

Lenses and Wedges  
for long arm cavities?  
Or:  
Terrain Following Interferometry

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LIGO-G1601202

Photo: Robert Ward / Stefan Ballmer (2016/03/12)

# LIGO The Idea

- Really long interferometers have two problems:
  - The required optics size becomes challengingly **large**
  - Straight beam tubes imply **a lot of earth moving ( $\$ \sim L^3$ )**  
( $h=30\text{m}$  at  $40\text{km}$ )



# LIGO The Idea



- Lenses / Wedges can
  - Keep the **beam size** reasonable
  - **Steer the beam**
- Can we **get away** with them in arm cavities?  
(esp. **long** ones?)



Caution:  
bending exaggerated



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# Beam deflection and vertical coupling



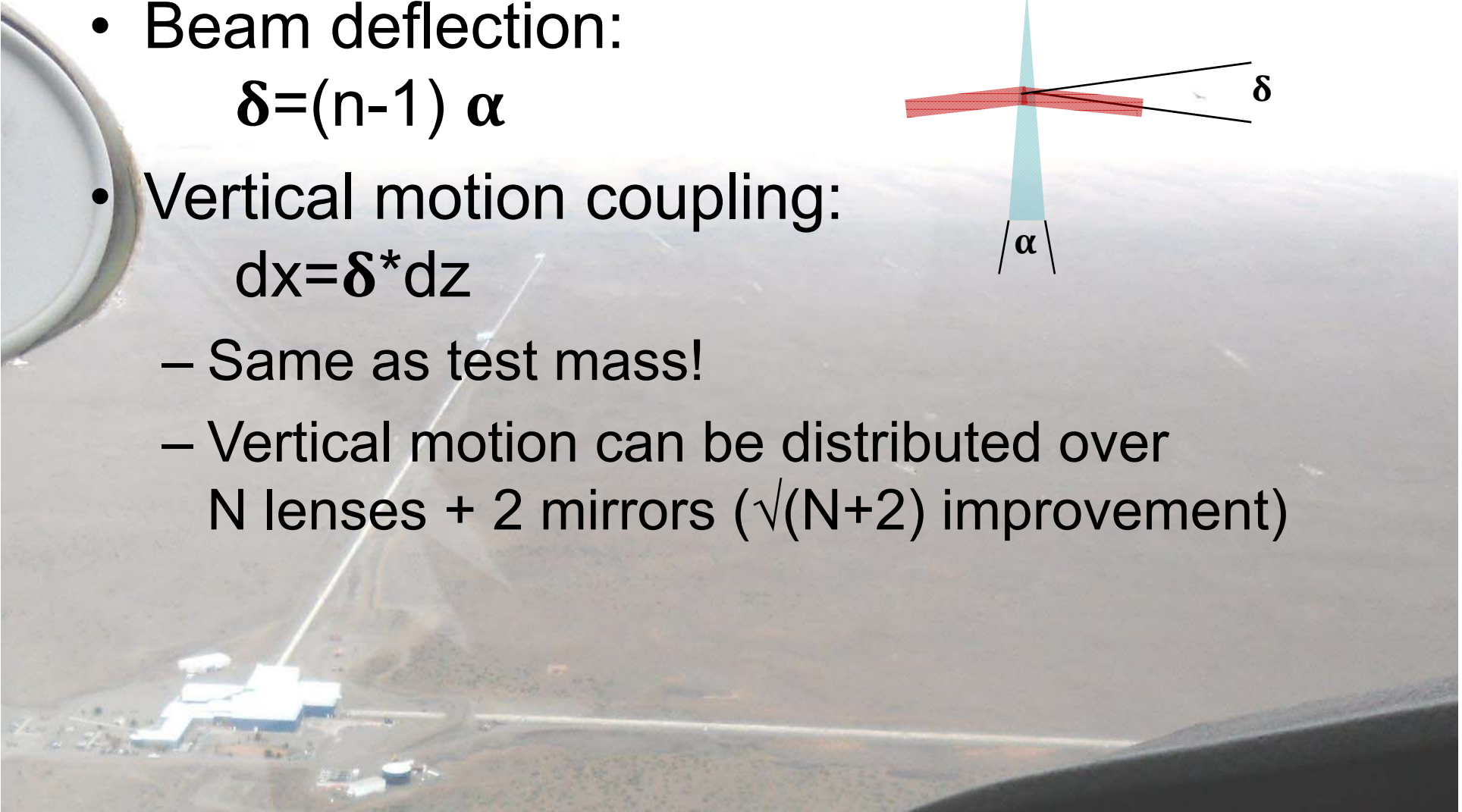
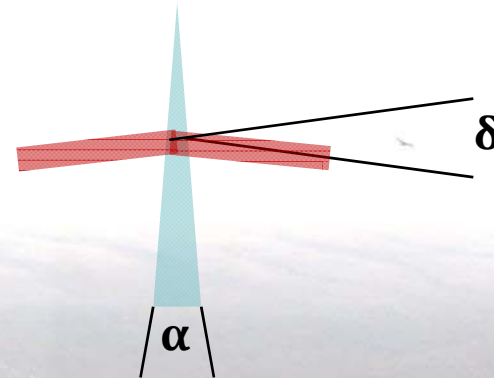
- Beam deflection:

$$\delta = (n-1) \alpha$$

- Vertical motion coupling:

$$dx = \delta * dz$$

- Same as test mass!
- Vertical motion can be distributed over N lenses + 2 mirrors ( $\sqrt{N+2}$  improvement)

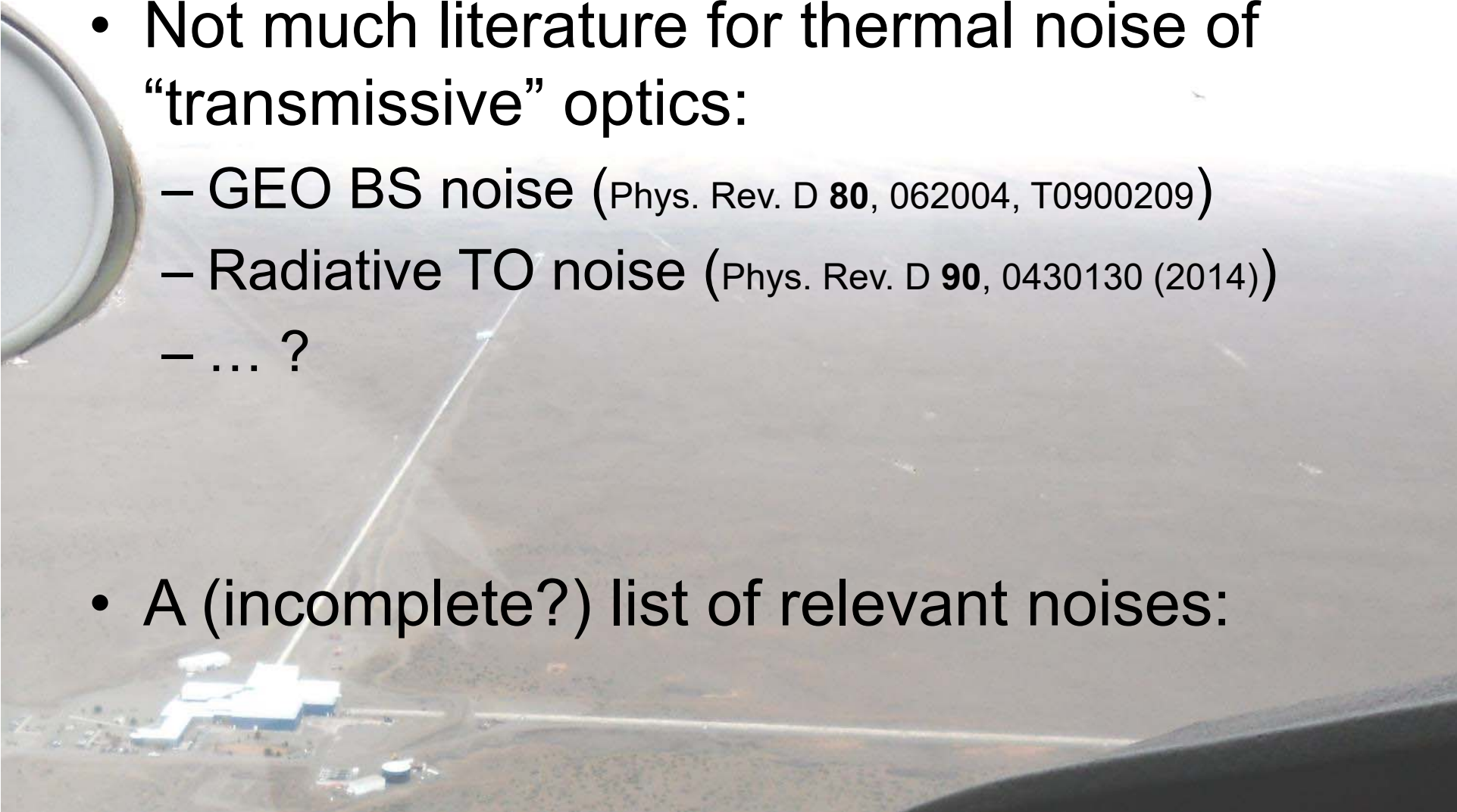




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## Noise Zoo



- 
- Not much literature for thermal noise of “transmissive” optics:
    - GEO BS noise (Phys. Rev. D **80**, 062004, T0900209)
    - Radiative TO noise (Phys. Rev. D **90**, 0430130 (2014))
    - ... ?
  - A (incomplete?) list of relevant noises:



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# Transmissive Brownian Noise



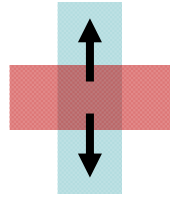
- **Dominant** noise source for thin lens
- Down by  $\sim(n-1)$  in amplitude compared to mirror (includes double-pass)
- For thin disks:
  - Substrate **scaling changes** from  $1/w$  to  $a/w^2$  (Same scaling as coating loss)
  - **Reduced coupling** to floppy mech. modes

$$S_x(f) = \frac{2k_B T (1-\eta^2) (n-1)^2}{\sqrt{\pi^3} f w Y} \left( \phi_s + \frac{2}{\sqrt{\pi}} \frac{1-2\eta}{1-\eta} \frac{d_c}{w} \phi_c \right)$$

# LIGO Thermo-Optic Noise

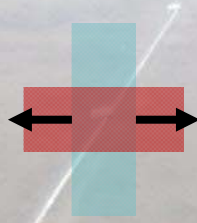


- Dissipative (radial & standing wave)



$$S_x(f) = \frac{16k_B\kappa T^2\beta_{eff}^2 a}{\pi C^2\rho^2 w^4\omega^2} \left( 1 + \frac{k^2 w^2}{1 + \frac{16k^4\kappa^2}{C^2\rho^2\omega^2}} \right)$$

- Radiative (surface)



$$S_x(f) = \frac{16k_B\epsilon\sigma T^5\beta_{eff}^2}{\pi C^2\rho^2 w^2\omega^2} N$$

- Coating (surface structure)



$$S_x(f) = \frac{2\sqrt{2}k_B T^2 (\beta_{eff}^c d)^2}{\pi w^2 \sqrt{\kappa C \rho \omega}} N$$



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## Another message



- For very large beam spots:
  - **Substrate Brownian** comparable to **Coating Brownian**

$$Sx \propto d_c \phi_c + (1.1w) \phi_s \quad d_s > w$$

$$Sx \propto d_c \phi_c + d_s \phi_s \quad d_s < w$$

$$\frac{\phi_c}{\phi_s} \approx 10^5, \quad d_c \frac{\phi_c}{\phi_s} \approx O(10 \text{ cm})$$



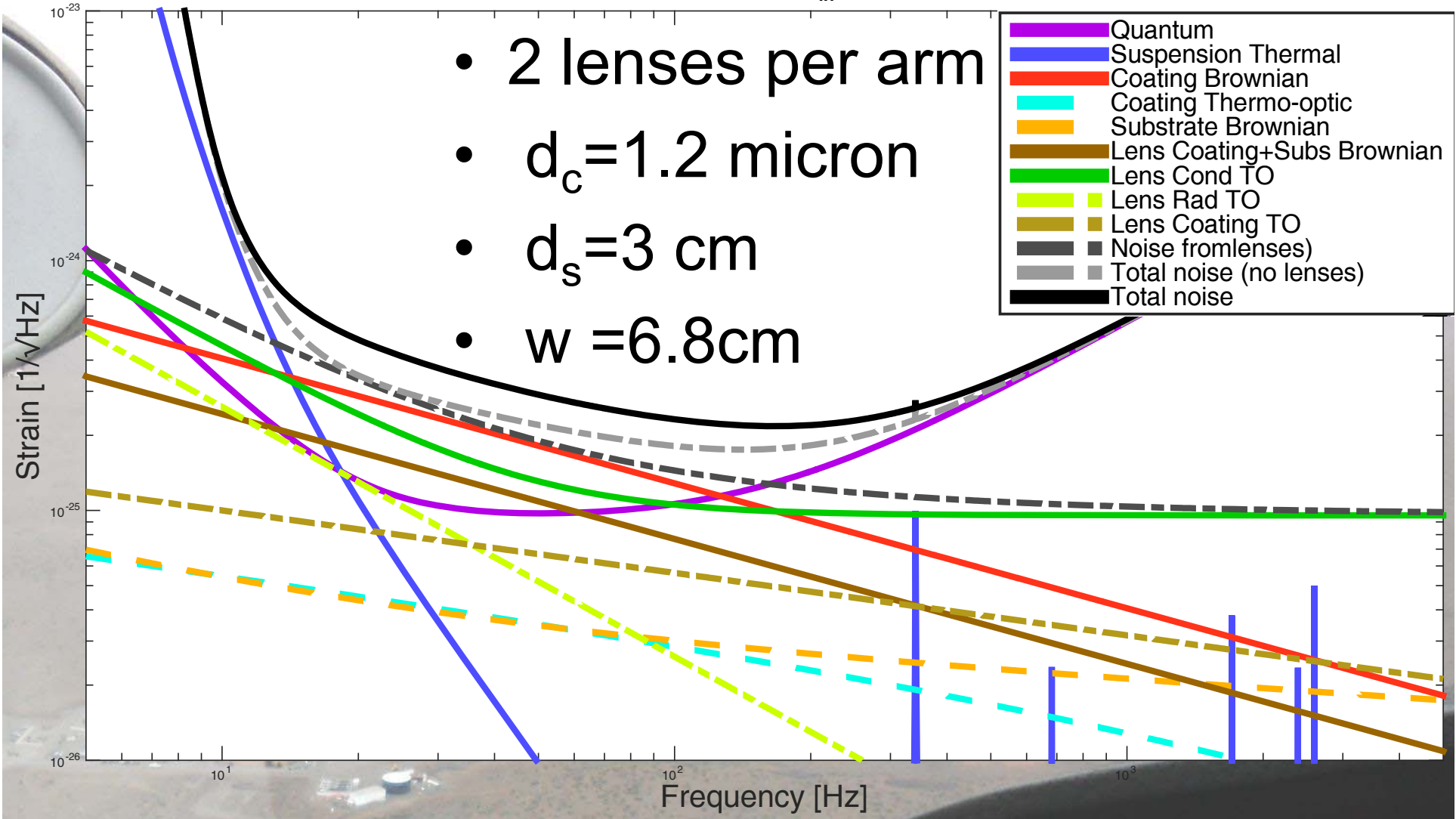


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# “CE1” (T=300K) with lenses, an example



CE1tfi Noise Curve:  $P_{in} = 150.0$  W



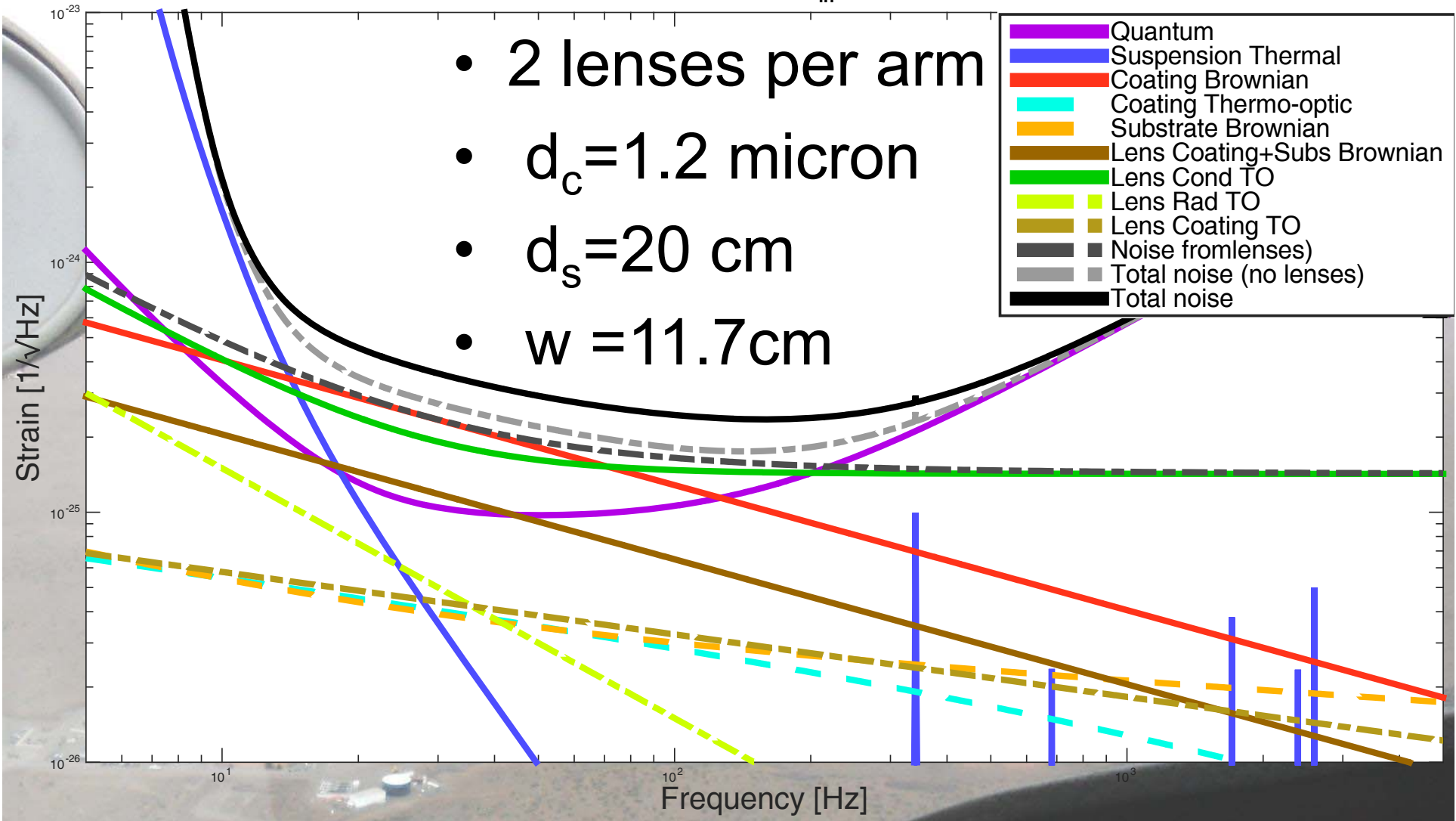


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# “CE1” (T=300K) with lenses, an example



CE1tfi Noise Curve:  $P_{in} = 150.0$  W

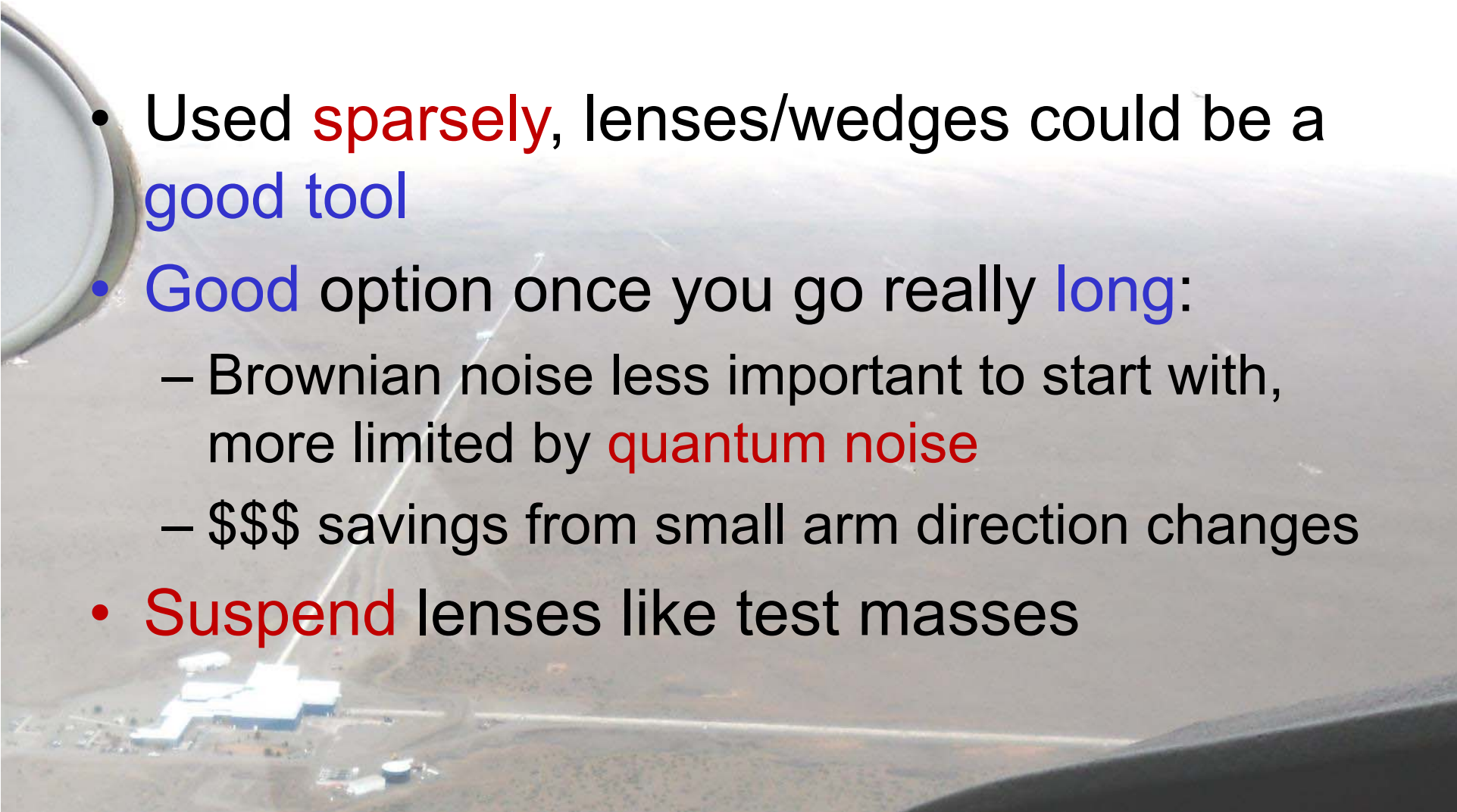


The LIGO logo consists of the word "LIGO" in a bold, black, sans-serif font. To the left of the text are several concentric, curved lines that resemble ripples or sound waves, rendered in a light gray color.

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# Assessment



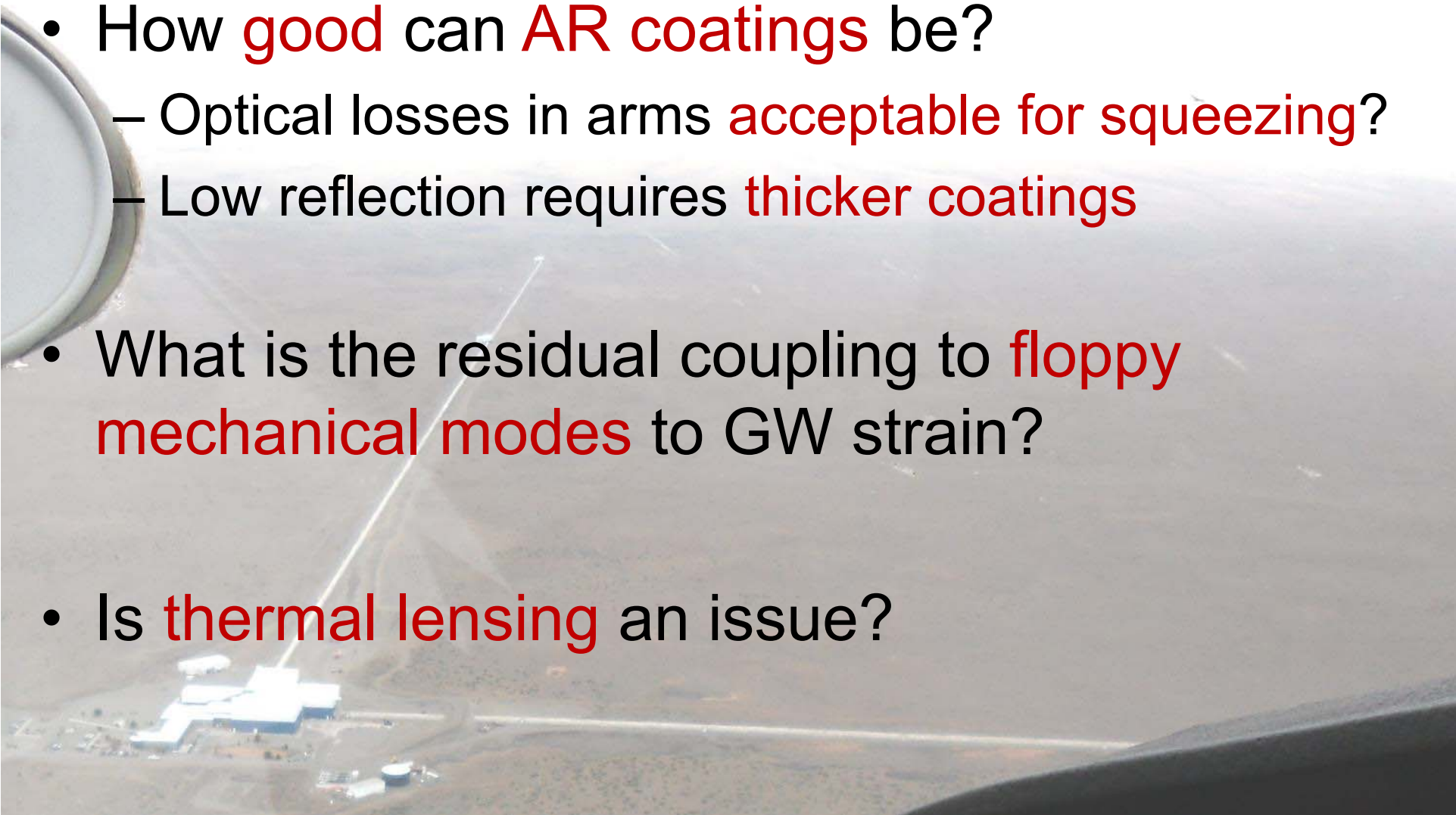
- 
- An aerial photograph of the LIGO observatory site in a desert landscape. A long, straight road or path runs across the terrain, with a small cluster of white buildings at one end. The background shows rolling hills under a clear sky.
- Used **sparingly**, lenses/wedges could be a good tool
  - Good option once you go really long:
    - Brownian noise less important to start with, more limited by **quantum noise**
    - \$\$\$ savings from small arm direction changes
  - **Suspend** lenses like test masses



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# Possible Issues



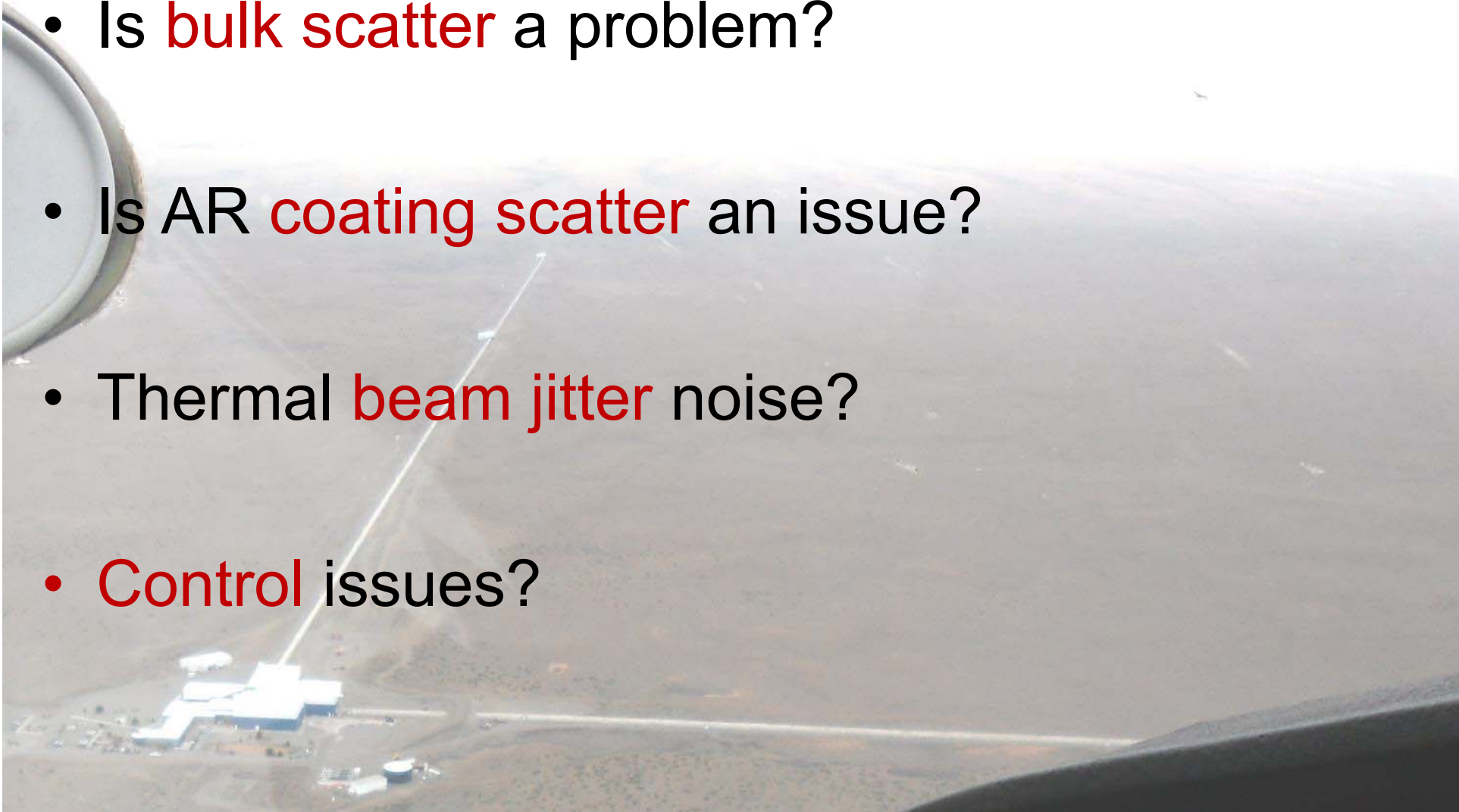
- 
- How **good** can **AR coatings** be?
    - Optical losses in arms **acceptable for squeezing**?
    - Low reflection requires **thicker coatings**
  - What is the residual coupling to **floppy mechanical modes** to GW strain?
  - Is **thermal lensing** an issue?



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# Possible Issues



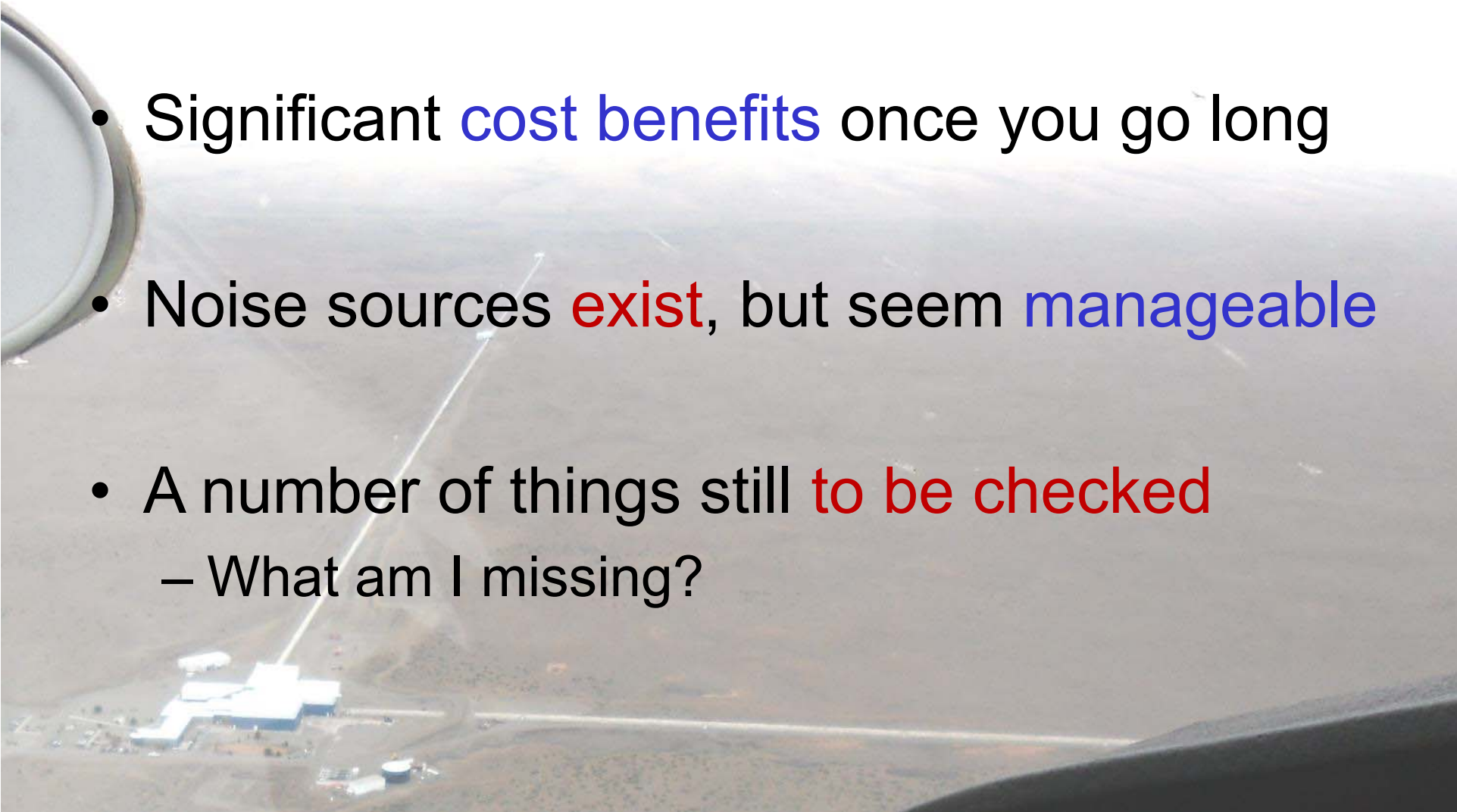
- Is **bulk scatter** a problem?
  - Is AR **coating scatter** an issue?
  - Thermal **beam jitter** noise?
  - **Control** issues?
- 



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# Conclusion: Is this a good idea?



- 
- Significant **cost benefits** once you go long
  - Noise sources **exist**, but seem **manageable**
  - A number of things still **to be checked**
    - What am I missing?