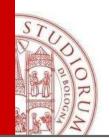


Algoritmi di ricostruzione tomografica in applicazioni di tomosintesi per imaging medico

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ALMA MATER STUDIORUM - UNIVERSITÀ DI BOLOGNA

IL PRESENTE MATERIALE È RISERVATO AL PERSONALE DELL'UNIVERSITÀ DI BOLOGNA E NON PUÒ ESSERE UTILIZZATO AI TERMINI DI LEGGE DA ALTRE PERSONE O PER FINI NON ISTITUZIONAL



Contents

- Image \Leftrightarrow sinogram
- Analytic methods: Filtered Back-Projection (FBP)
- Iterative methods: outline
- Iterative vs analytic methods
- Reconstruction in Breast Tomosynthesis
- Reconstruction in ECORAD



Contents

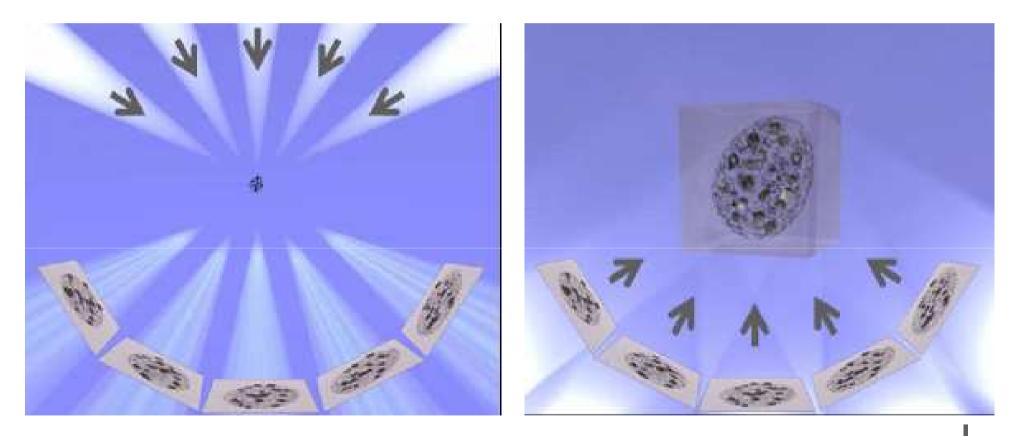
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Image reconstruction

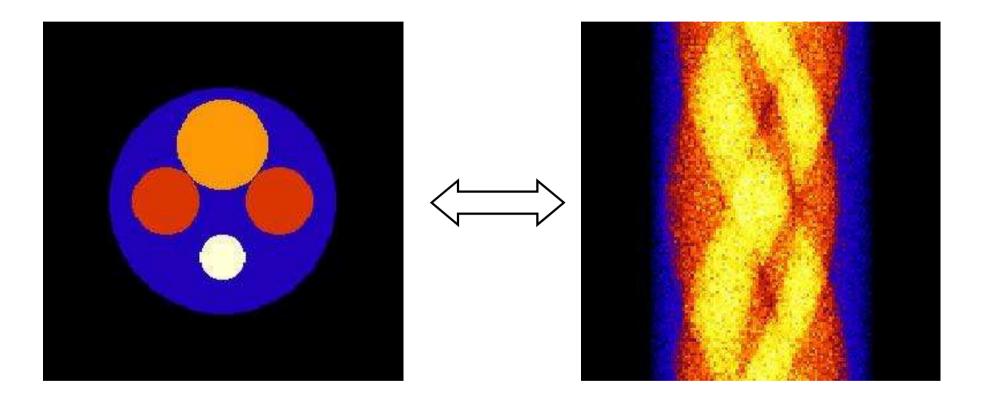
3D object \Rightarrow set of 2D projections

2D projections \Rightarrow 3D reconstruction





From image to sinogram

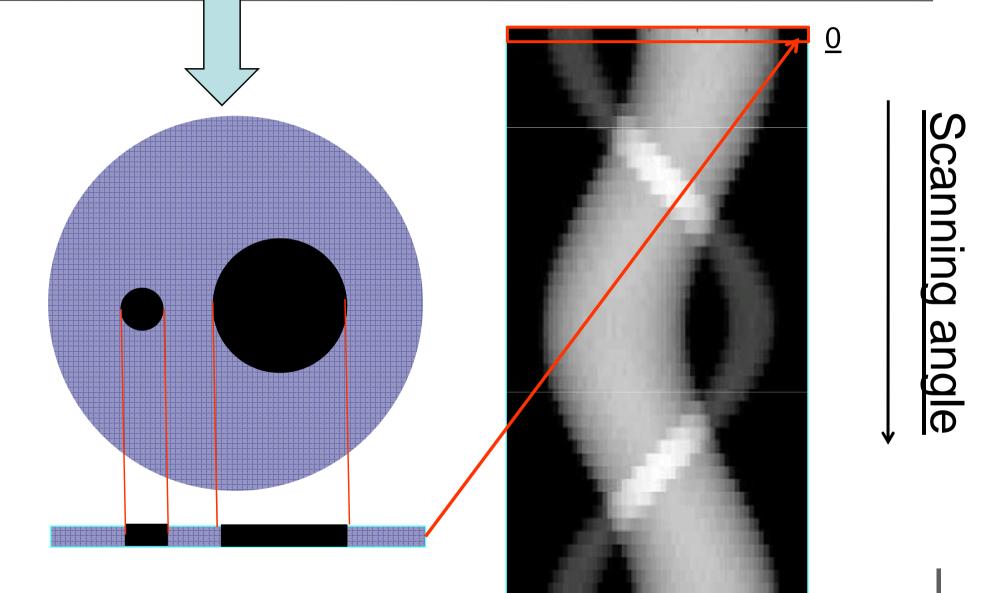


True image



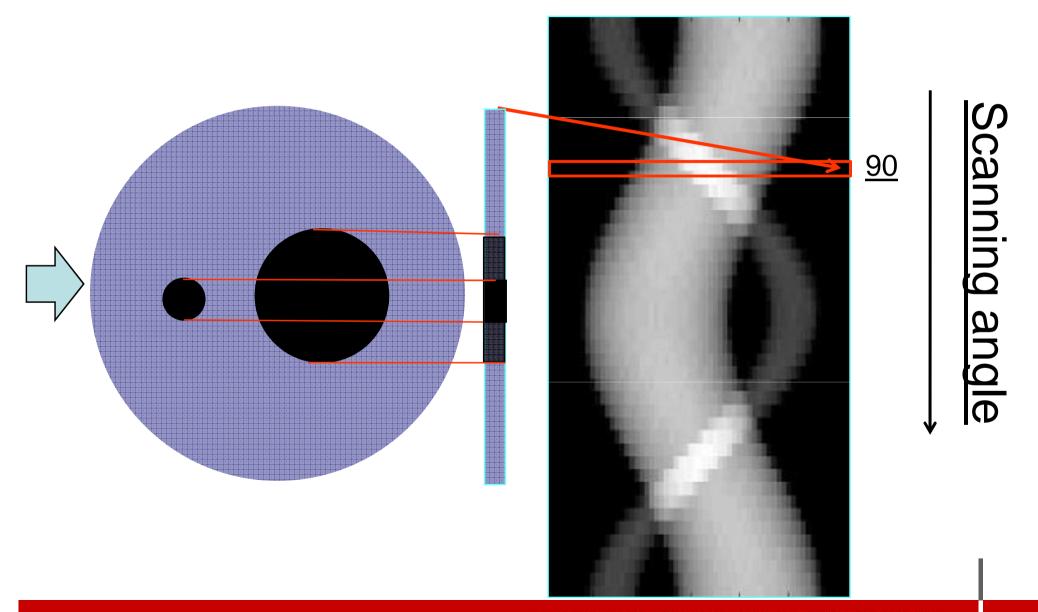


Sinogram formation





Sinogram formation





Sinogram formation

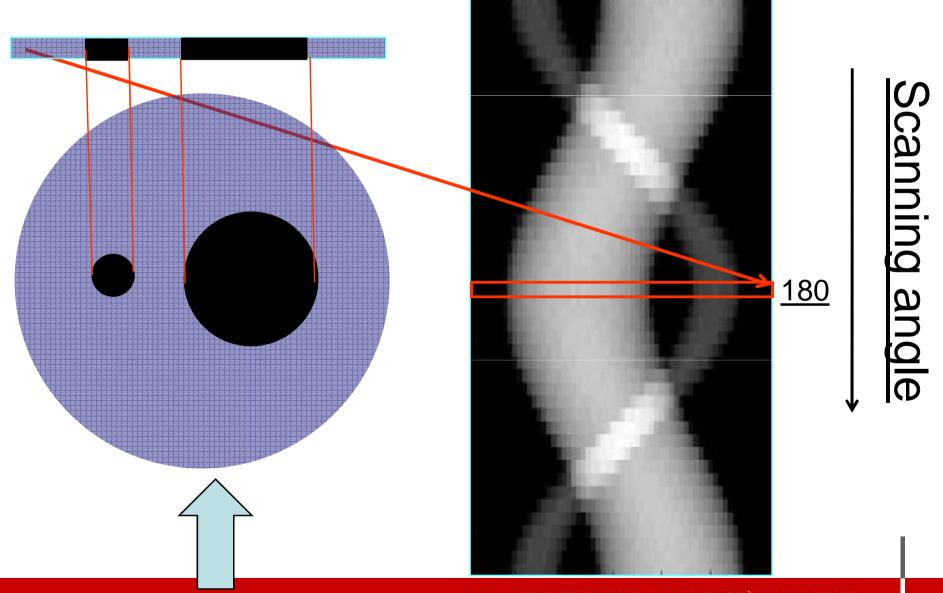
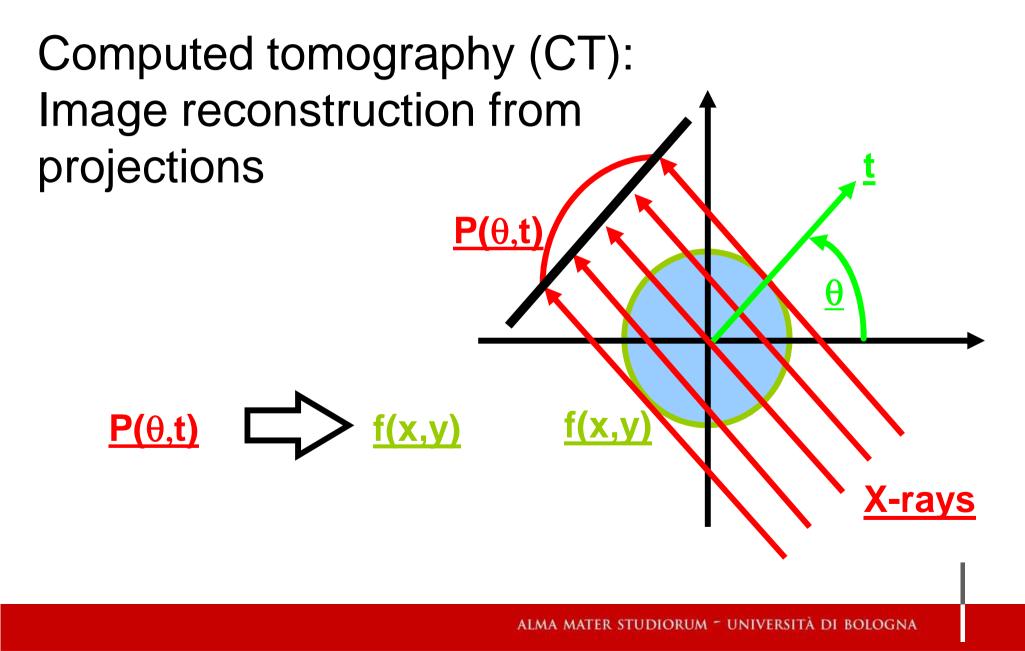




Image reconstruction principle





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FBP: outline

- 1. Projection of original data (sinogram)
- 2. Transformation of data into Fourier Domain
- 3. Filtering of data in Fourier space
- 4. Transformation of data back into Spatial Domain (inverse Fourier transform)
- 5. Backprojection

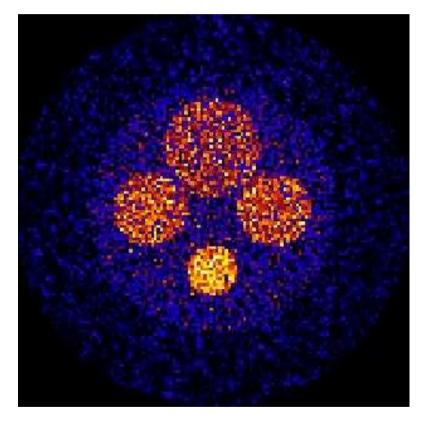


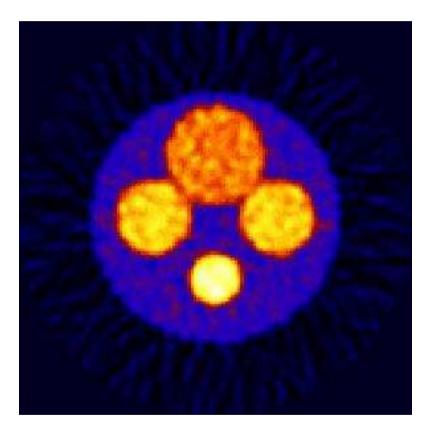
Filtering: why?

- Intrinsinc effect of FBP of amplifying low-frequency signals
- Inherent noise in the data due to the random nature of radioactivity
- Smooth out the statistical noise
- Filtering in Fourier space is less timeconsuming than in real space



Data filtering



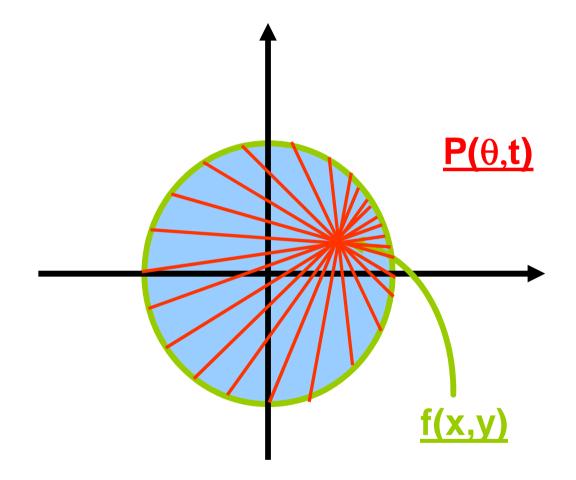


Non-filtered





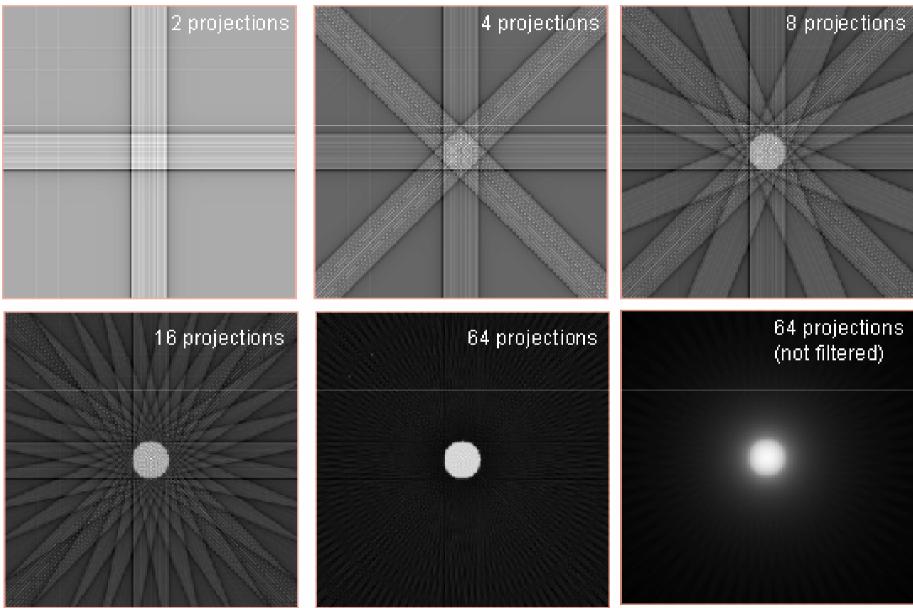
Backprojection



f(x,y) is calculated by means of all the projections $P(\theta,t)$ which cross the point (x,y)

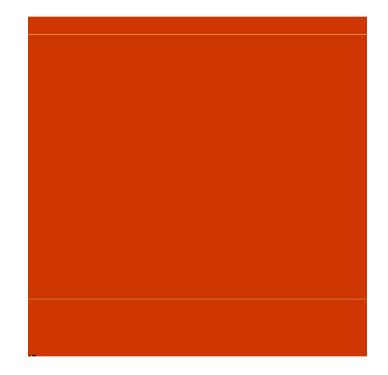


Backprojection





From projections to image





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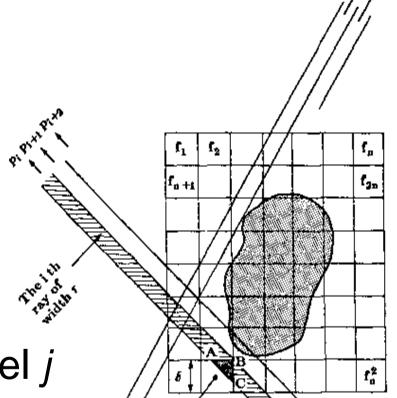
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Image and projection representation

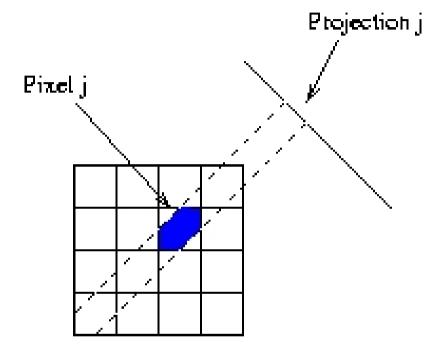
$$p_i = \sum_{j=1}^N w_{ij} f_j$$
 $i = 1, 2, ..., M$

- *p_i*: ray-sum (line integral)
- w_{ij}: weighting factor
- *f_i*: attenuation (activity) of pixel *j*
- *M*: # of rays
- N: # of pixel





Weighting factor



The weighting factors w_{ij} could simply be equal to the ratio of the two areas

Or:

- Incorporate in w_{ij} the physics of the detection process
- Effects (e.g. scatter) can be included by known models or MonteCarlo simulations, or ...



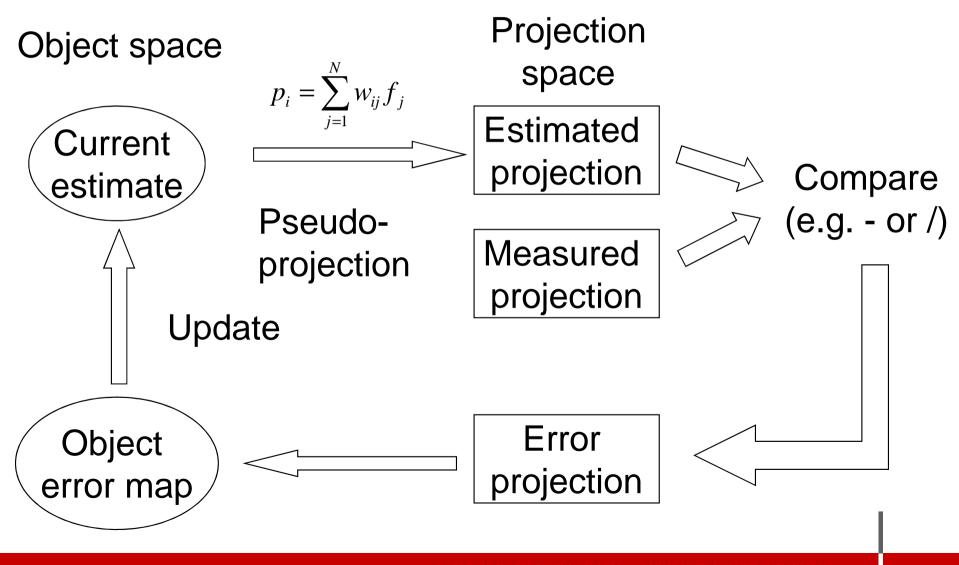
Problem formulation

- The image reconstruction task consists in estimating *f* from the previous equation. If *M* and *N* are small, we could use matrix theory methods to invert the system of equations
- Unfortunately, in practice, this is NOT possible for the following reasons:
 - *M* and *N* are very large
 - noise is present in measured data.

$$p_i = \sum_{j=1}^N w_{ij} f_j$$

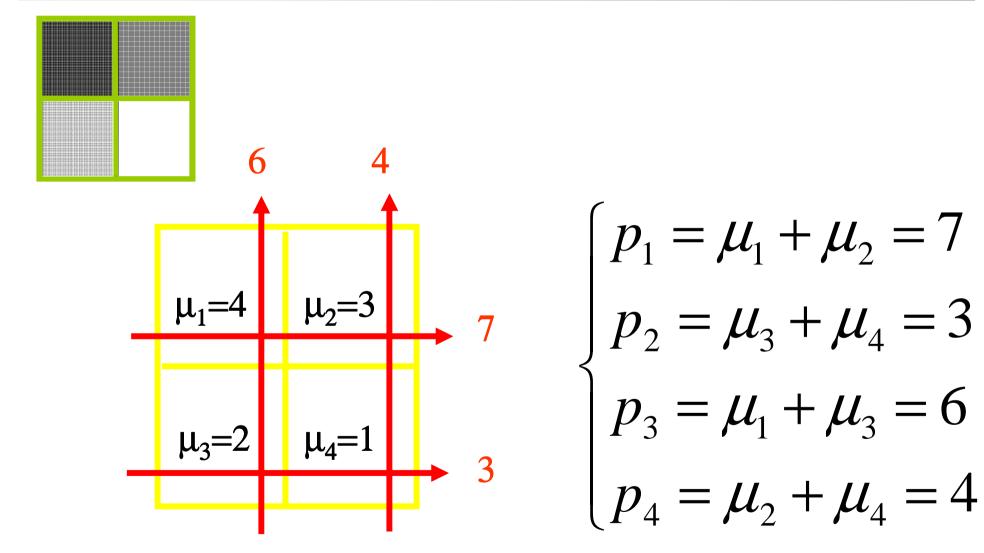


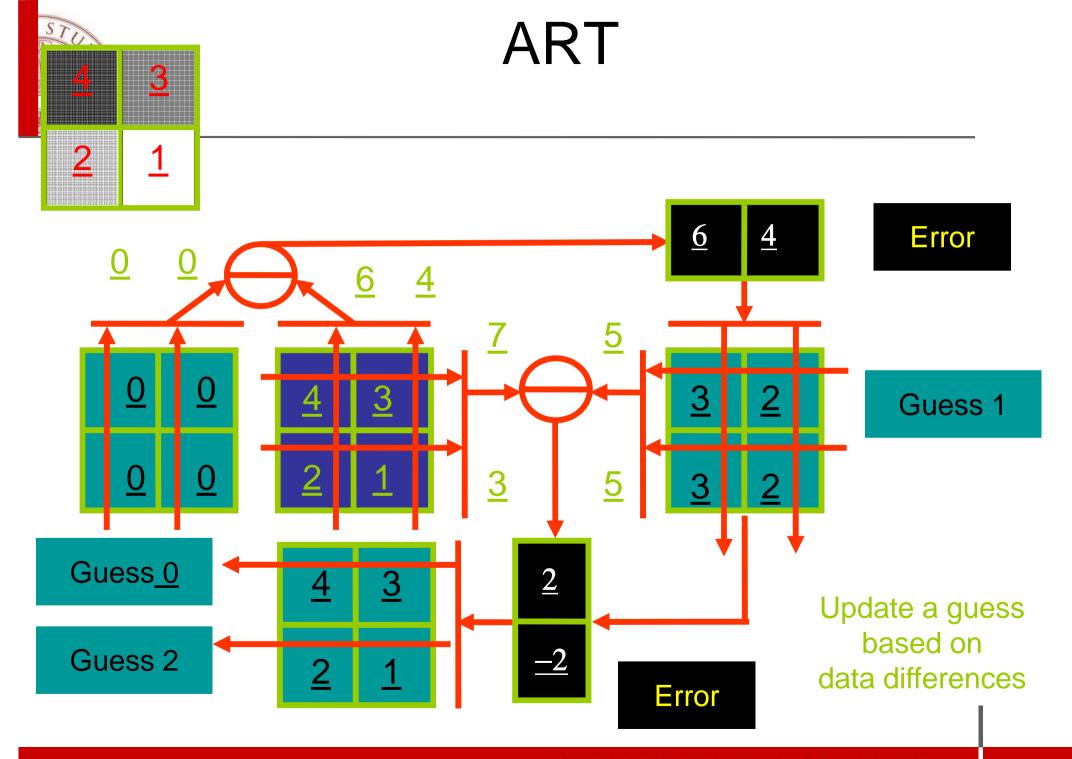
Iterative reconstruction





Reconstruction idea







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Iterative vs. Analytic reconstruction

Advantages of analytic reconstruction (FBP):

- Very often much faster
- Sometimes simpler
- Very predictable, linear, behavior easier to understand.

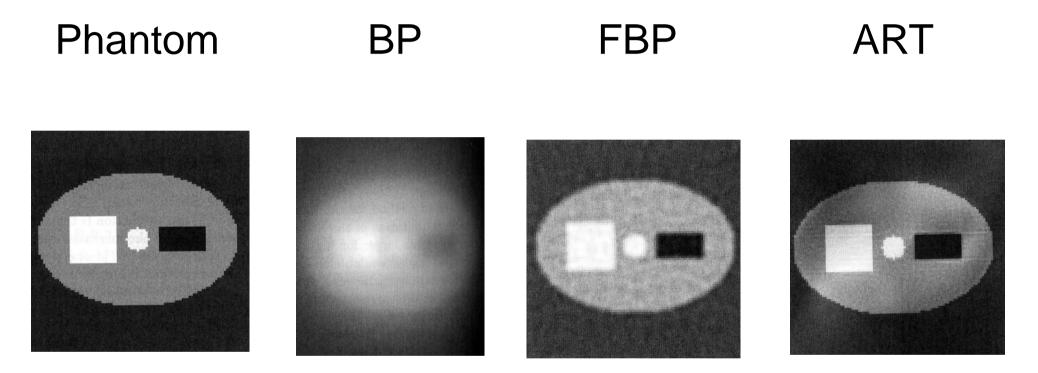
Iterative vs. Analytic reconstruction

Advantages of discrete reconstruction:

- Accurate models of the image formation process can be incorporated \Rightarrow <u>quantitative</u> <u>image reconstruction</u>, noise reduction
- Very flexible to adapt to different imaging geometries
- Well-designed for non-standard ring geometries
- Non-negativity constraints can be used



Comparison

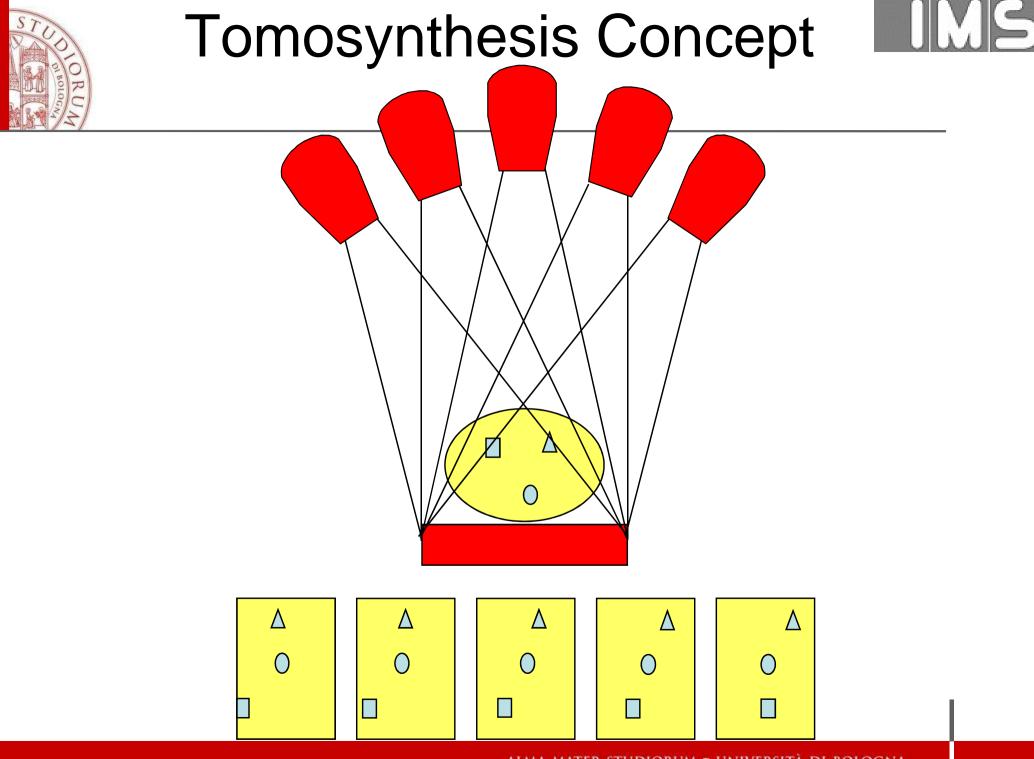


Reconstruction of phantom with different reconstruction methods using 90 projections

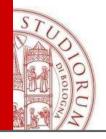


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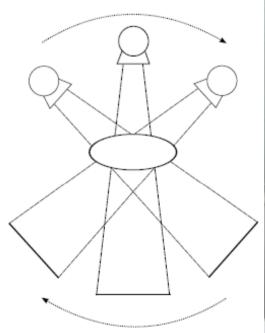






The first prototype

- Geometry:
 - C-arm
 - Angular range: ± 18°
- Detector:
 - a-Se Flat panel
 - 85 um pixel size
 - 24 cm × 30 cm
- X-ray tube:
 - W anode
 - Rh and Ag filter

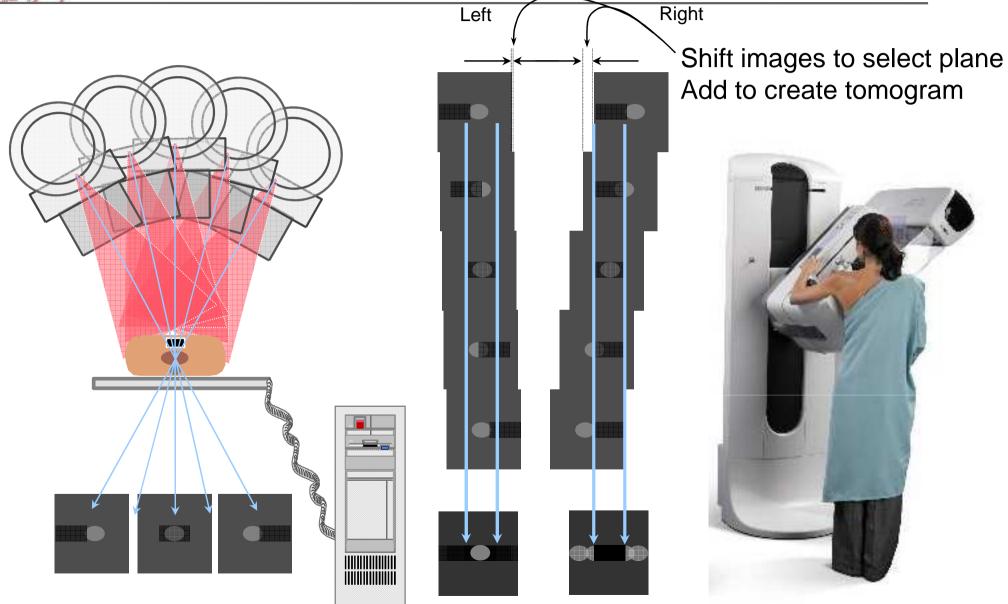






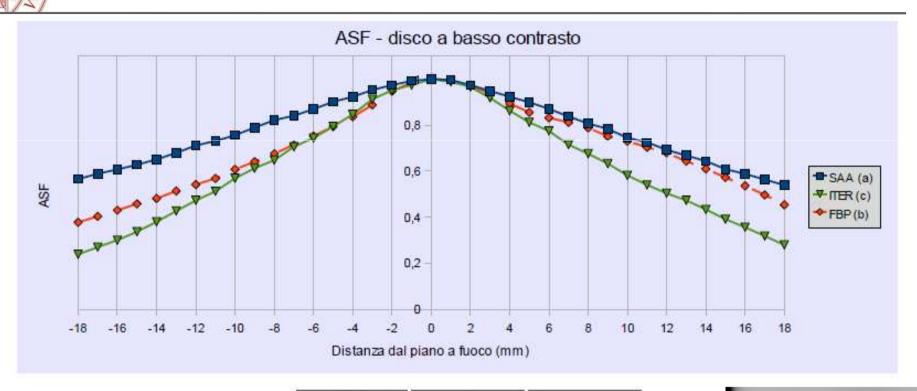
Digital Tomosynthesis

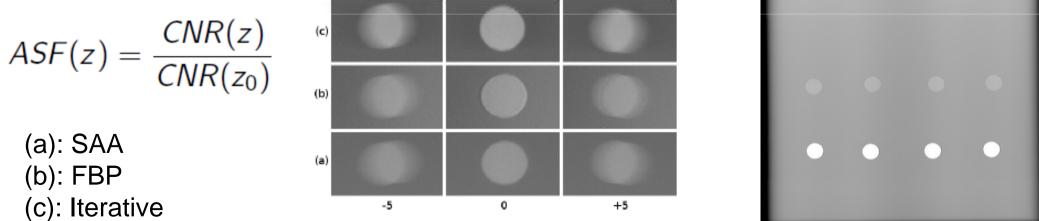






Results: phantoms

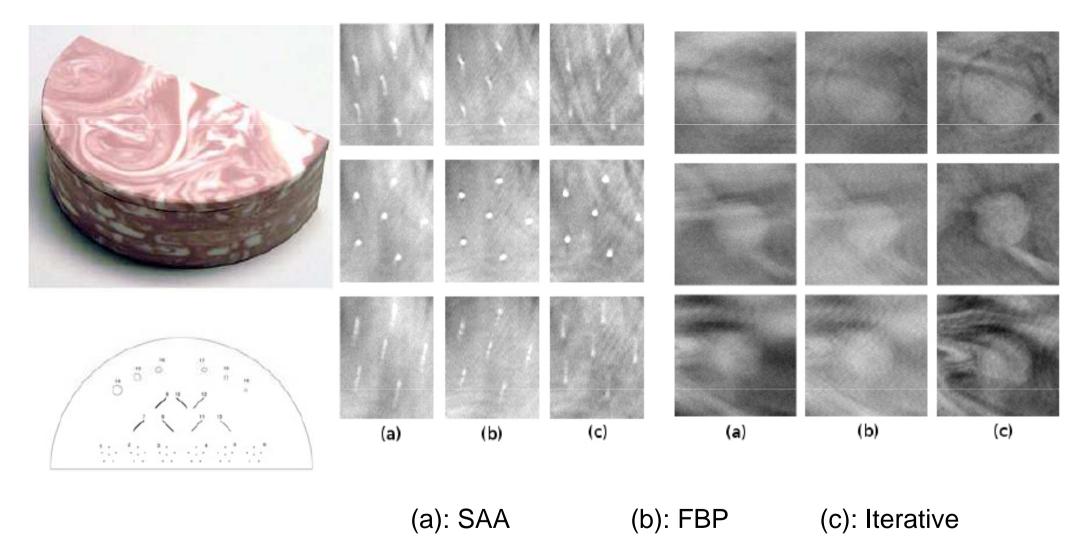






Results: phantoms









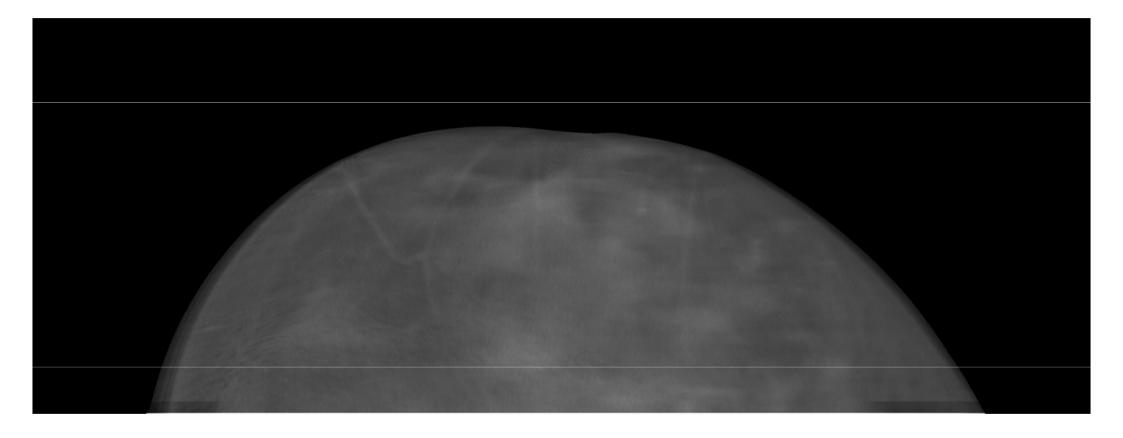


Image courtesy of IMS



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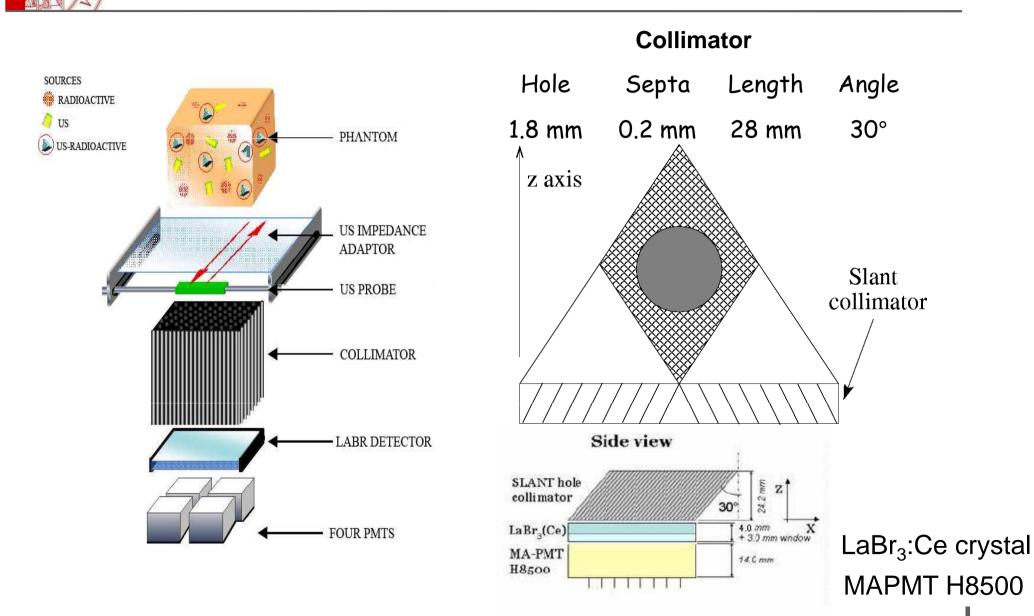
ECORAD

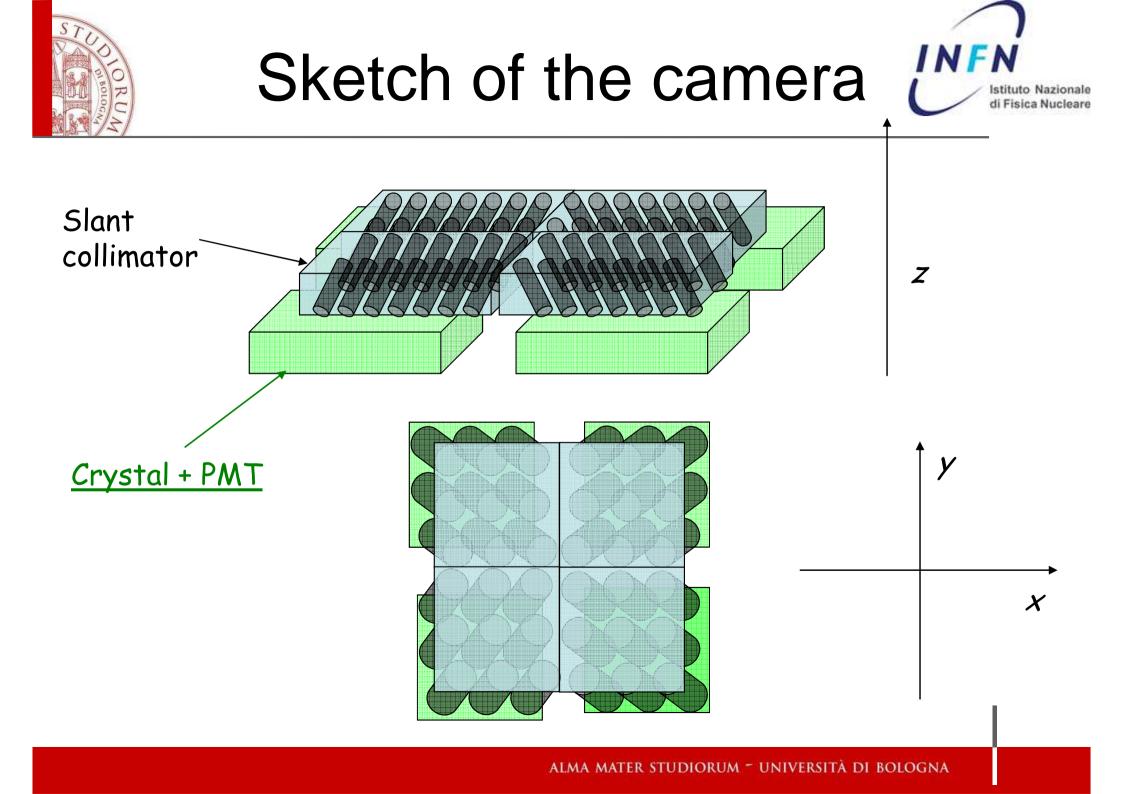


- <u>Aim</u>: to develop a dual compact camera for acquiring ultrasound and scintigraphic images (Rome I and III, Bologna, LNL)
- It will allow to get both morphological and functional information on the same device
- A volumetric image containing the fusion information will be provided to the user

ECORAD



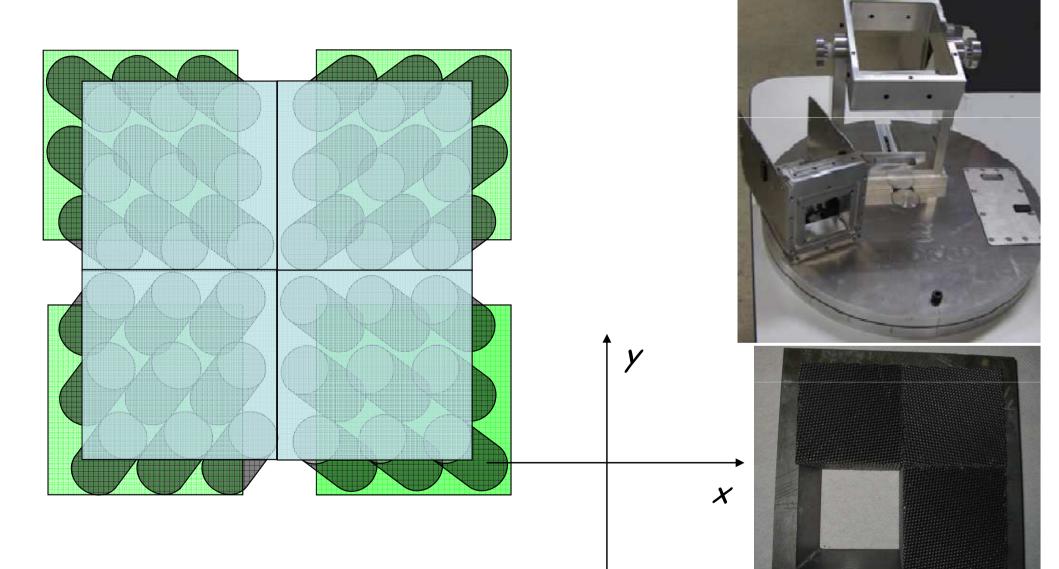






Rotating camera

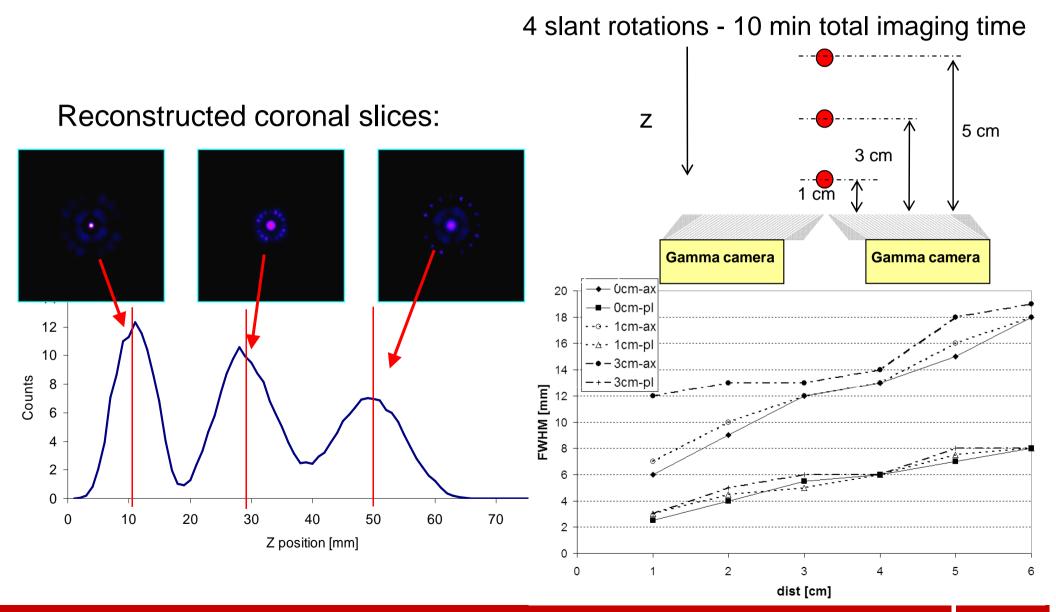


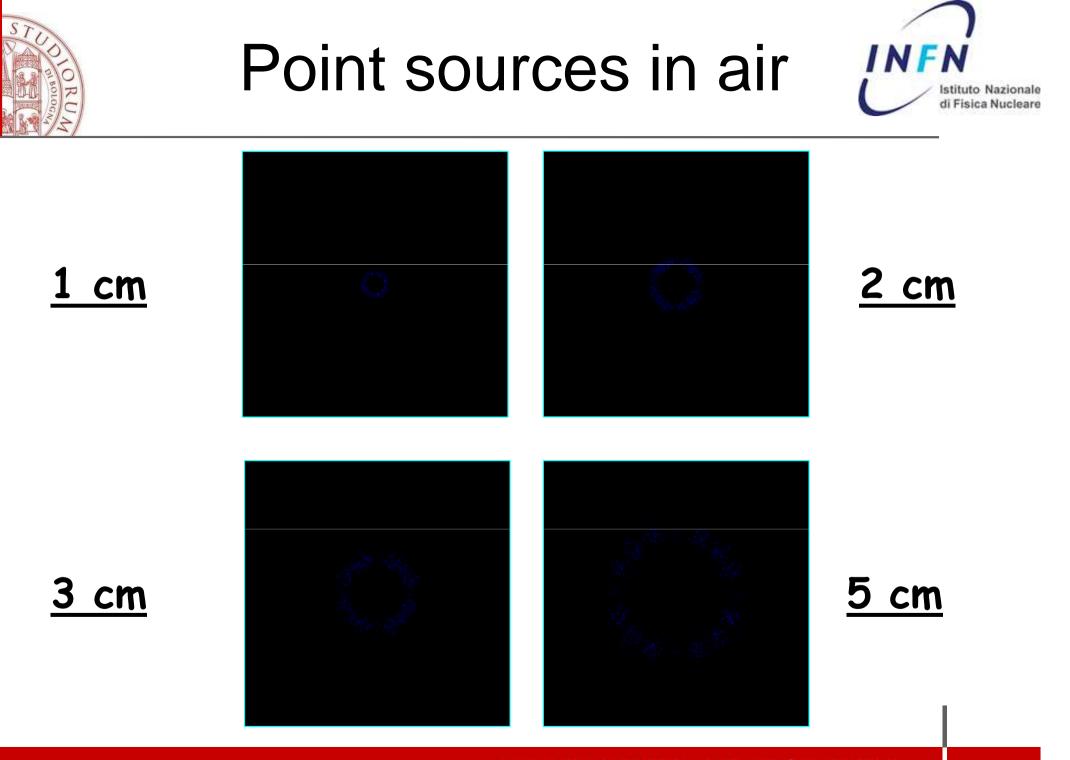




ECORAD









Domande-guida

- Risultati recenti?
- Prospettive future e dove si prevedono gli sviluppi più interessanti?
- Competitori esterni al mondo della ricerca di fisica (industria, altri settori di ricerca...)?
- Cosa potrebbe permettere di migliorare la ricerca? (Formazione, personale e fondi, coordinamento e management,...)



Thank you!



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