B \rightarrow K_sπ⁰(γ) & SVT outer radius: updated study

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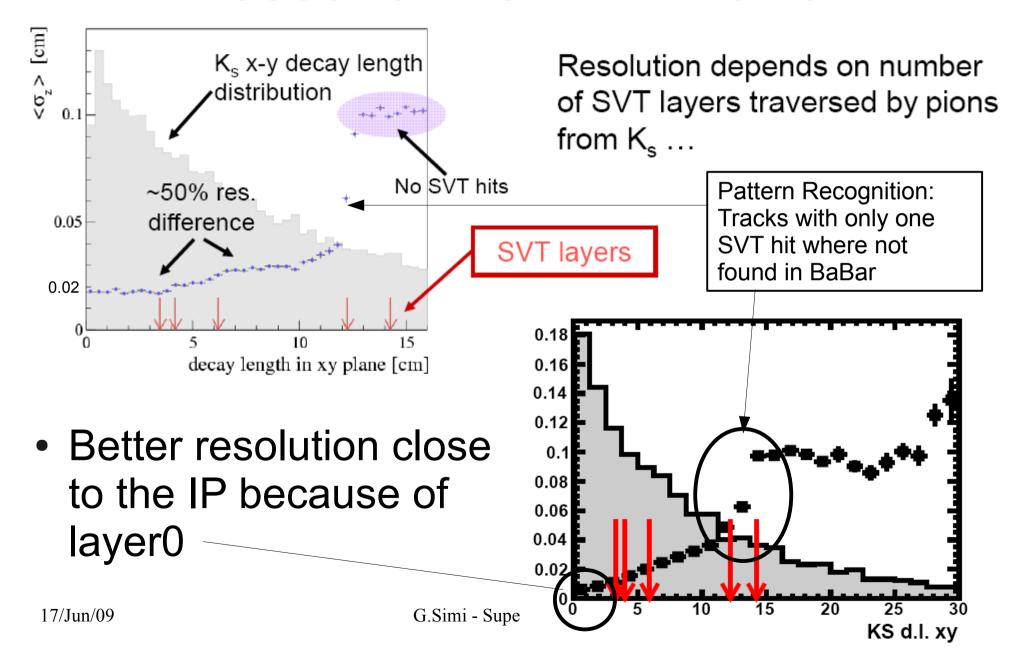




Outline

- New SVT configuration: L0 and acceptance
- Estimate the error on S
 - Δz resolutions for baseline as similar as BaBar but dt resolution is worse
 - Expanded SVT: fraction of usable KS for time dependent study increases

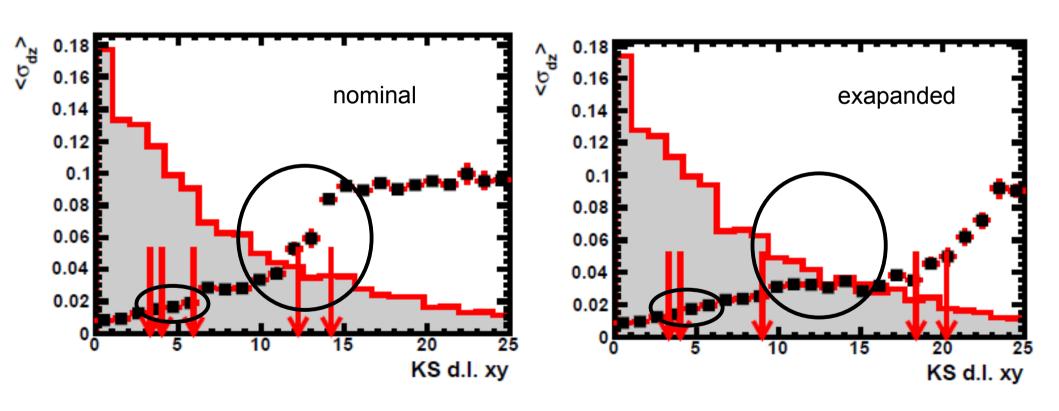
Resoution vs f.t. In BaBar



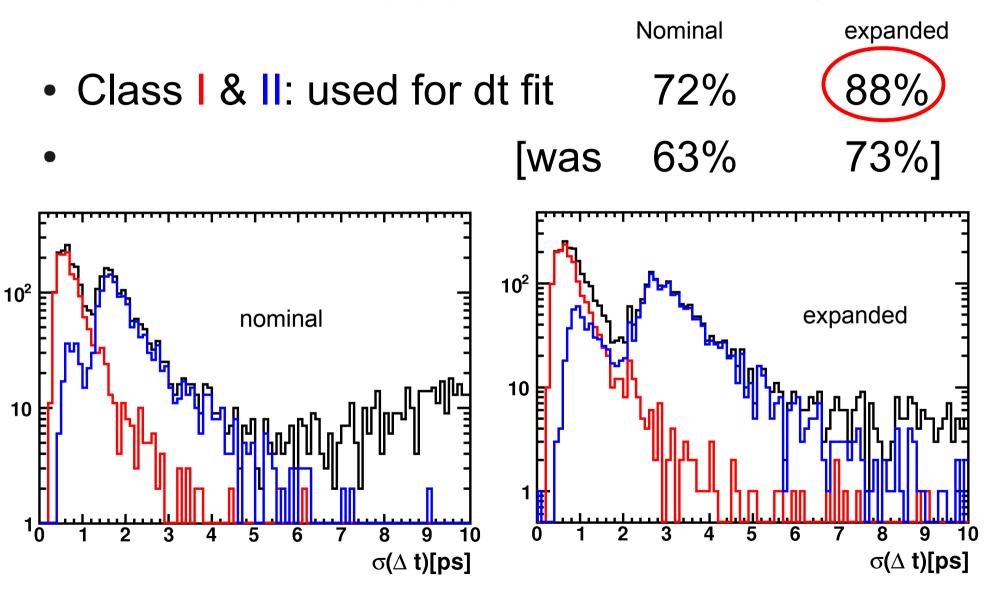
Baseline and expanded configurations

- Baseline SVT configuration as implemented by Nicola
 - L0 is now the hybrid pixel solution
 - Angular coverage increased down to 300mrad
 - Geometric acceptance goes from 89% to 95%
- Expanded configuration: L45 and L3 [N.Neri]
 - Layer 3: 5.9-> 9.4
 - Layer 4: 12.2->20.6
 - Layer 5: 14.2->22.6 (DCH S.T. is at 23.6cm)

Filling the gap between SVT and DCH

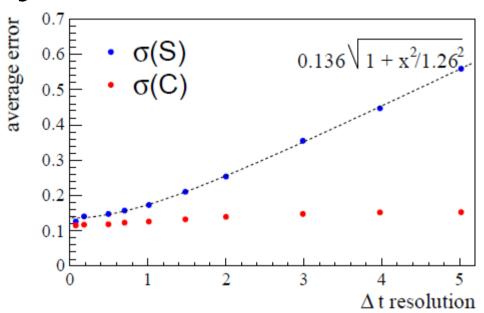


Events used in Δt fit for S



Sensitivity on S,C

• Dependence of S from $\sigma_{\Delta t}$ studied in BAD 904 for perfect tagging

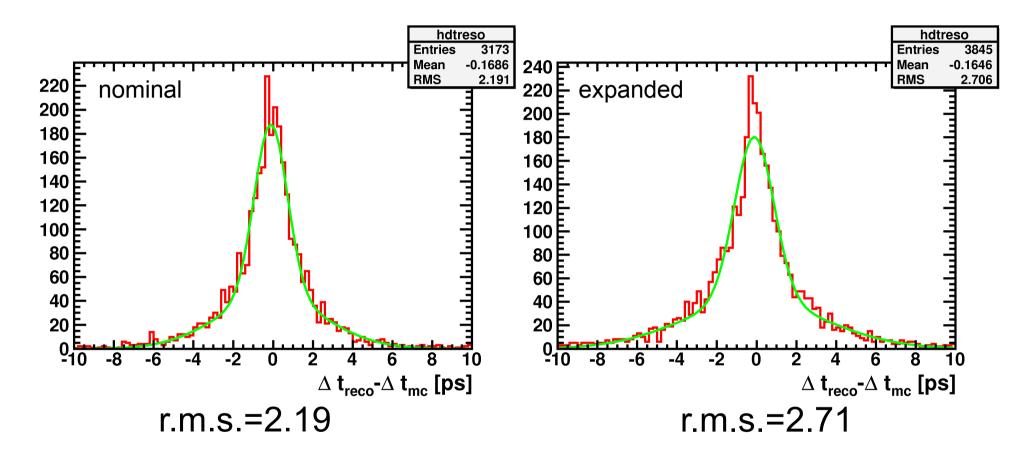


Useful to compare different configurations assuming the dependence

$$-\sigma_{s}^{\sim\sqrt{[(1+\sigma_{\Delta t}^{2}/1.26^{2})/f_{good}]}}$$

$$-\sigma_{\rm C} \sim \sqrt{[1/\text{eff}]}$$

∆t resolution



Babar configuration gives r.m.s.=1.84

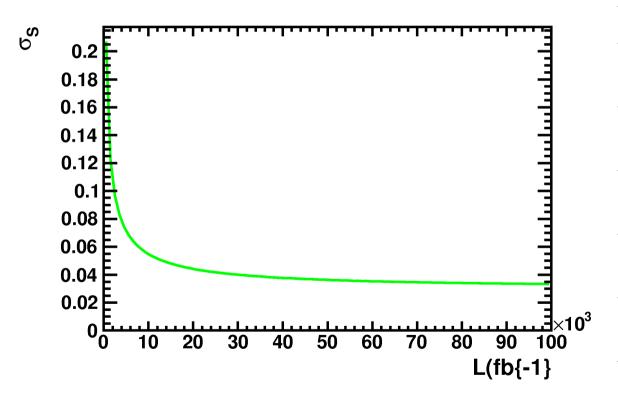
Comparison of Sensitivity on S,C

	rms[ps]	f _{good} [%]	$\sigma_{\rm S}/\sigma_{\rm S}^{\rm nominal}$	$\sigma_{\rm C}/\sigma_{\rm C}^{\rm nominal}$
babar	1.84	69	0.90	0.98
nominal	2.19	72	1	1
expanded	2.71	88	1.07	1.00

- Sensitivity in nominal configuration is comparable to BaBar (10% worse on S)
- Sensitivity in expanded configuration is 10% worse than nominal on S, the same on C

Sensitivity on S for SuperB

 Scale the BaBar result by the luminosity and correct for different resolution, efficiency



	Sys error	
Bflav parameters	0.016	
Bias correction	0.011	
Input PDF params	0.010	
SVT alignment	0.009	
Vertexing method	0.008	

Summary

- Updated study of $K_s\pi^0$ resolutions to baseline SVT configuration, compared to expanded
- Estimated sensitivity on S
- Indication of no gain using expanded SVT

Plans

- Update selection
- Implement ML fit of time dependent CPV
- Add K*γ