



# Collective motion and chain representation of non-Markovian dynamics

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# Outline

- Opens systems and non-Markovian dynamics
- Independent oscillators model
- Collective motion and chain representation
- Future work

# Open quantum systems

- Interaction between the system and the environment

$$\rho = \rho_S \otimes \rho_E$$

$$H = H_S + H_E + H_{\text{INT}}$$

- General evolution has a complicated form

$$\frac{d}{dt}\rho_S(t) = -i \text{tr}_E[H, \rho(t)] \longrightarrow \text{it is necessary to introduce some approximation}$$

# Markovian vs non-Markovian dynamics

- Markovian dynamics: the evolution has **no memory terms**

$$\frac{d}{dt}\rho_S(t) = -i[H, \rho_S(t)] + \mathcal{D}[\rho_S(t)] \quad \mathcal{D}[\rho_S(t)] = \sum_k \gamma_k \left( A_k \rho A_k^\dagger - \frac{1}{2} \left\{ A_k^\dagger A_k, \rho \right\} \right)$$

- Physics: the bath timescale is **much faster** than the system

- Non-Markovian dynamics  $\longrightarrow$  **memory terms**

$$\frac{d}{dt}\rho_S(t) = \int_{t_0}^t ds K(t, s) \rho_S(s)$$

# Why non-Markovian dynamics?

- Experimental:
  - ultrafast chemical reactions (OLEDs, FMO)
  - solid state (PBG materials)
  - quantum optics
  
- Theoretical:
  - inflation models / semiclassical gravity
  - statistical mechanics
  - collapse models

# Non-Markovian dynamics

- “Non-Markovian” is all what goes beyond the Markov approximation, no characterization is implied



one needs to **introduce a characterization**, e.g. a particular model

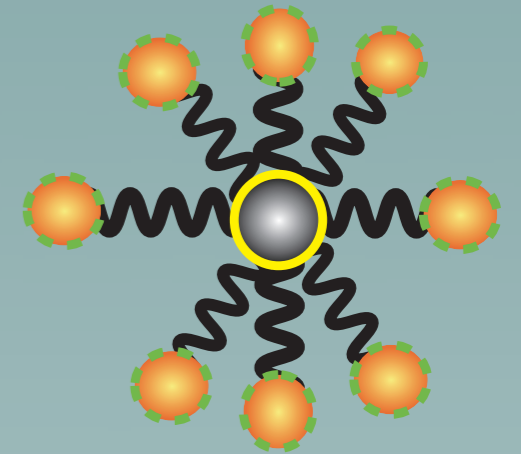
- All models proposed so far are phenomenological



**lack of description emerging from first principles**

# The independent oscillators model

- System bilinearly coupled to  $N$  **independent** harmonic oscillators



- Hamiltonian

$$H = \frac{p^2}{2M} + V(x) + x \sum_{k=1}^N c_k x_k + \sum_{k=1}^N \frac{1}{2} (p_k^2 + \omega_k^2 x_k^2)$$

- Environmental coupling is determined by the **spectral density**

$$J(\omega) = \frac{\pi}{2} \sum_k \frac{c_k^2}{\omega_k} \delta(\omega - \omega_k)$$

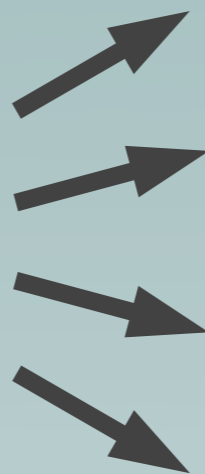
# The independent oscillators model

- Generalized Langevin equation (GLE)

$$M\ddot{x}(t) + M \int_0^t ds K(t-s)\dot{x}(s) + V_x(s) = f(t)$$

where  $K(t-s)$ ,  $f(t)$  are functions of  $J(\omega)$ ,  $\{x_k(0), \dot{x}_k(0)\}$

- Well known model:



Quantum Brownian Motion

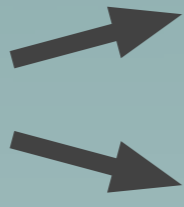
Master equation

Fluctuation dissipation relation

...



# What do we learn about NM?

- We **do** learn:  new non-Markovian (or memory) effects  
how they affect the system's dynamics
- We **do not** learn: how they arise from the microscopic motion



aim of the project is to understand how non-Markovian effects **emerge from microscopic motion**

# The chain model

- System coupled to a **chain** of  $N$  harmonic oscillators



- Hamiltonian

$$H = \frac{p^2}{2M} + V(x) + DxX_1 + \sum_{k=2}^N D_{k-1}X_{k-1}X_k + \sum_{k=1}^N \frac{1}{2} (P_k^2 + \Omega_k^2 X_k^2)$$

- It gives a more physical idea of propagation



more suitable to study **short time effects**

# The chain representation

- Idea: **chain representation** of the **independent oscillators** bath

Independent

$$\begin{pmatrix} \ddot{x}_1(t) \\ \ddot{x}_2(t) \\ \ddot{x}_3(t) \\ \vdots \end{pmatrix} = - \begin{pmatrix} \omega_1^2 & 0 & 0 & \dots \\ 0 & \omega_2^2 & 0 & \dots \\ 0 & 0 & \omega_3^2 & \dots \\ \vdots & \vdots & \vdots & \ddots \end{pmatrix} \begin{pmatrix} x_1(t) \\ x_2(t) \\ x_3(t) \\ \vdots \end{pmatrix}$$

Chain

$$\begin{pmatrix} \ddot{X}_1(t) \\ \ddot{X}_2(t) \\ \ddot{X}_3(t) \\ \vdots \end{pmatrix} = - \begin{pmatrix} \Omega_1^2 & -D_1 & 0 & \dots \\ -D_1 & \Omega_2^2 & -D_2 & \dots \\ 0 & -D_2 & \Omega_3^2 & \dots \\ \vdots & \vdots & \vdots & \ddots \end{pmatrix} \begin{pmatrix} X_1(t) \\ X_2(t) \\ X_3(t) \\ \vdots \end{pmatrix}$$

- Find orthogonal  $Q$  such that

$$Q \begin{pmatrix} \omega_1^2 & 0 & 0 & \dots \\ 0 & \omega_2^2 & 0 & \dots \\ 0 & 0 & \omega_3^2 & \dots \\ \vdots & \vdots & \vdots & \ddots \end{pmatrix} Q^T = \begin{pmatrix} \Omega_1^2 & -D_1 & 0 & \dots \\ -D_1 & \Omega_2^2 & -D_2 & \dots \\ 0 & -D_2 & \Omega_3^2 & \dots \\ \vdots & \vdots & \vdots & \ddots \end{pmatrix}$$



inverse  
eigenvalue  
problem

- Collective motion:**

$$X_k = \sum_j Q_{kj} x_j$$

# The chain representation

- Short times  $\longrightarrow$  truncated chain

- First proposed by chemical physicists
  - $\nearrow$  looking for faster simulations
  - $\longrightarrow$  complicated transformation through hierarchical baths
  - $\searrow$  fitting parameters with observed dynamics

- Approximation for the kernel of the GLE:

$$K(t) \simeq K^{(n)}(t) + o(t^{4n})$$

# Where do we stand?

- The inverse eigenvalue problem has unique solution
- General evolution for the chain model has a complicated form



no more a GLE but nested integrals

- **Final goal:**  
Prove that

$$\forall n, \exists T : \tilde{x}_{\text{TC}}^{(n)}(t) = x_{\text{IO}}(t), \forall t \leq T$$