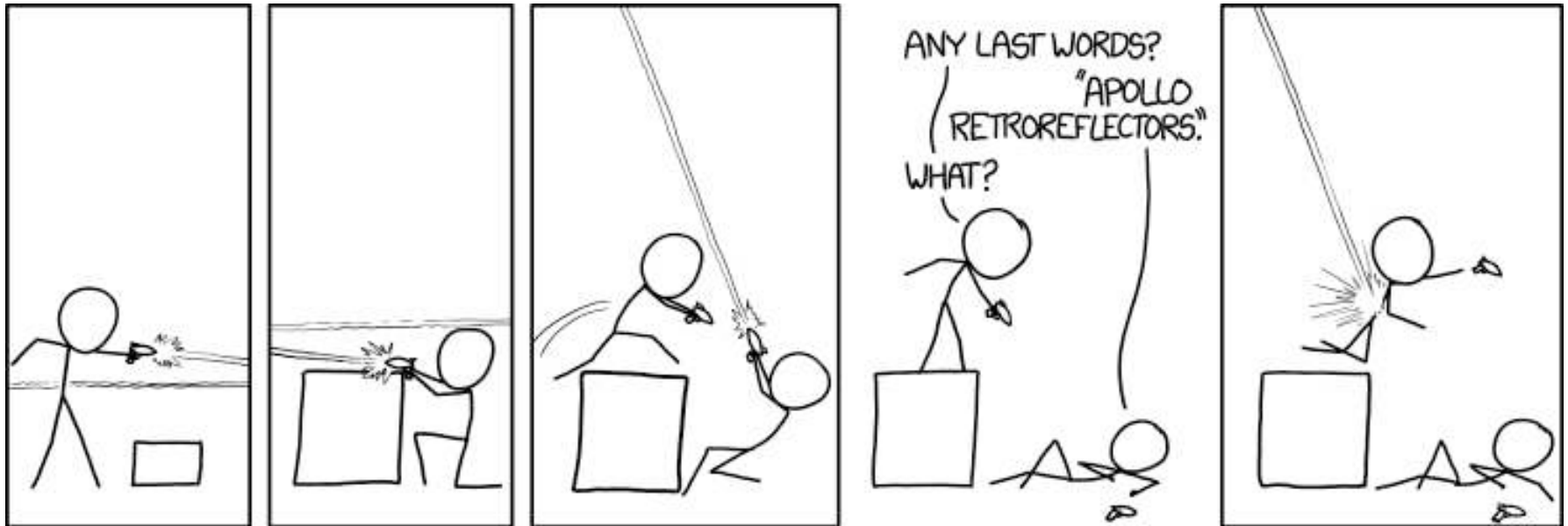
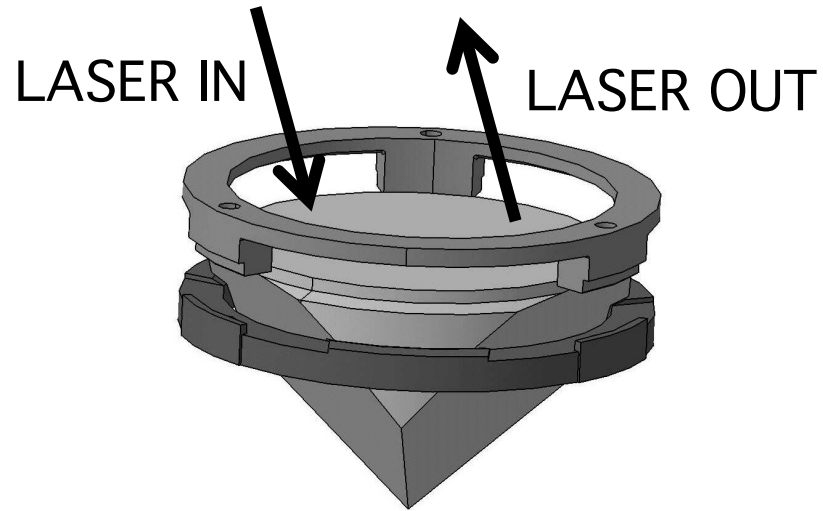
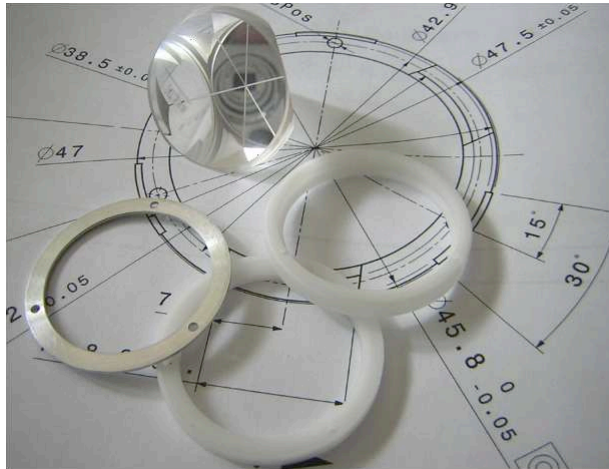
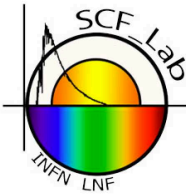
- The “Planetary Ephemeris Program (PEP)”
- Physics simulations (Moon/Mars)
- Results

Conclusions and prospects

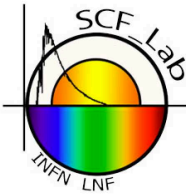


Introduction

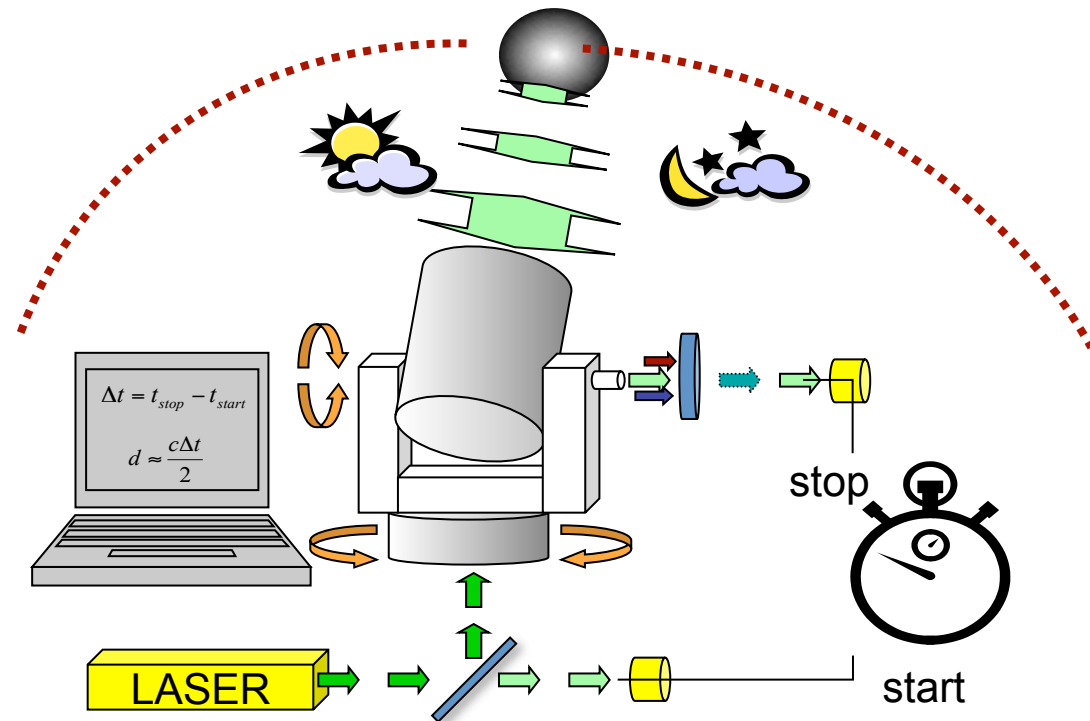
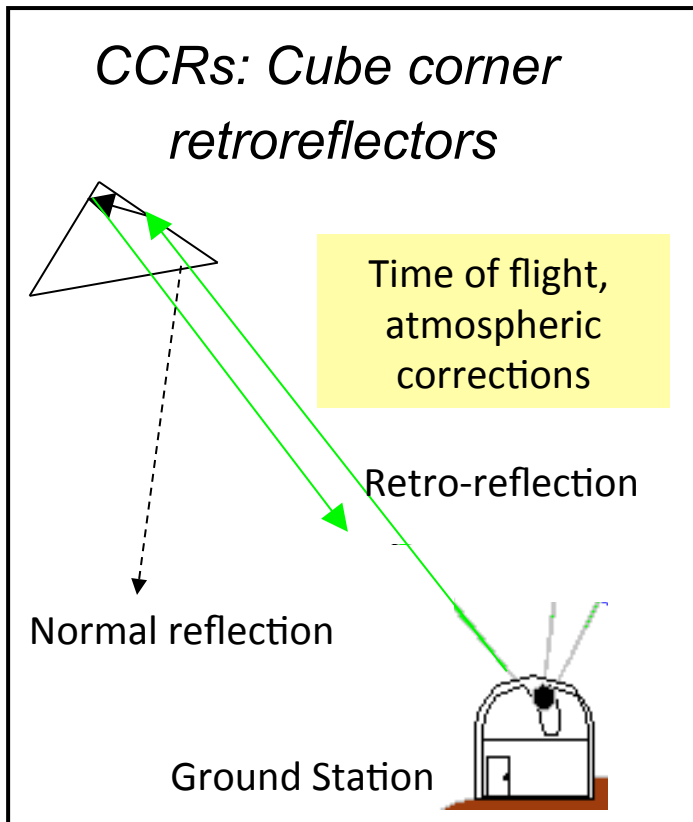
Corner Cube Retroreflector



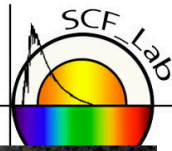
Satellite/Lunar Laser Ranging



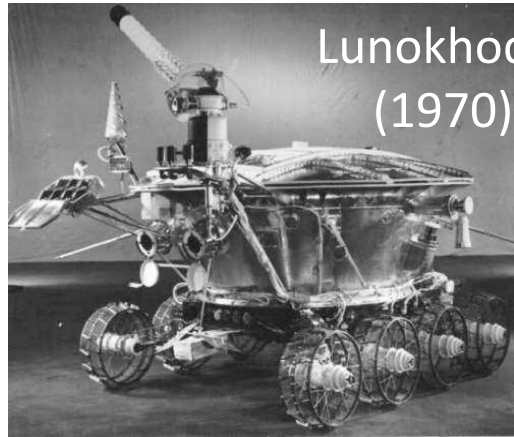
- An observatory on Earth transmits a short pulse towards a CCR array on Satellite/Moon.
- The CCR reflect the pulse back to the observatory.
- Time of flight measurement \rightarrow Distance
- Track Satellite/Moon orbit and obtain orbit parameter



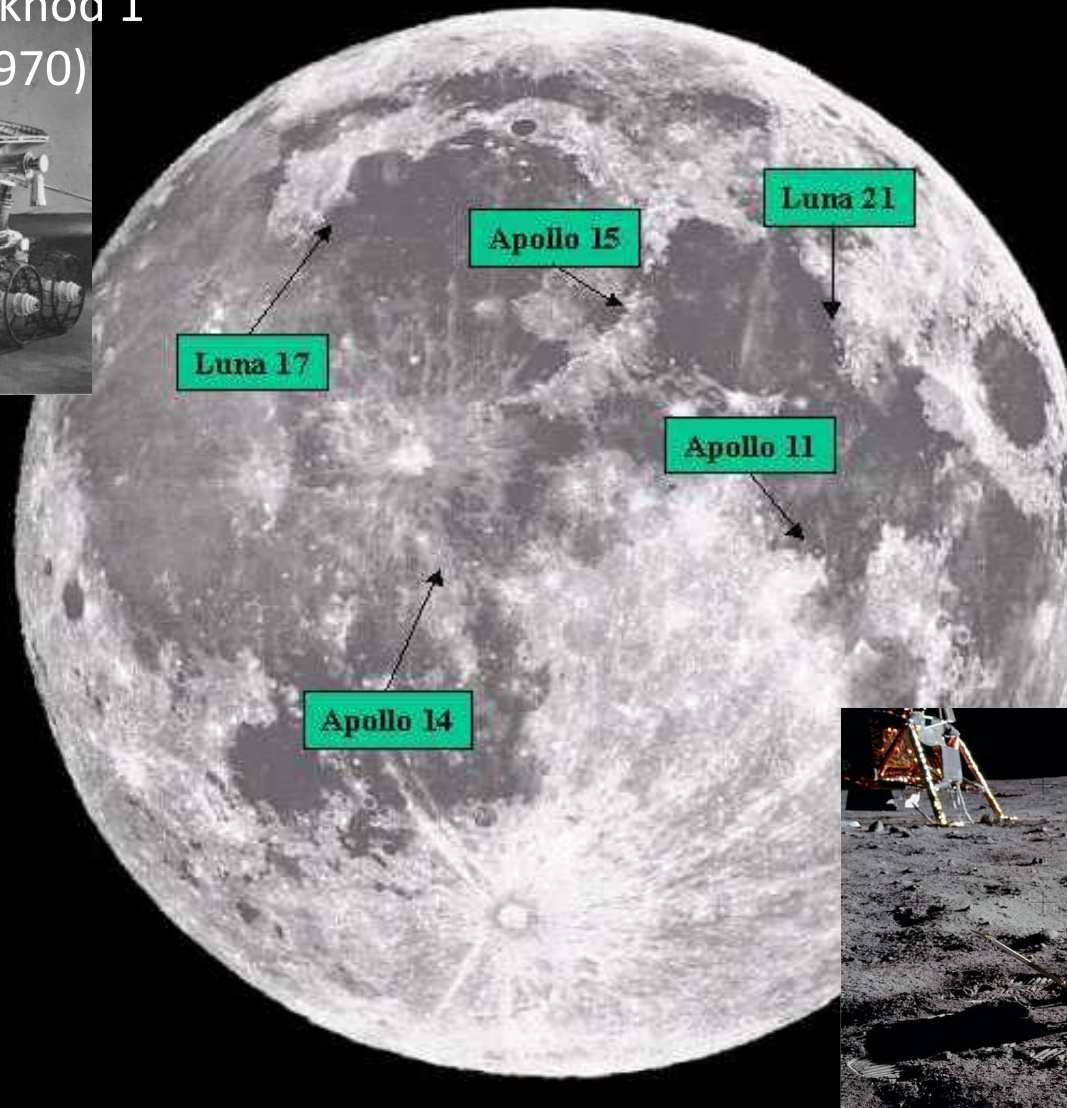
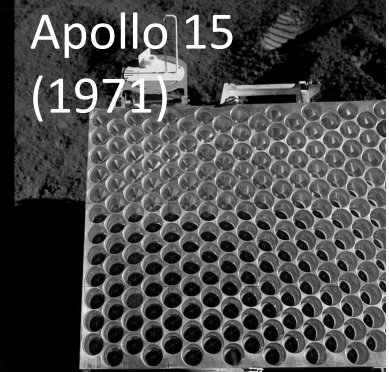
Lunar Laser Ranging



Lunokhod 1
(1970)



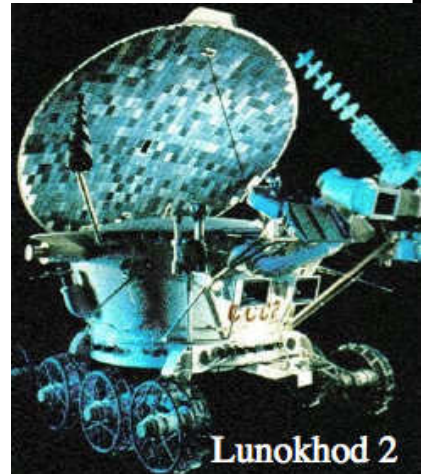
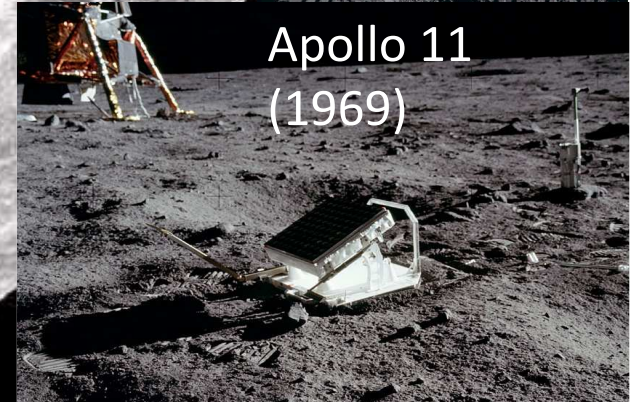
Apollo 15
(1971)



Apollo 14
(1971)

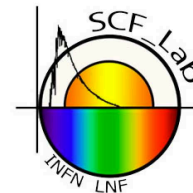


Apollo 11
(1969)



Lunokhod 2

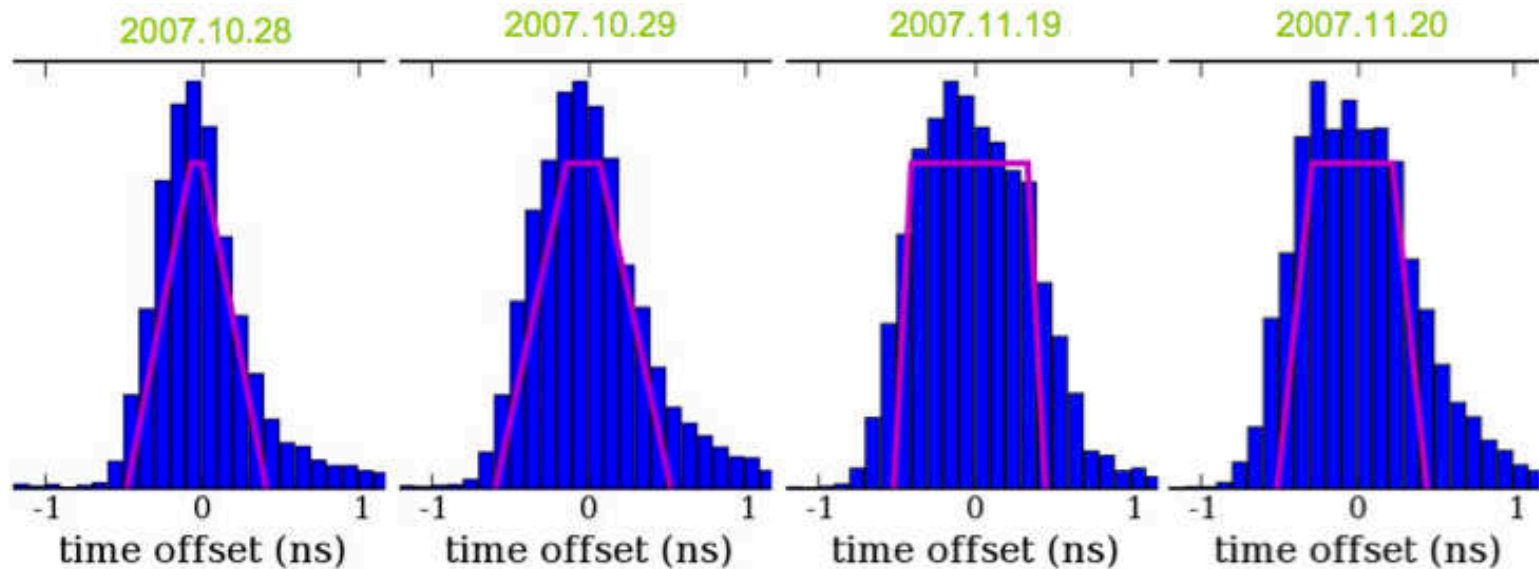
Tests of General Relativity



- Measurement of relativistic geodetic precession of lunar orbit, a true three-body effect ($\sim 3\text{m}$ / lunar orbit)
- Time variation of universal gravitational constant G
- Violation of Weak and Strong Equivalence Principle (WEP/SEP)
- Parametrized Post-Newtonian (PPN) parameter β : measures the non-linearity of gravity

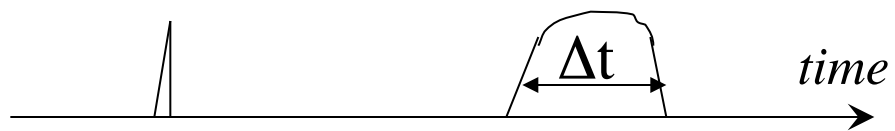
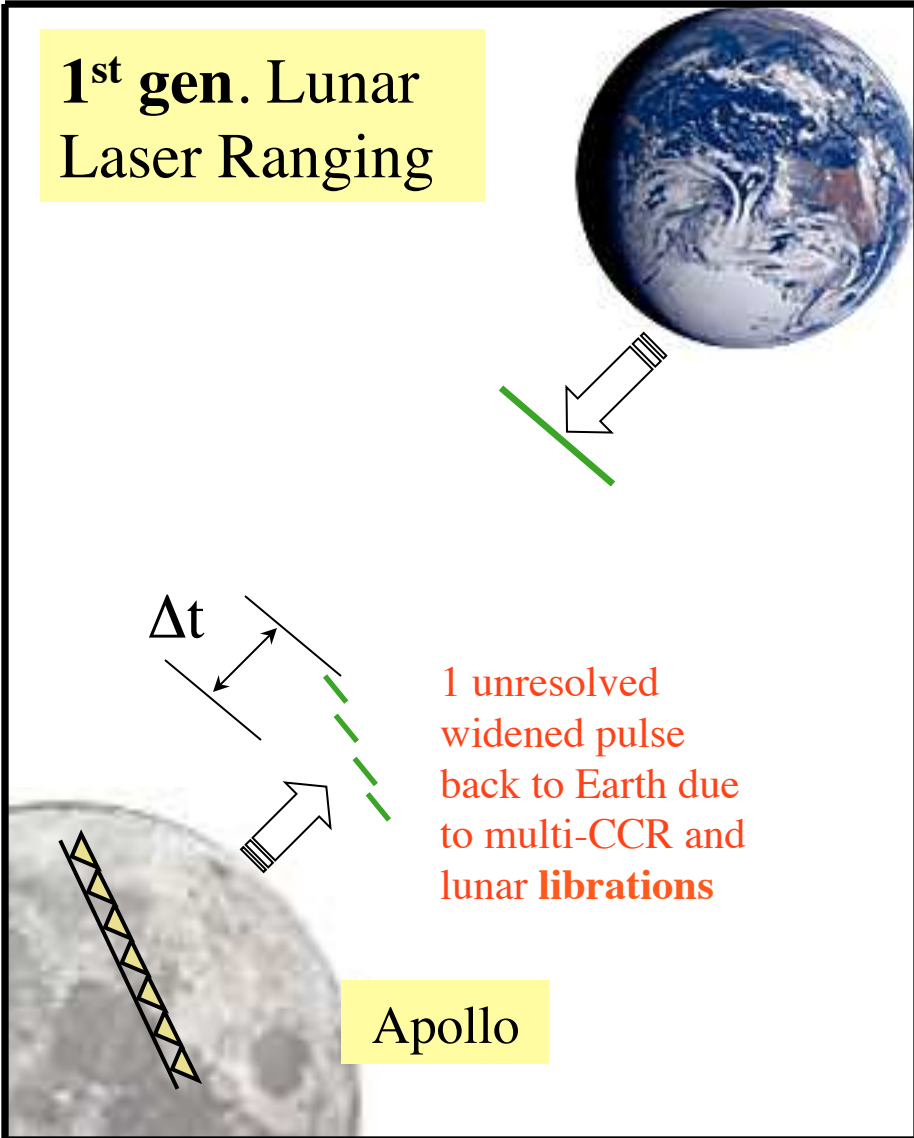
| Science measurement / Precision test of violation of General Relativity | Apollo/Lunokhod few cm accuracy* |
|---|--|
| Parameterized Post-Newtonian (PPN) β | $ \beta-1 < 1.1 \times 10^{-4}$ |
| Weak Equivalence Principle (WEP) | $ \Delta a/a < 1.4 \times 10^{-13}$ |
| Strong Equivalence Principle (SEP) | $ \eta < 4.4 \times 10^{-4}$ |
| Time Variation of the Gravitational Constant | $ \dot{G}/G < 9 \times 10^{-13} \text{yr}^{-1}$ |
| Inverse Square Law (ISL) | $ \alpha < 3 \times 10^{-11}$ |
| Geodetic Precession | $ \mathbf{K}_{\text{gp}} < 6.4 \times 10^{-3}$ |

Effect of multi-CCR array orientation due to lunar librations



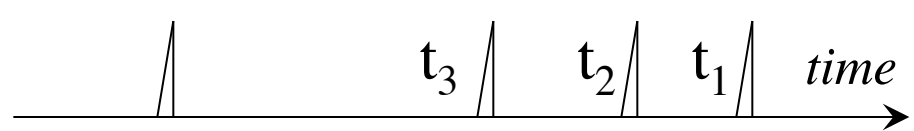
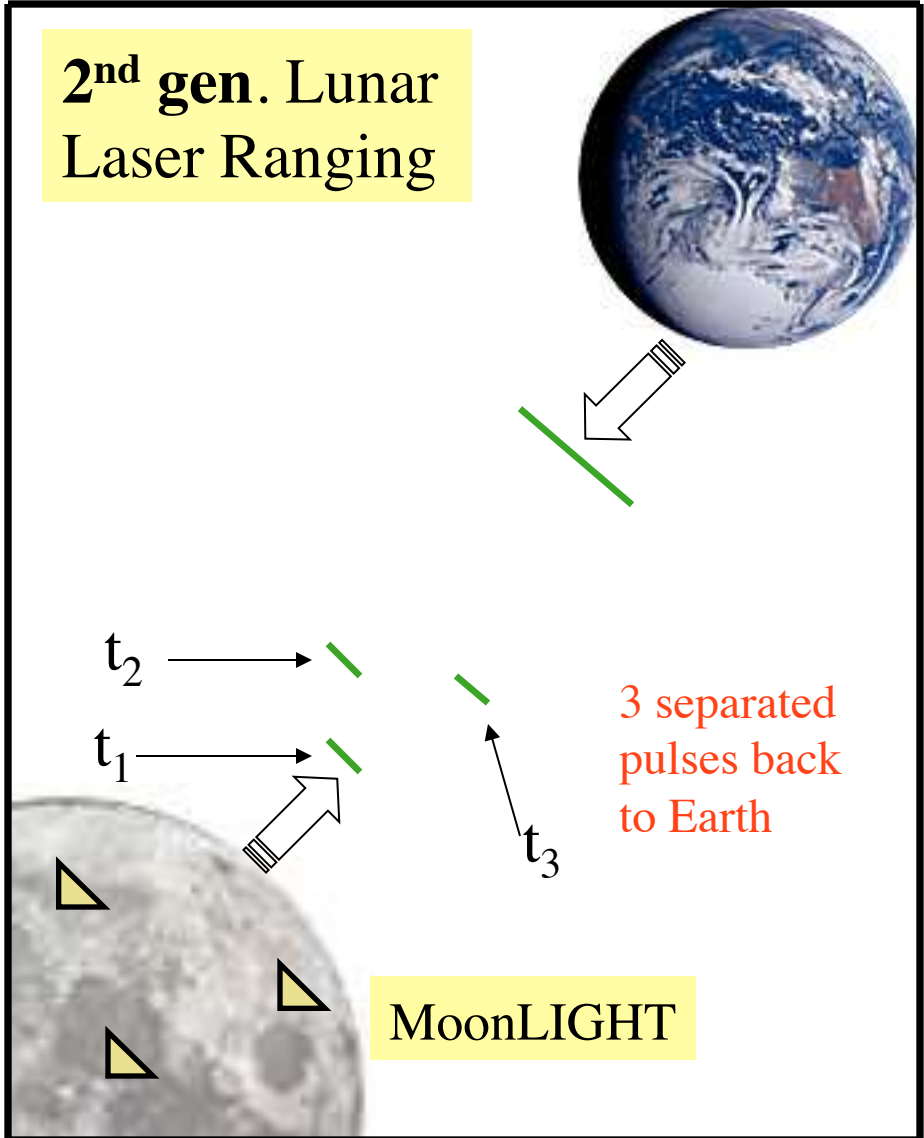
Due to this phenomenon the Apollo arrays are moved so that one corner of the array is more distant than the opposite corner by a few decimeters. Because of this libration tilt, the arrays broaden the LLR pulse back to Earth.

1st gen. Lunar Laser Ranging



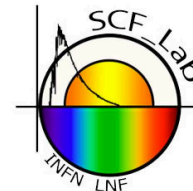
Short Pulse to Moon **Wide Pulse to Earth**

2nd gen. Lunar Laser Ranging



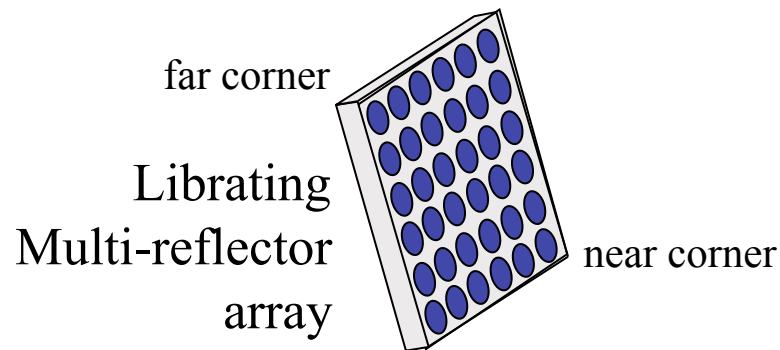
Pulse to Moon **Pulses to Earth**

MoonLIGHT-2 reflector



Libration rotations up to $\sim 8^\circ$
(effect of e and i of Moon orbit).
Current accuracy of ~ 2 cm

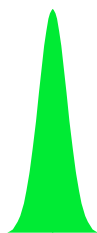
Laser Pulse



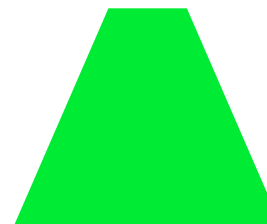
Past
(Apollo)

fat laser pulse:
return uncertainty
dominated by pulse

Present
(APOLLO)

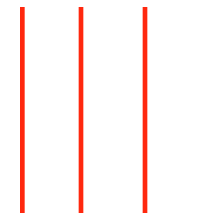


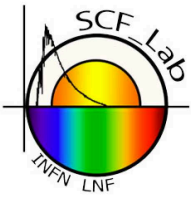
medium laser pulse:
return uncertainty
dominated by array libration



Future
(MoonLIGHT)

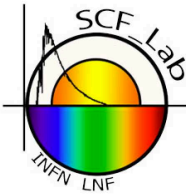
short laser pulse:
return uncertainty
dominated by pulse
Shorter pulses can be done





Data Analysis

Planetary Ephemeris Program

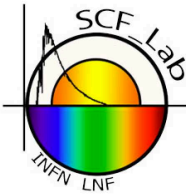


In order to analyze LLR data we used the PEP software, developed by the CfA, by I. Shapiro et al. starting from 1970s.

The model parameter estimates are refined by minimizing the residual differences, in a weighted least-squares sense, between observations (O) and model predictions (C, stands for "Computation"), O-C.

"Observed" is the measured round-trip time of flight.
"Computed" is modeled by the PEP software.

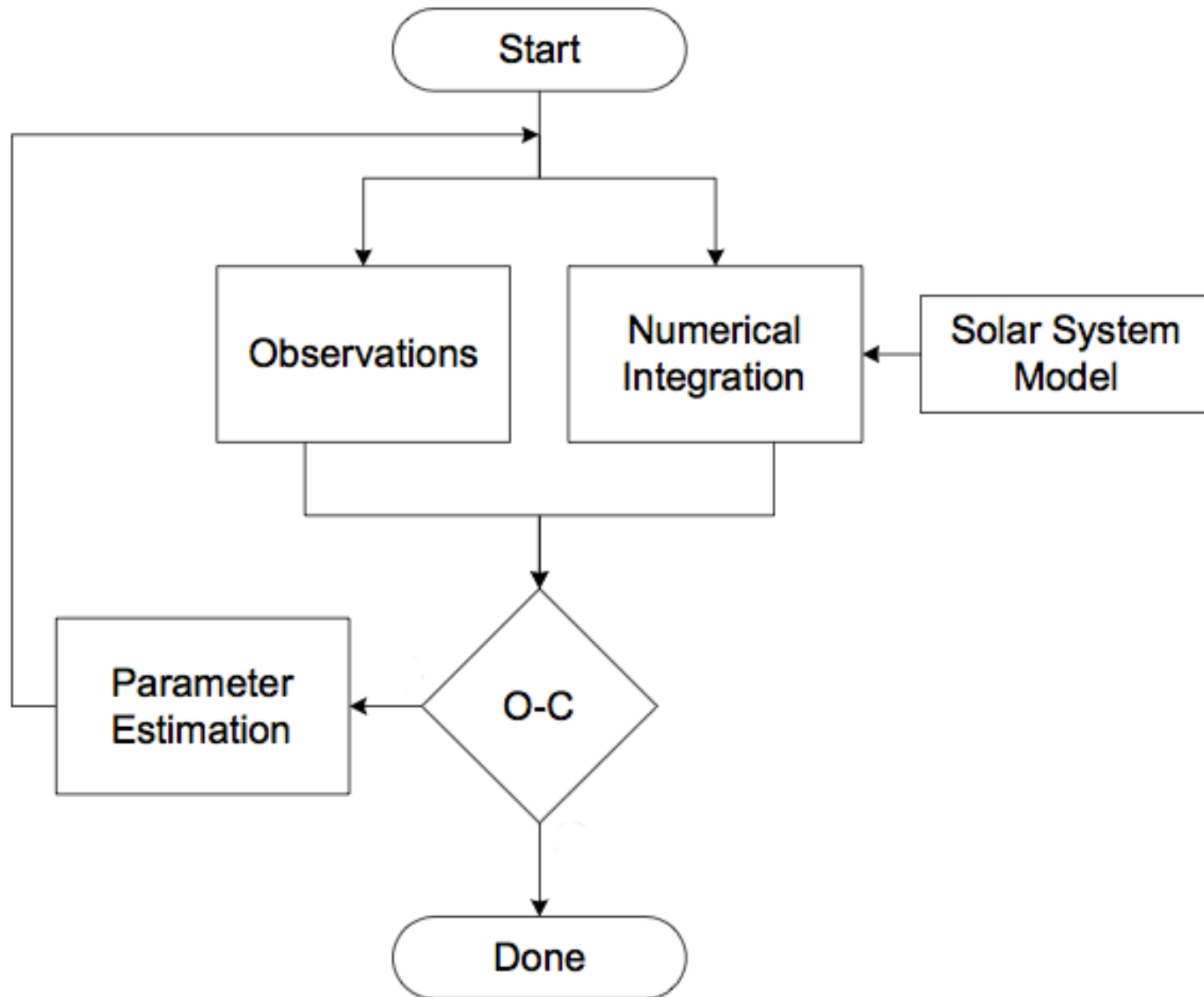
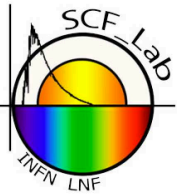
Generating Predictions



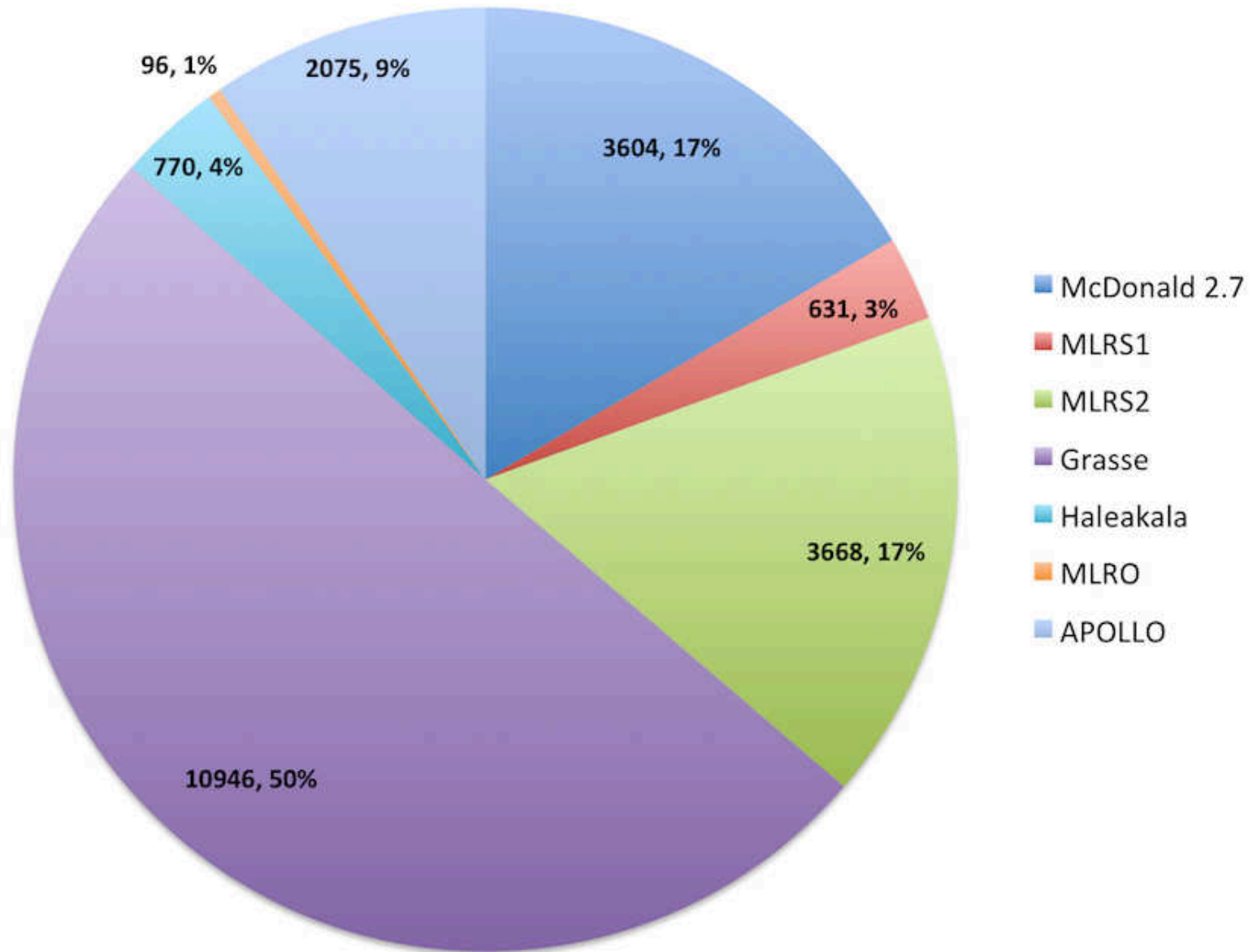
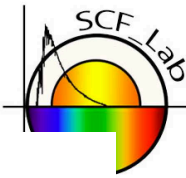
How does one can generate an ephemeris?

- Must obtain accurate observations;
- Develop a comprehensive solar system model that we then integrate numerically (including complications, such as planetary rotation dynamics and lunar motion);
- Simultaneously fit all of these model parameters to the available observations (from asteroids and interplanetary probes, etc.).

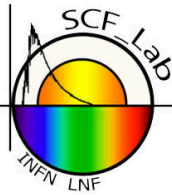
Generating Predictions



Data Analysis LLR Normal Points



Normal Point Data



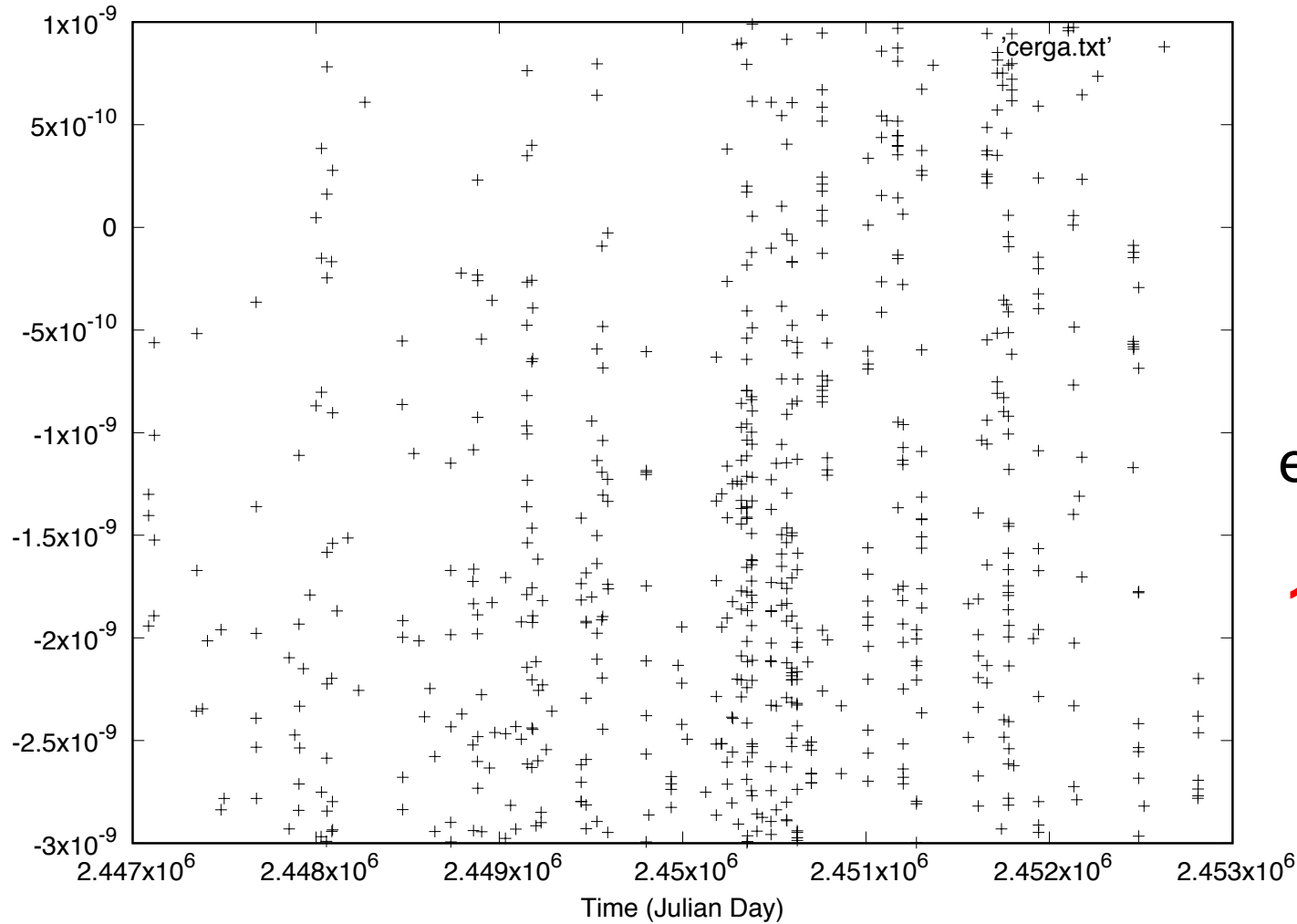
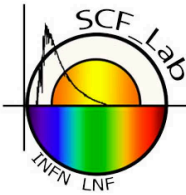
512008 330123950000000026170710379889370610207 317312B 72439 -5134 5320A 250A

The fields are:

| field | width | represents | this example | notes |
|----------------|-------|--|-------------------|---------------------------------|
| 51 | 2 | ? | 51 | |
| 2008 | 4 | year | 2008 | time is UTC launch time |
| 3 | 2 | Month | March | |
| 30 | 2 | Day | 30 th | |
| 12 | 2 | Hour | 12 h | |
| 39 | 2 | Monute | 39 m | |
| 500000000 | 9 | 10 ⁻⁷ seconds | 50.0000000 s | |
| 26170710379889 | 14 | round trip time, 10 ⁻¹³ seconds | 2.6170710379889 s | measured round trip |
| 3 | 1 | reflector number | Apollo 15 (#3) | 0=A11; 1=L1; 2=A14; 3=A15; 4=L2 |
| 70610 | 5 | station ID | Apache Point | |
| 207 | 3 | # photons in NP | 207 photons | saturates at 999 |
| 317 | 6 | uncert in 0.1 ps | 31.7 ps | |
| 312 | 3 | 10×SNR | 31.2 | saturates at 99.9 |
| B | 1 | data quality grade | B | A, B, C, D |
| 72439 | 6 | pressure, 0.01 mbar | 724.39 mbar | |
| -51 | 4 | temperature, 0.1°C | -5.1°C | |
| 34 | 2 | % relative humidity | 34% | |
| 5320 | 5 | wavelength, angstroms | 5320 angstrom | |
| A | 1 | ? | A | |
| 250 | 4 | NP duration, sec | 250 sec | |
| A | 1 | ? | A | |

A normal point contains several information e.g. date of observation, atmospheric conditions, as well as time of flight, data quality and CCR arrays

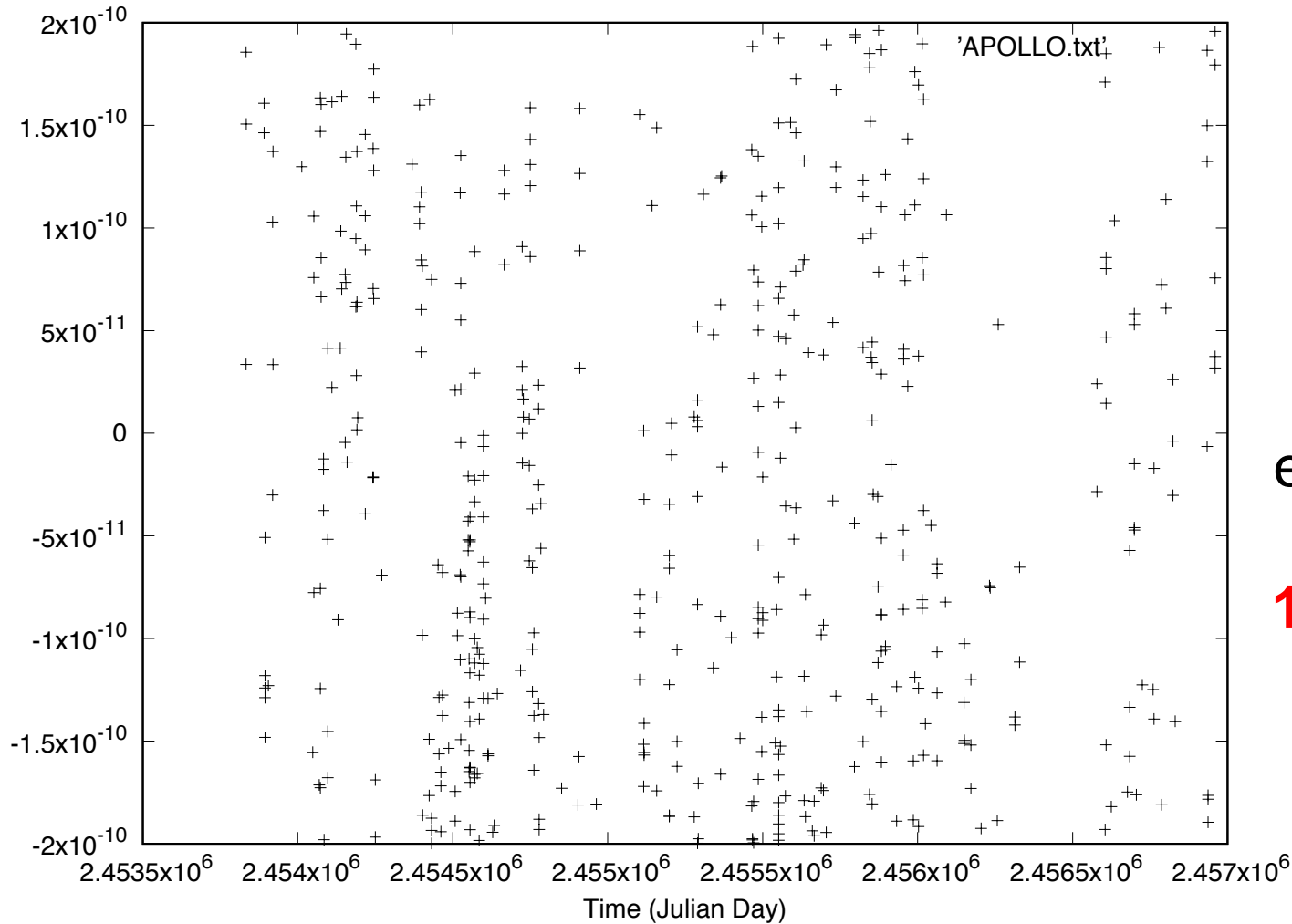
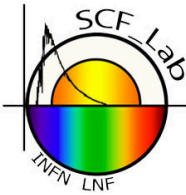
O-C residual analysis with PEP



CERGA
on
existing CCRs

10^{-9} seconds

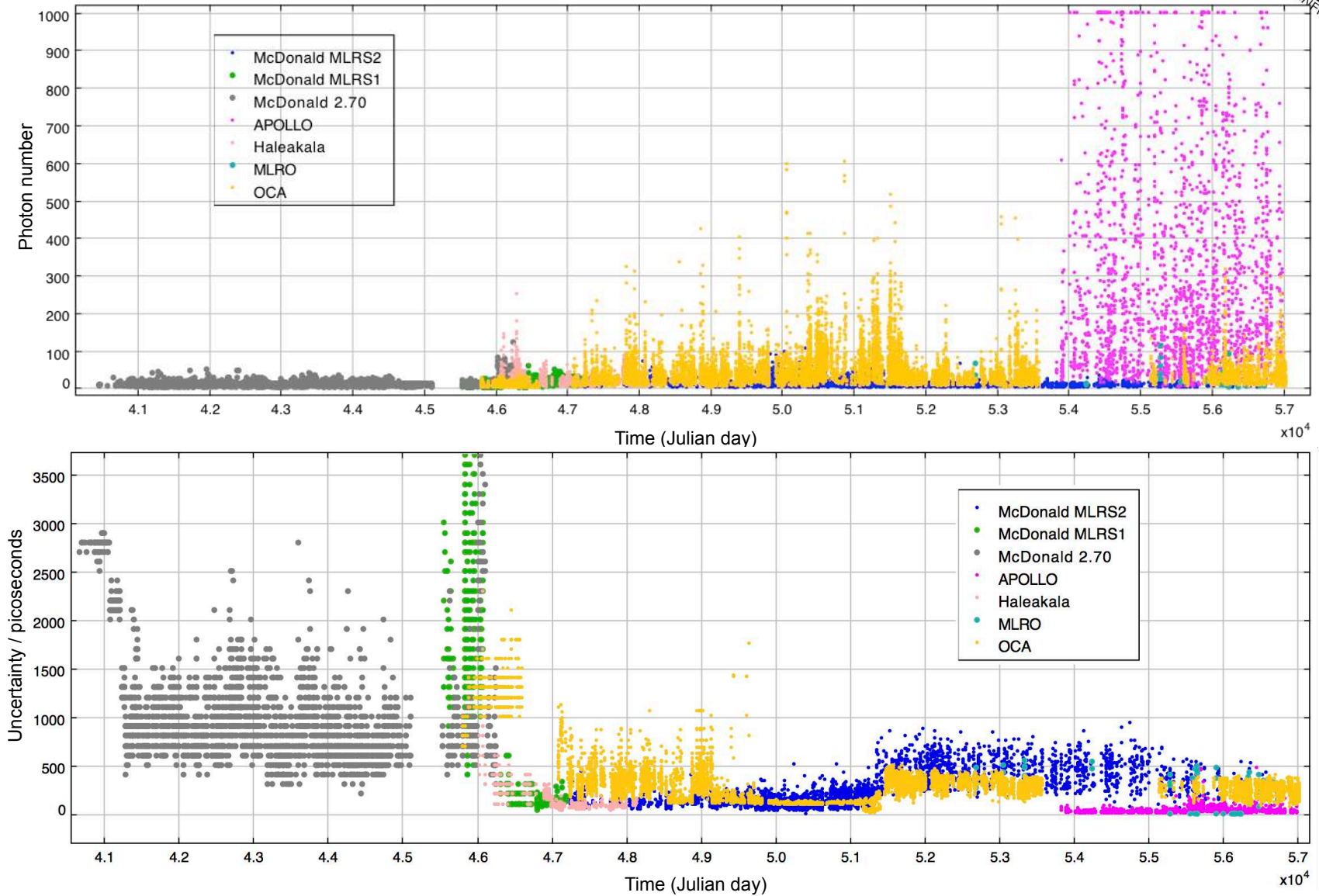
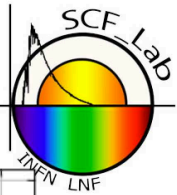
O-C residual analysis with PEP



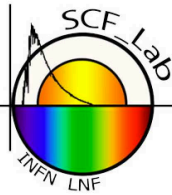
APOLLO
on
existing CCRs

10^{-10} seconds

O-C residual analysis with PEP



LLR tests of General Relativity (GR)



Due to librations a major improvement in LLR efficiency and precision and, therefore, on GR tests can and must be obtained only by going from arrays to single retroreflectors.

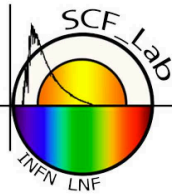
It is a pre-requisite (condicio sine qua non)

Efficiency (# returns to make a normal point) of single, large reflector: few thousands times larger than reflector arrays

State of the art measurements

| Precision test of violation of GR | Apollo/Lunokhod JPL | Apollo/Lunokhod PEP |
|--|--|--|
| Geodetic Precession | $ K_{gp} < 6.4 \times 10^{-3}$ | $ K_{gp} < 7.9 \times 10^{-3}$ |
| Time Variation of the Gravitational Constant | $ \dot{G}/G < 9 \times 10^{-13} \text{yr}^{-1}$ | $ \dot{G}/G < 9.8 \times 10^{-13} \text{yr}^{-1}$ |
| Parametrized Post-Newtonian, β | $ \beta - 1 < 1.1 \times 10^{-4}$ | $ \beta - 1 < 4.0 \times 10^{-4}$ |

Simulated observations



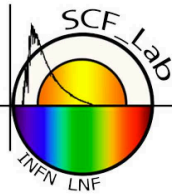
Simulation to optimize MoonLIGHT for the first deploying (2018) using all real LLR data taken until now from Apollo and Lunokhod

| CCR Array | Data Type | Time Span | Sites | Stations | Accuracy |
|---|-----------|--------------|-------------------------|----------|----------|
| Apollo + Lunokhod | Dummy | 2015 2030 | 11-14-15 Lunokhod1-2 | APOLLO | 0,5 cm |
| | | | | CERGA | 1,0 cm |
| | | | | MLRS | |
| | | | | MLRO | |
| MoonLIGHT with and without Sun Shade | Dummy | 2018 2030 | 80°N, 0°W | APOLLO | 0,1 cm |
| | | | 80°S, 0°E | CERGA | 0,2 cm |
| | | | 0°N, 80°E | MLRS | |
| | | | 0°N, 80°W | MLRO | |

➤ GR tests expected improvement:

- 4 MoonLIGHT-2 (starting from 2018, one per year) plus any other Apollo/Lunokhod
- 15 years of simulations starting from 2015.
- Accuracy simulation of Optimal design as “STD”
- 3 different accuracy value set: STD, double STD and half of STD.

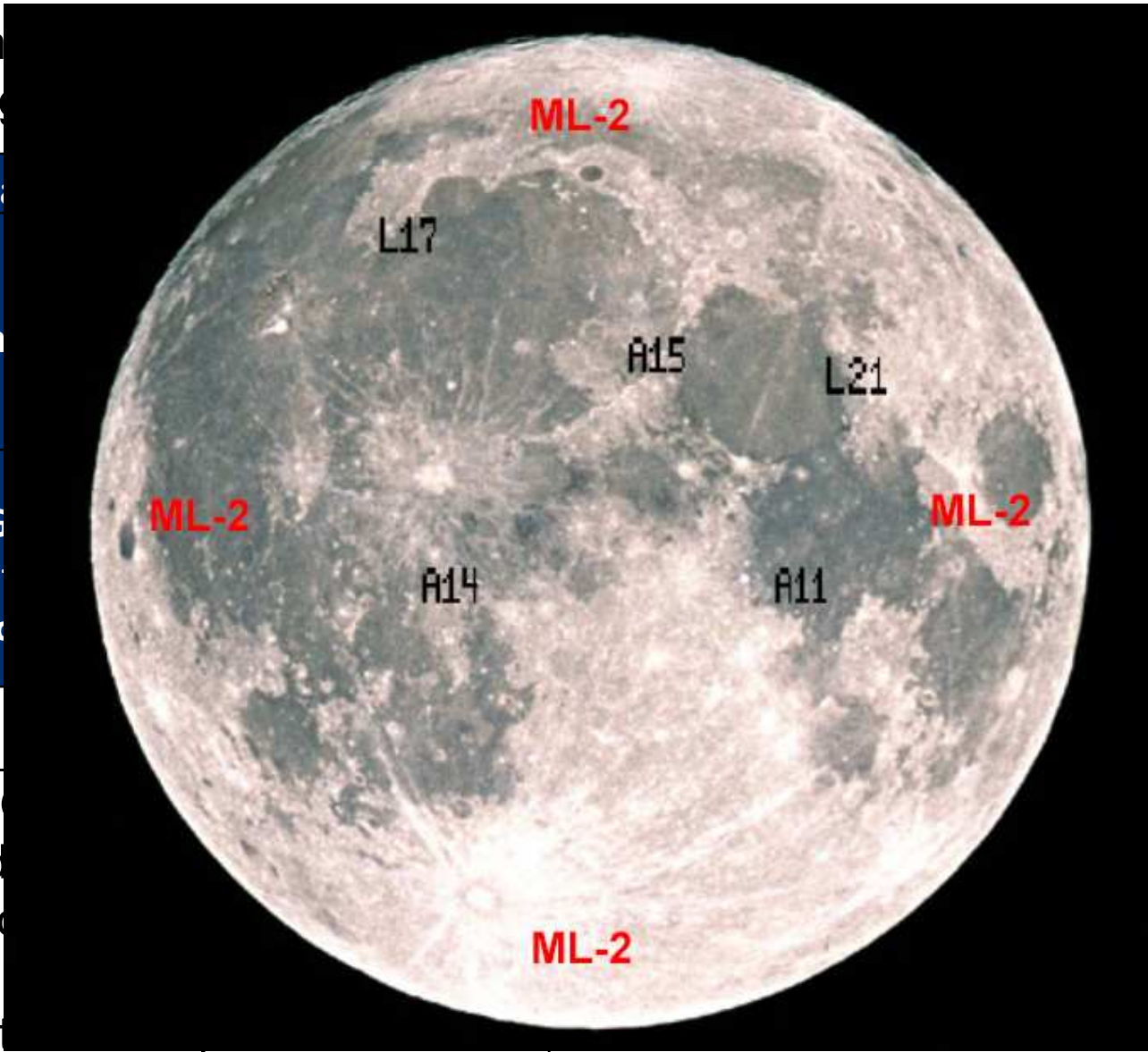
Simulated observations



Sim
using

2018)
Lunokhod

| |
|-----------------------------------|
| CCR Arr |
| Apollo + Lun |
| MoonLIG with and wi Sun Sha |

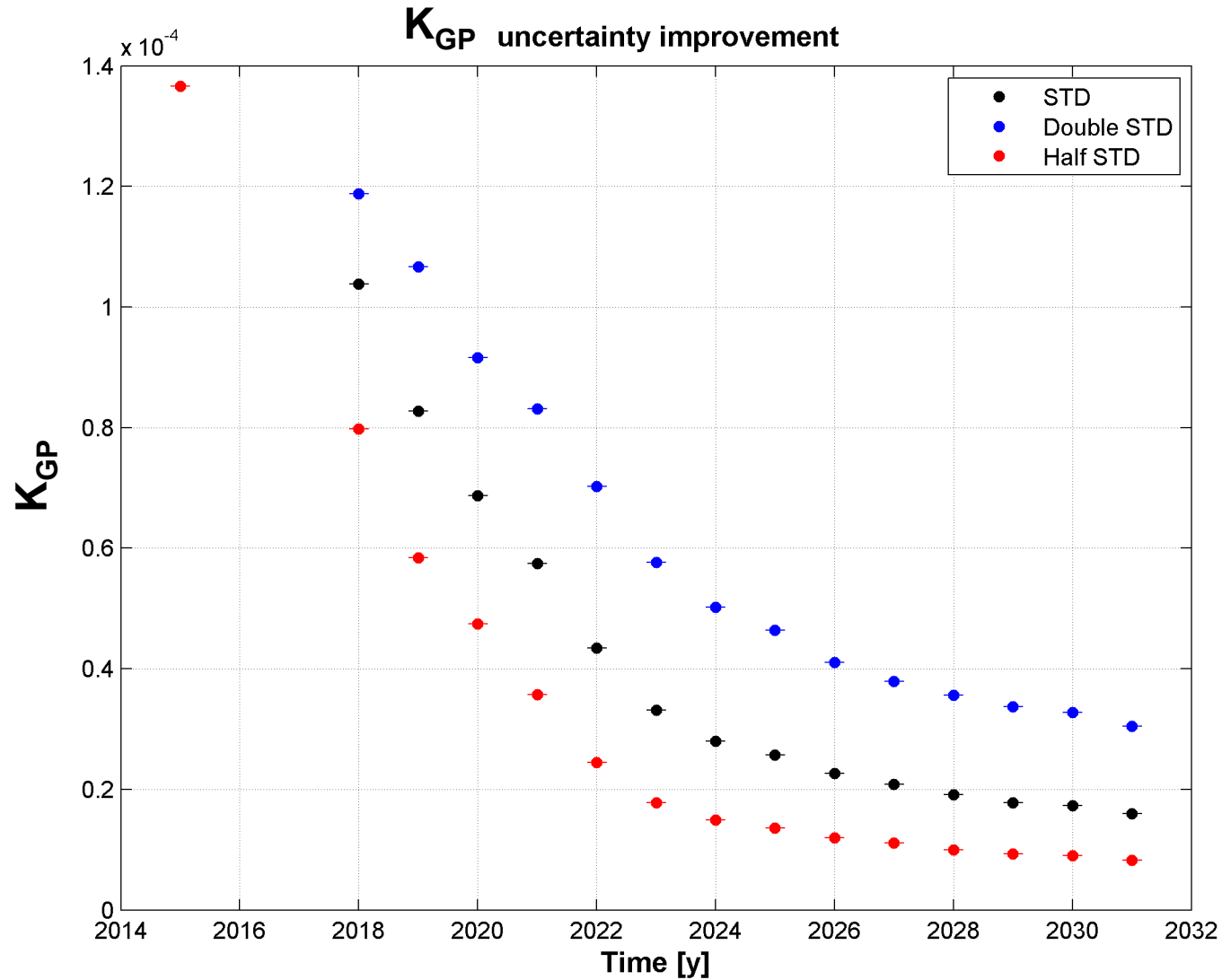
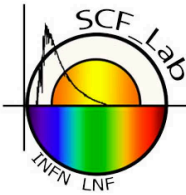


| Accuracy |
|----------|
| 0,5 cm |
| 1,0 cm |
| 0,1 cm |
| 0,2 cm |

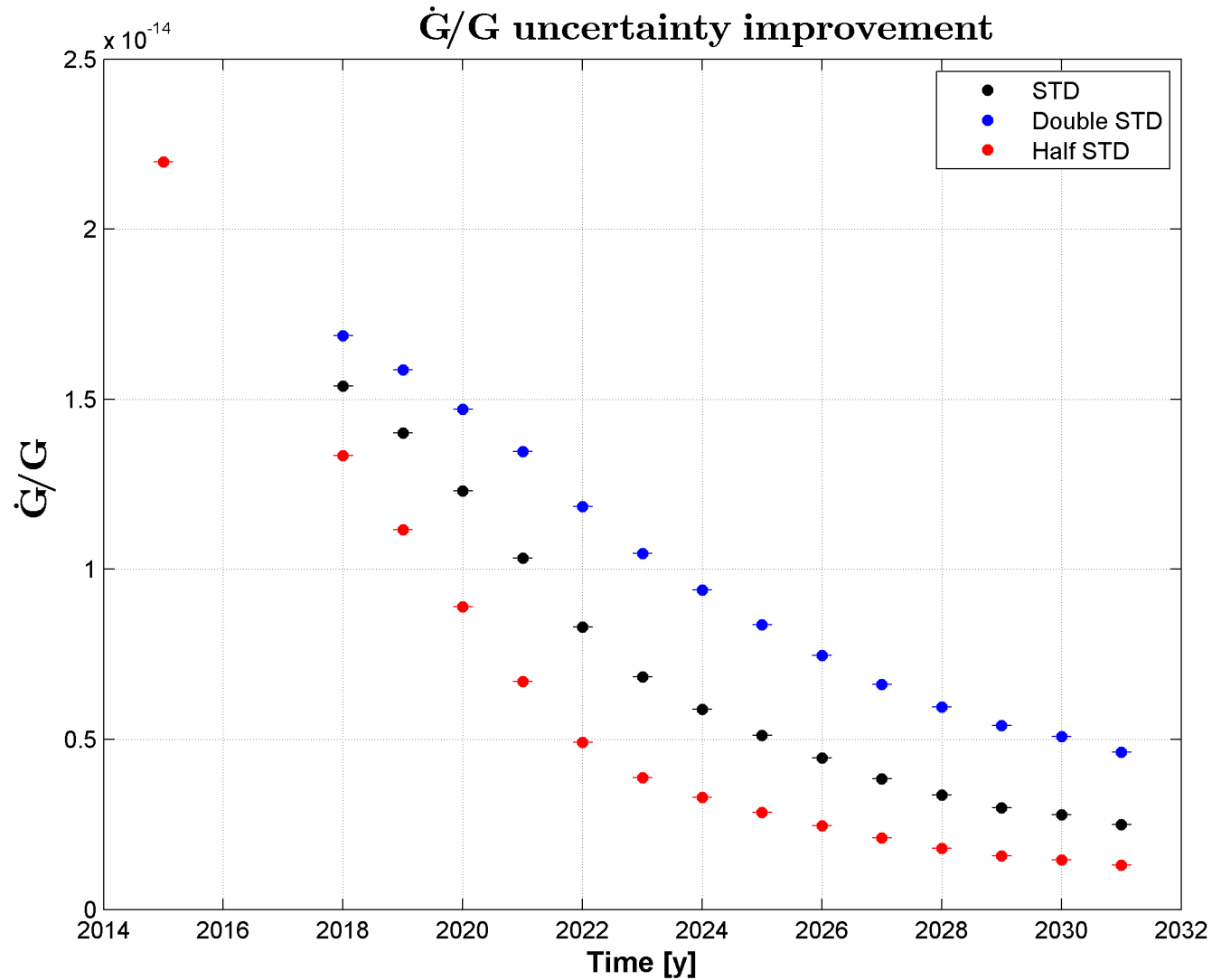
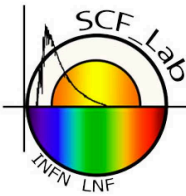
- **GR tests**
- 4 MoonLI
- Lunokhod
- 15 years of
- Accuracy
- 3 different

er Apollo/

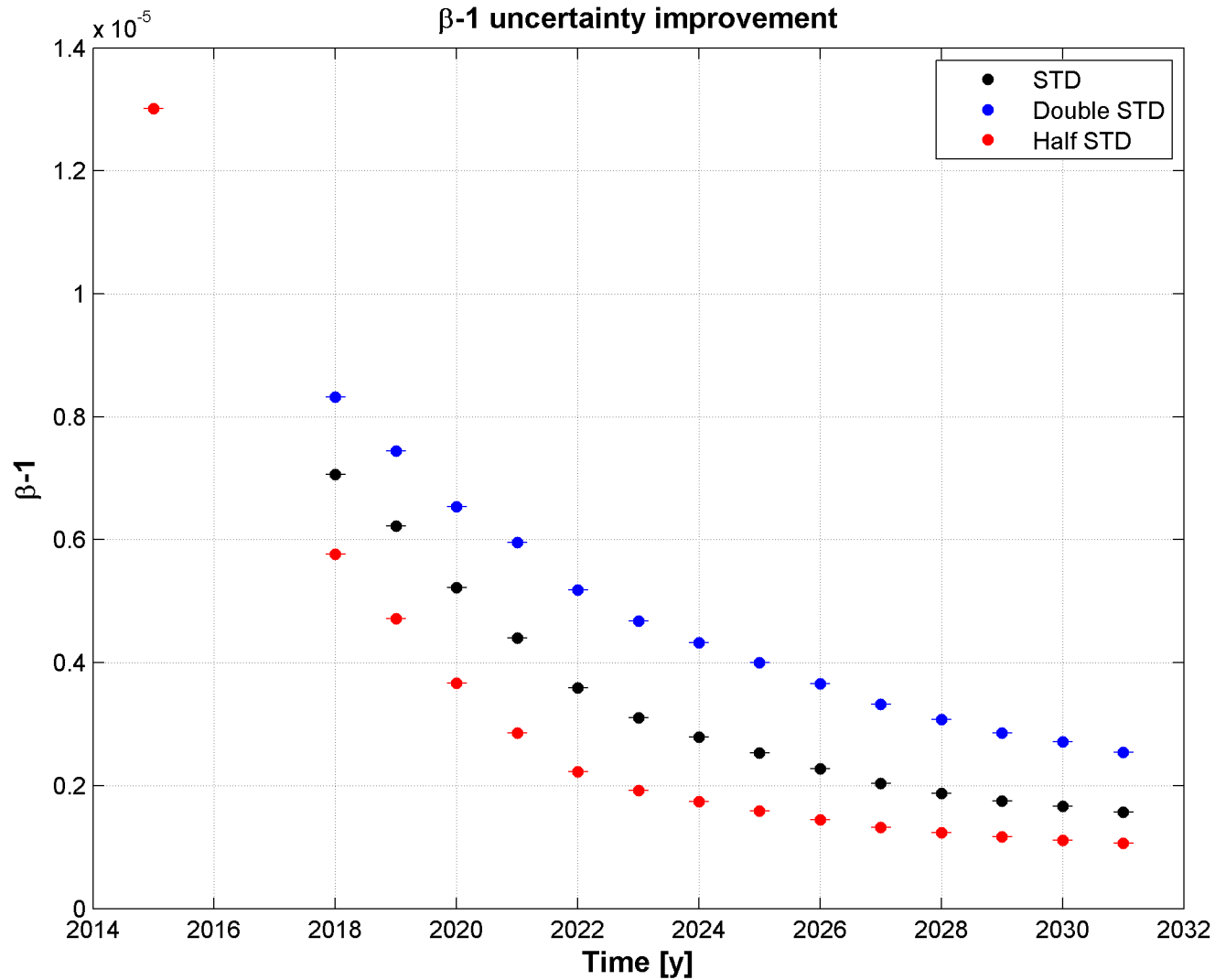
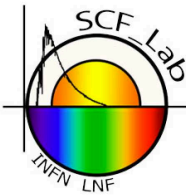
GR test improvement: Simulated observations



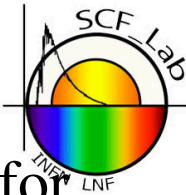
GR test improvement: Simulated observations



GR test improvement: Simulated observations



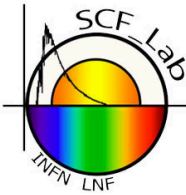
Results



- We, in Italy, developed new reflectors, and we have agreements for new lunar missions to deploy them
- Using simulation by PEP *as-is* we will improve the test of General Relativity by a factor ~ 10 with new reflectors and new missions (not including improved stations/software)
 - *Lots of new data from new reflectors/missions WILL HELP improve PEP*
 - *Improvement of PEP software (better modeling of effect included in PEP, addition of effects not yet implemented) will follow the improvement due to new reflectors.*

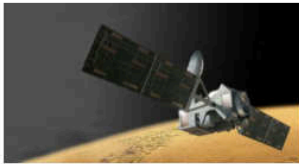
| Precision test of violation of GR | Improvement STD | Improvement H-STD |
|--|--------------------|----------------------|
| Time Variation of the Gravitational Constant | $\times 8.8$ | $\times 16.9$ |
| Geodetic Precession | $\times 8.6$ | $\times 16.6$ |
| Parametrized Post-Newtonian, β | $\times 8.2$ | $\times 12.3$ |

Fly me to the Moon...and beyond



EXOMARS, A BORDO NUOVO STRUMENTO ITALIANO TARGATO ASI E INFN

Pubblicato Mercoledì, 28 Ottobre 2015



In attesa di vedere il primo uomo saltellare sulla polvere di Marte, si prepara a sbarcare sul Pianeta Rosso, nel 2016, con la missione ExoMars dell'European Space Agency (ESA). Una missione in cui l'Italia si arricchisce ulteriormente in questi giorni. Sale, infatti, a bordo del nuovo strumento INRRI (INstrument for landing-Roving laser Retroreflector Investigations) Spaziale Italiana (ASI) e dell'Istituto Nazionale di Fisica Nucleare (INFN) la supervisione scientifica di Simone Dell'Agnello, fisico dell'Istituto Nazionale di Fisica Nucleare (INFN) di Frascati (LNF) dell'INFN.

Dopo aver superato con successo tutti i test previsti, lo strumento è stato consegnato a tempo di record sul modulo di discesa marziano ExoMars EDM (Entry, descent and landing Demonstrator Module) battezzato con il nome dell'astronomo italiano Giovanni Schiaparelli, che disegnò la prima mappa del Pianeta Rosso. INRRI diventerà un punto di riferimento sulla superficie marziana e il primo oltre la Luna. Dovrebbe inoltre essere l'antesignano di una serie di futuri Lander o Rover, che assieme formeranno un Mars Geo/physics Network (MGN): una rete di punti di riferimento geodesici di Marte e test di Relatività Generale. A lungo termine, MGN potrebbe diventare una rete di punti di riferimento simile a quella dei retroriflettori laser delle missioni Apollo e Lunokhod sulla Luna.

La missione ExoMars è stata ideata per indagare eventuali tracce di vita, passata o presente, su Marte. Il modulo di discesa sarà lanciato nel mese di marzo del 2016 e, dopo un viaggio di circa 7 mesi, si poserà sulla superficie del Pianeta Rosso.

ASI - AGENZIA SPAZIALE ITALIANA NEWS

Home > News > New Italian instrument on board ExoMars

New Italian instrument on board ExoMars
The INRRI (INstrument for landing-Roving laser Retroreflector Investigations) laser micro-reflector was developed by ASI and INFN

28 October 2015
While waiting to see the first man walk on the oxidised powder surface of Mars, Europe is preparing to land on the red planet in 2016 with the robotic ExoMars mission by the European Space Agency (ESA).

A mission in which Italy is playing a key role that will be becoming increasingly important in the next few days, as the INRRI (INstrument for landing-Roving laser Retroreflector Investigations) laser micro-reflector developed by the Italian Space Agency (ASI) together with the National Institute of Nuclear Physics (INFN) with scientific direction by Simone Dell'Agnello, physicist from the INFN's National Laboratories of Frascati (LNF), is loaded on board.

After passing all the necessary tests, the instrument was delivered in record time and has just been installed on the Martian descent module ExoMars EDM (Entry, descent and landing Demonstrator Module) named Schiaparelli after Italian astronomer Giovanni Schiaparelli, who drew the first map of the red planet.

INRRI will be the first passive laser reflector on the surface of Mars and the first to go further than the moon. It should also be the first of a series of micro-reflectors carried on board future landers or rovers, that will go together to form a Mars Geophysical Network (MGN): a network of reference points for taking geodesic measurements and conducting general relativity tests on Mars. In the long term, MGN could become a precision positioning network similar to that created using laser retro-reflectors on the Apollo and Lunokhod moon missions.

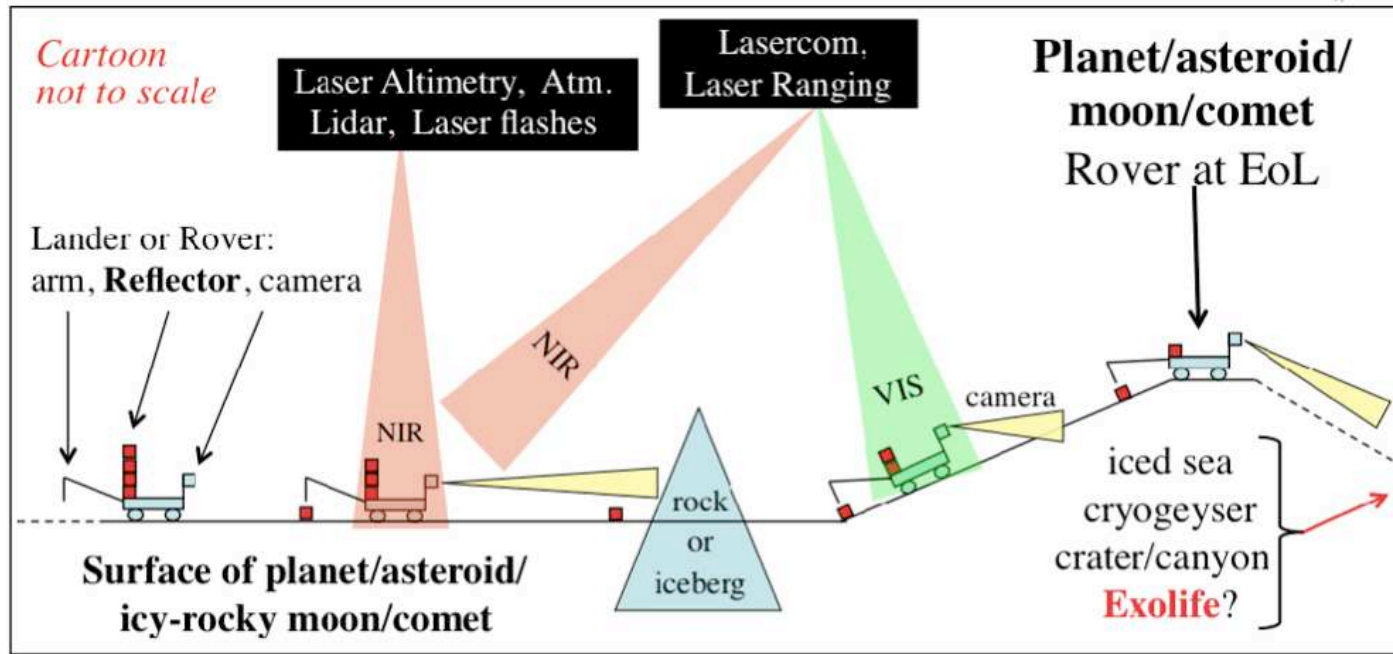
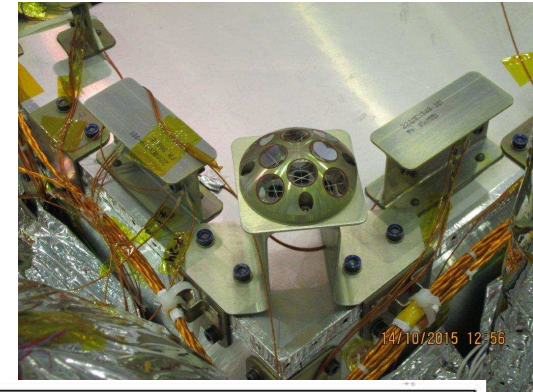
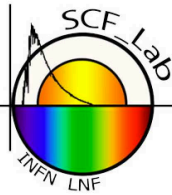
The ExoMars mission was designed to investigate possible traces of life, past or present, on Mars. The Schiaparelli module will be launched in March 2016, and will land on the surface of the red planet after a journey of around seven months. Scientific analyses will therefore begin with the DRFAMS (Dust characterization Risk assessment and Environment Analyser on the Martian Surface) weather station.

Half a century of Italian space missions.
The Space history in Italy since 1964.

ASI Events
Scientific and institutional conferences, workshops, exhibitions and outreach events.

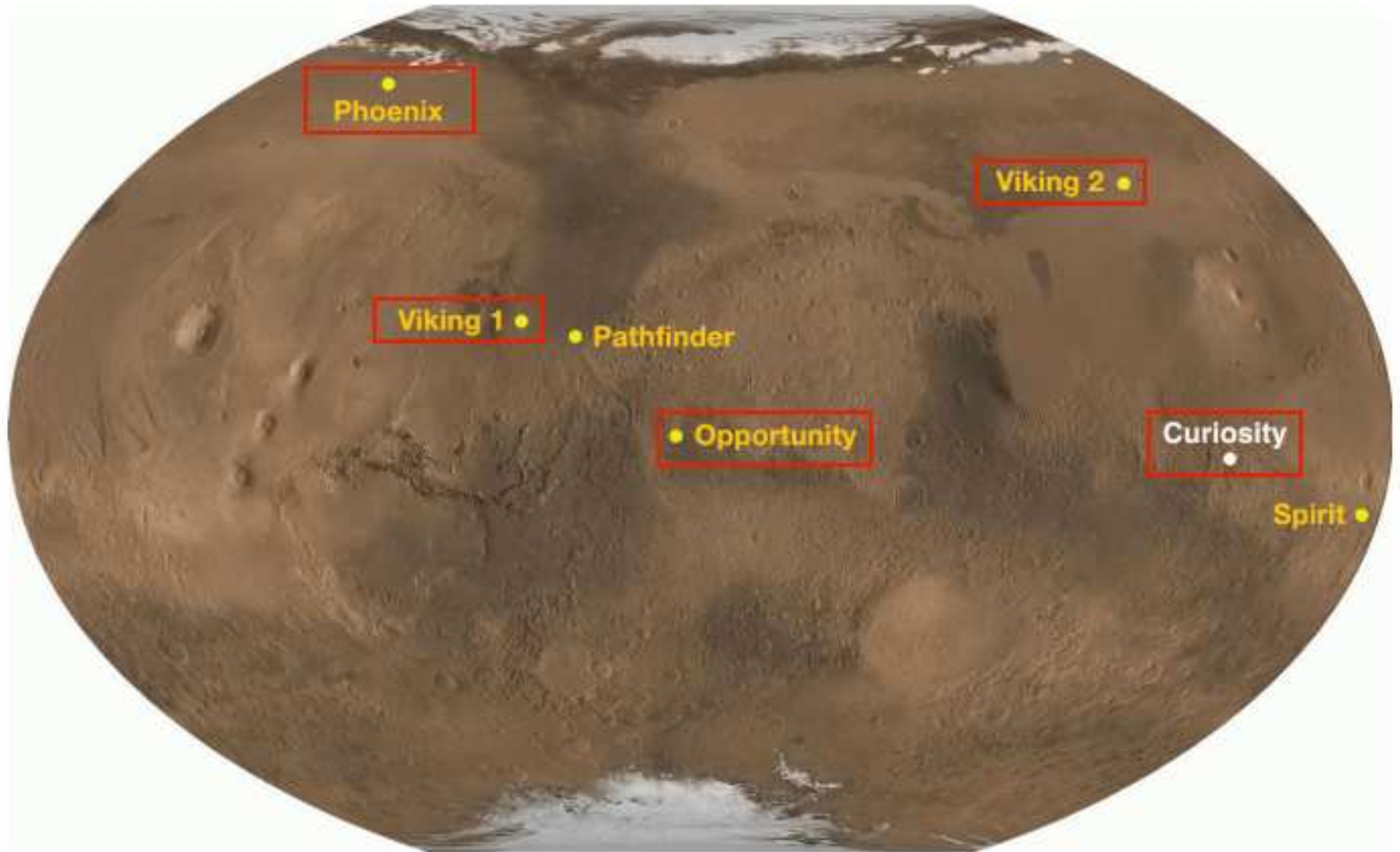
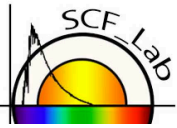
"Distretto Virtuale" Portal
Web interface open for business, science community and institutions The "Distretto Virtuale" is an innovative

INRRI the first laser retroreflector on Mars

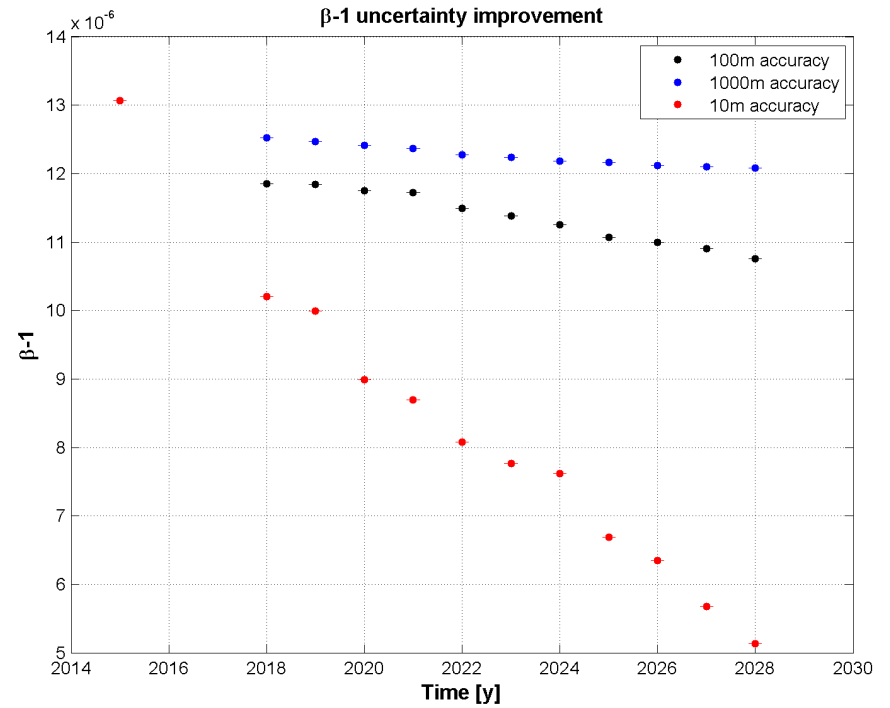
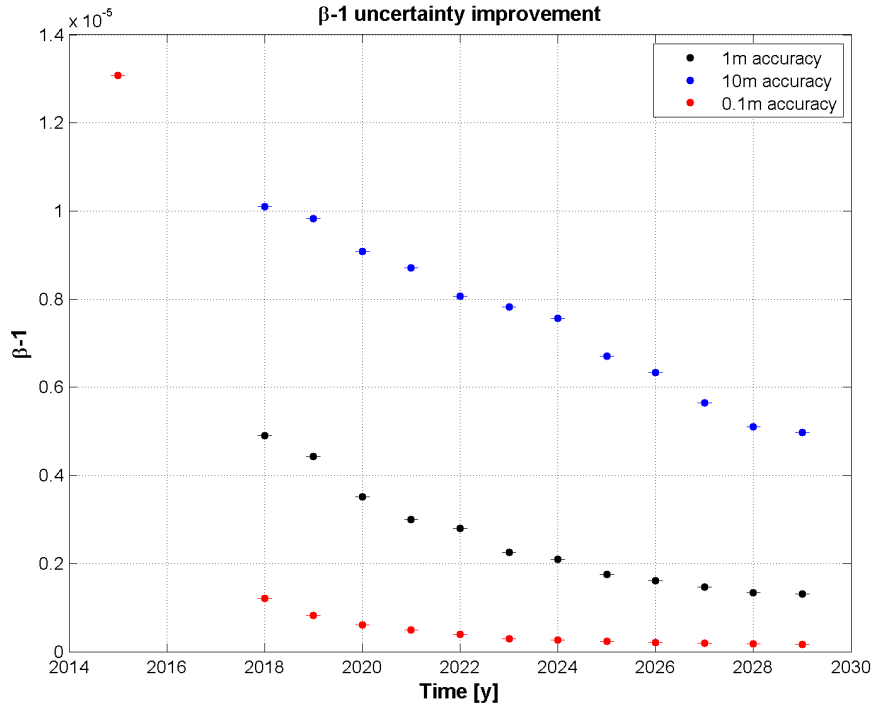
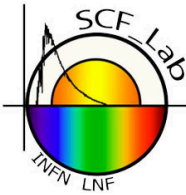


INstrument for landing-Roving laser ranging/altimetry Retroreflector Investigations

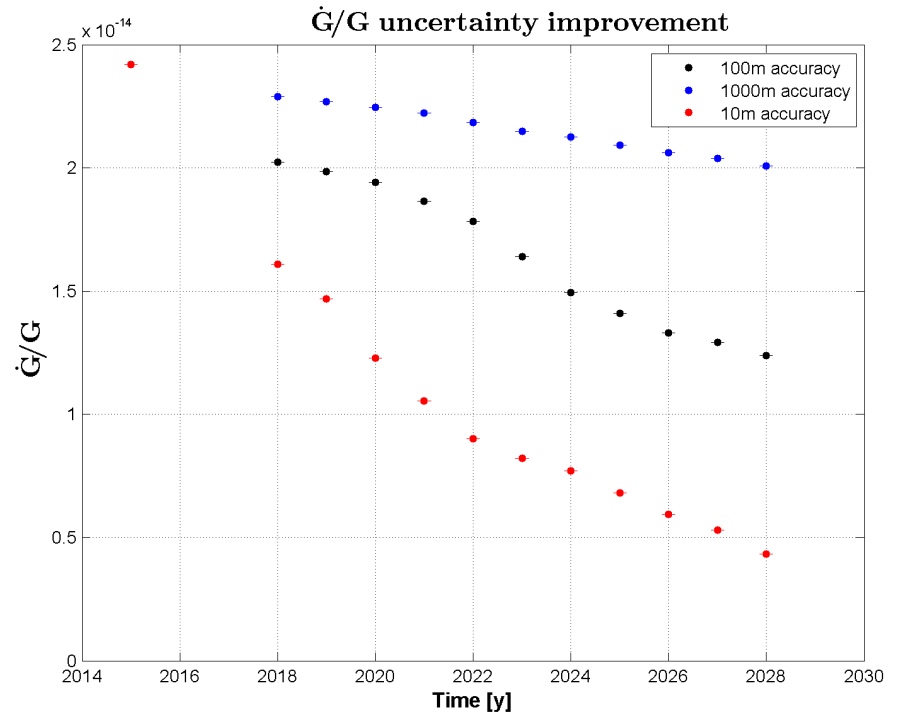
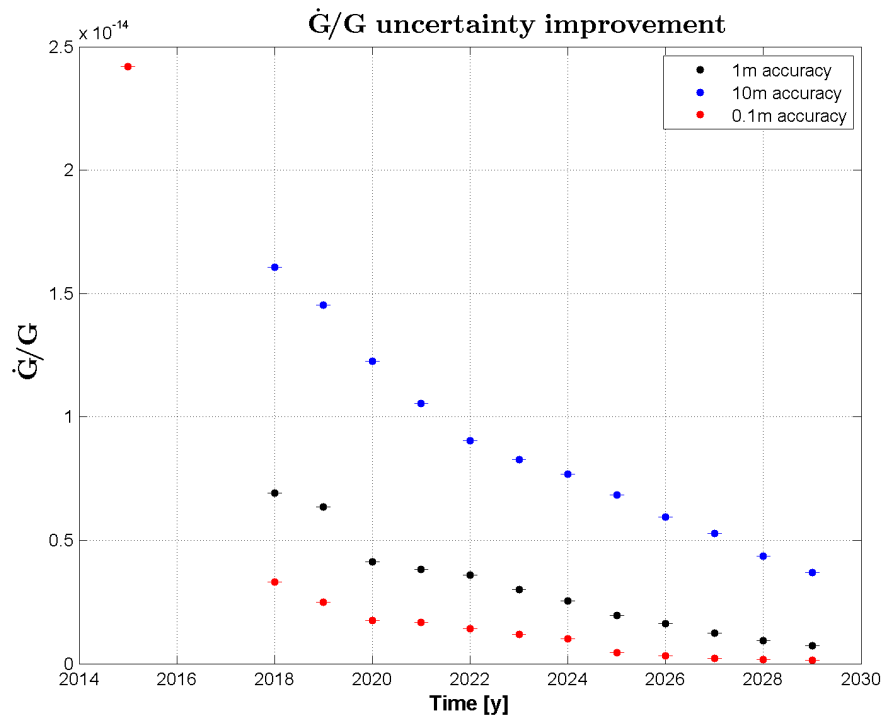
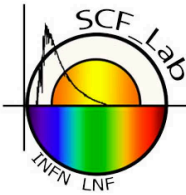
Simulated observations



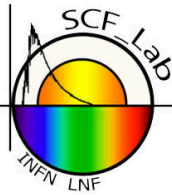
Preliminary Results



Preliminary Results



Conclusions and Prospects

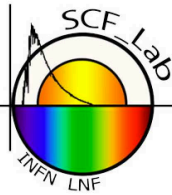


We have developed and built, **MoonLIGHT**, a unique next-generation lunar laser retroreflector payload and validated its performance with a unique facility and an innovative industry-standard laboratory test

The improvements shown by simulations are important and represent the most pessimistic case where we do not consider **LLR station upgrades** or **any software updates**

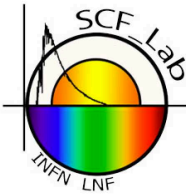
We are currently simulating INRRI performance for Mars missions of ESA/ASI and NASA. **To the Moon and beyond ...**

Further prospects

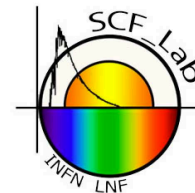


- Continue to refine our knowledge of data and software to better estimate (and reduce) the measurement uncertainty on geodetic precession, \dot{G}/G and on other GR parameters.
- After the ExoMARS landing we can also develop future General Relativity tests with Mars.
- We have the option to implement the equations of motion of new gravity theories (like SPACE-TIME TORSION and NON-MINIMALLY COUPLED GRAVITY) inside PEP and study not only the secular variation of the geodetic precession , but also periodic signatures of NEW PHYSICS on the geodetic precession and on other PPN parameters

Publications

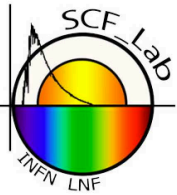


- M. Martini et al, Moonlight: A new lunar laser ranging retroreflector and the lunar geodetic precession, *Acta Polytechnica* **53**(Supplement):746–749, 2013, DOI: 10.14311/AP.2013.53.0746
- M. Martini et al, MoonLIGHT: A USA–Italy lunar laser ranging retroreflector array for the 21st century, *Planetary and Space Science* 74 (2012) 276–282.
- M. Martini et al, Laser ranging positioning metrology for Galileo and the Moon, *Metrology for Aerospace*, 2015 IEEE, DOI: 10.1109/MetroAeroSpace.2015.7180630
- S. Dell’Agnello et al, Advanced Laser Retroreflectors for Astrophysics and Space Science, *Journal of Applied Mathematics and Physics*, 3, 218-227, 2015
- M. Martini and S. Dell’Agnello, Probing gravity with next generation lunar laser ranging, Chapter in the book: R. Peron et al. (eds.), *Gravity: Where Do We Stand?*, DOI 10.1007/978-3-319-20224-2_5, Springer International Publishing, Switzerland, 2016.
- INRRI-EDM/2016: the first laser retroreflector on the surface of Mars, submitted to *Advances in Space Research, 2016*
- *M. Martini et al, PRL* in preparation



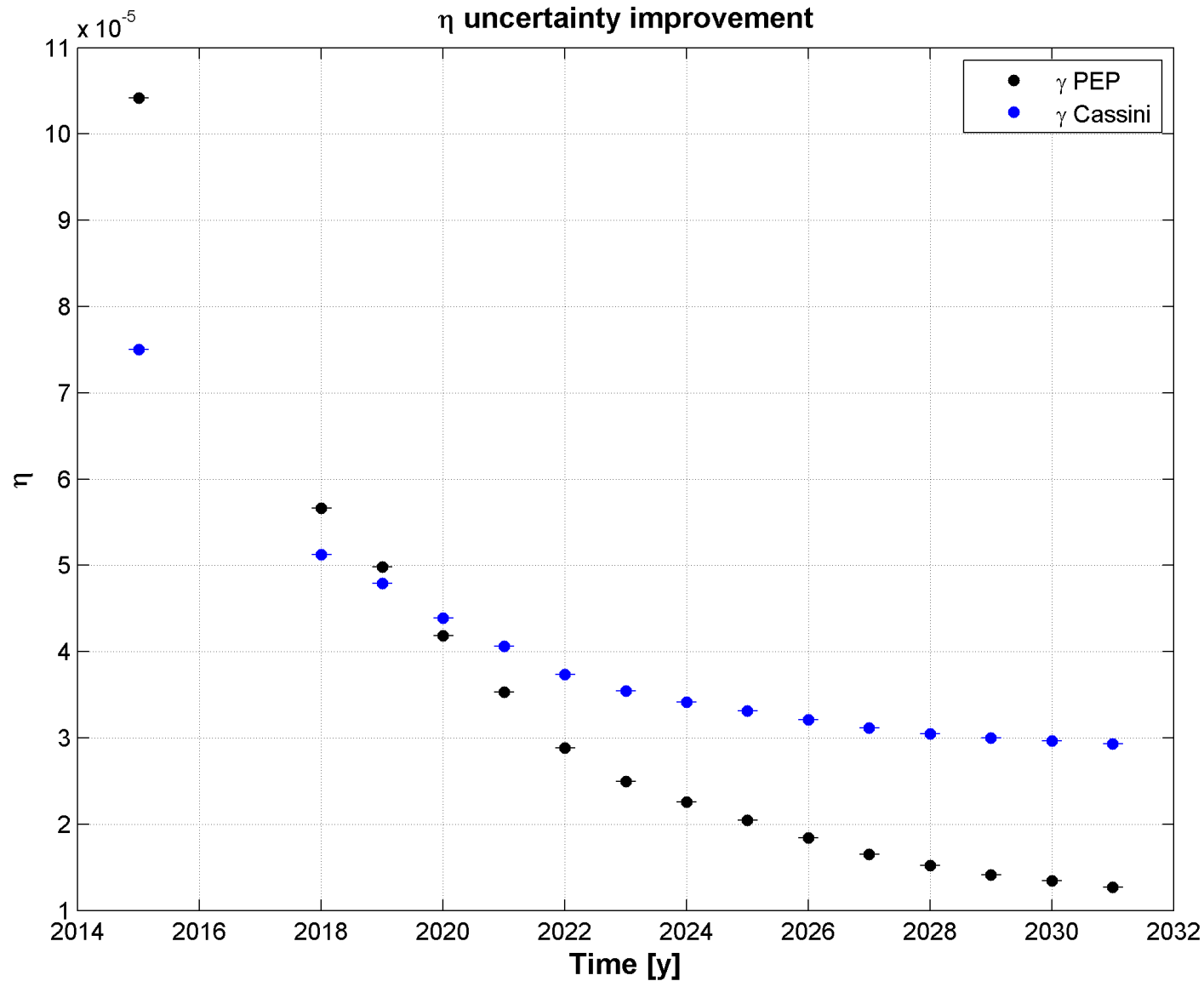
***THANK YOU
FOR YOUR ATTENTION***

ANY COMMENTS/QUESTIONS?



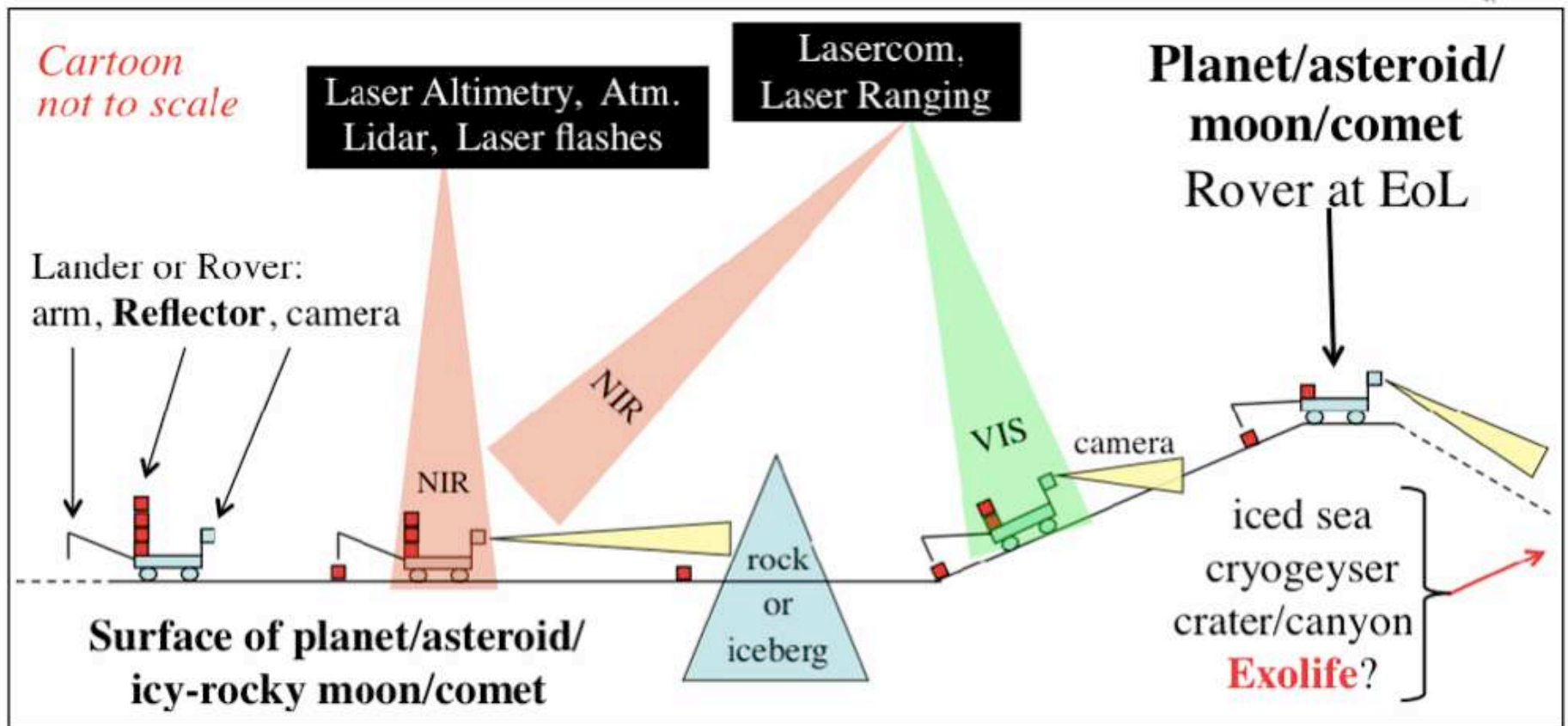
SPARES

GR test improvement: Simulated observations

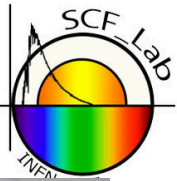


INstrument for landing-Roving laser ranging/altimetry Retroreflector Investigations

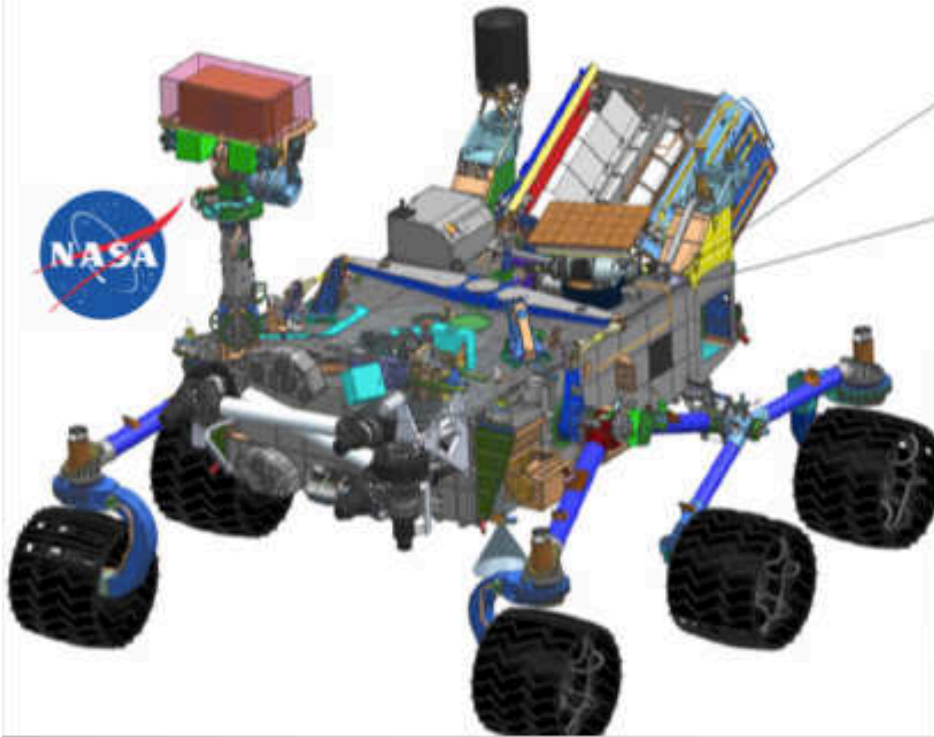
Microreflector: Passive: 25 gr; Compact: 54 mm × 20



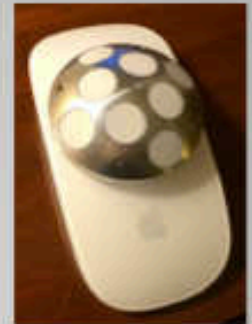
Next steps



INRRI-2020:
INstrument for landing-**R**oving laser **R**etroreflector **I**nvestigations
for NASA **Mars 2020**



25 grams
Smaller than a computer mouse



ESA
**ExoMars
2018**

